

#### Hierarchies

- Definition
  - An ordering of groups in which larger groups encompass sets of smaller groups.
  - Data repository in which cases are related to subcases

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#### Hierarchies in the World

Family histories, ancestries
File/directory systems on computers

Organization charts
Object-oriented software classes

My Documents My Computer ■ Local Disk (C:) Jyang13 on 'Usrserv5\Uvol5\Coit' (H:) 49Desk Fall2006 My Documents øffer public\_html travel UNCC\_xmdv4.12\_imagefinal VarUserStudy UNCC\_xmdv4.12\_imagefinal.zip UNCC\_xmdv.zip mdvtool.zip Mydept on 'Dataserv2\Dvol2\Coit' (J:) ■ 

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Barbara Sample Sam September 2 S Section (T:)

#### Discussion

- What do you want to do with a hierarchy? Assume that you have
  - Family histories, ancestries
  - File/directory systems on computers
  - Organization charts
  - Object-oriented software classes

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#### Discussion

- How will you draw a hierarchy?
- Assume that you have
  - Family histories, ancestries
  - File/directory systems on computers
  - Organization charts
  - Object-oriented software classes

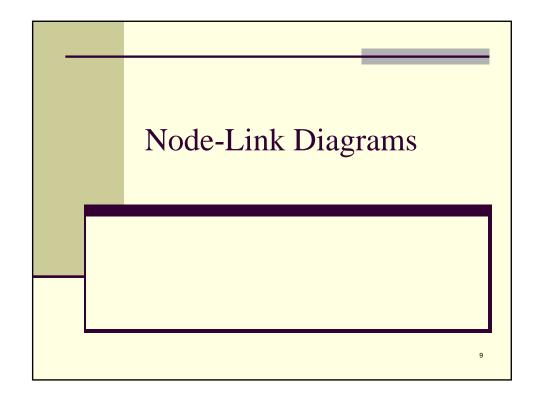
#### Good Hierarchy Visualization

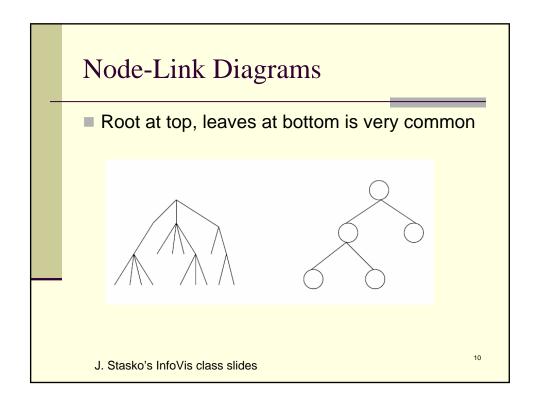
- Allow adequate space within nodes to display information
- Allow users to understand relationship between a node and its context
- Allow to find elements quickly
- Fit into a bounded region
- Much more

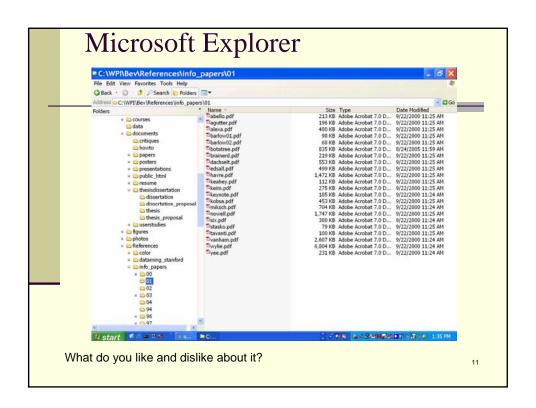
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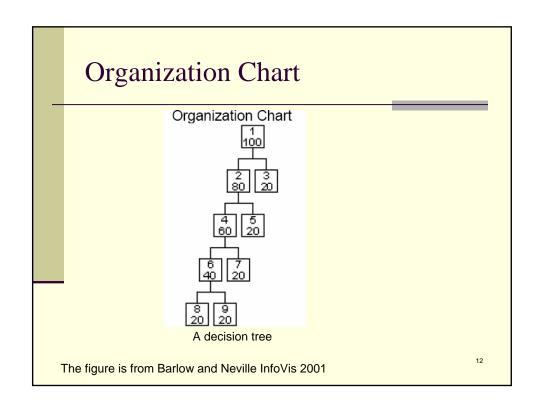
#### Trees

- Hierarchies are often represented as trees
  - Directed, acyclic graph
- Two major categories of tree visualization techniques:
  - Node-link diagram
    - Visible graphical edge from parents to their children
  - Space-filling



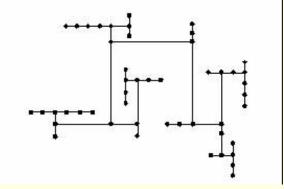






# H-Tree Layout

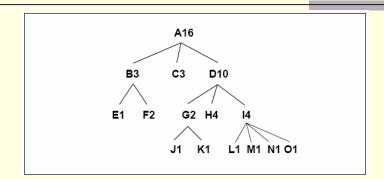
Work well only for binary trees



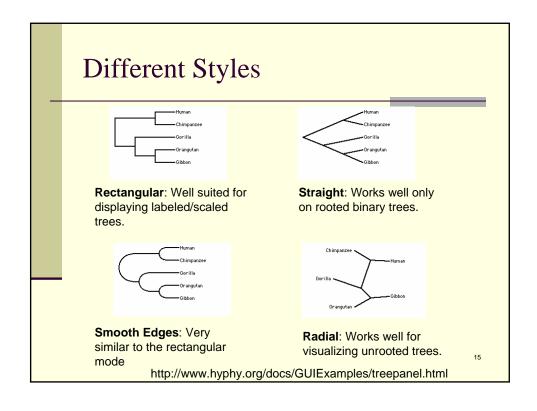
Herman, G. Melançon, M.S. Marshall, "Graph Visualization in Information Visualization: a Survey" In: *IEEE Transactions on Visualization and Computer Graphics*, 2000, pp. 24-44.

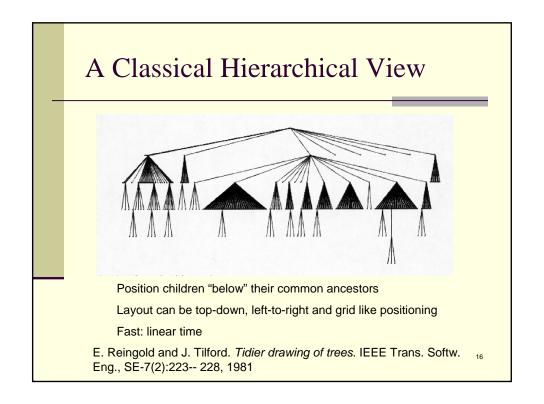
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#### A Common Visualization

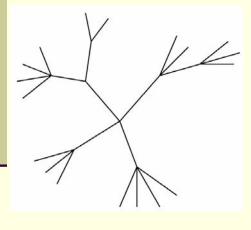


E. Kleiberg et. al. InfoVis 2001





# Why Put Root at Top (Left)



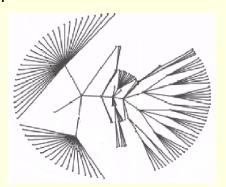
- Root can be at center with levels growing outward too
- Can any node be the root?

J. Stasko's InfoVis class slides

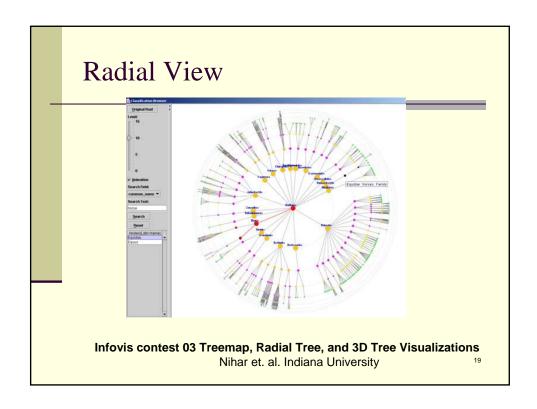
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#### Radial View

- Recursively position children of a subtree into circular wedges
- the central angle of these wedges are proportional to the number of leaves



P. Eades, "Drawing Free Trees", *Bulleting of the Institute fro Combinatorics and its Applications*, 1992, pp. 10-36.



#### **Balloon View**

Siblings of sub-trees are included in circles attached to the father node.

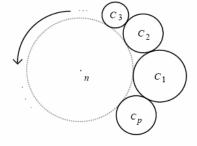
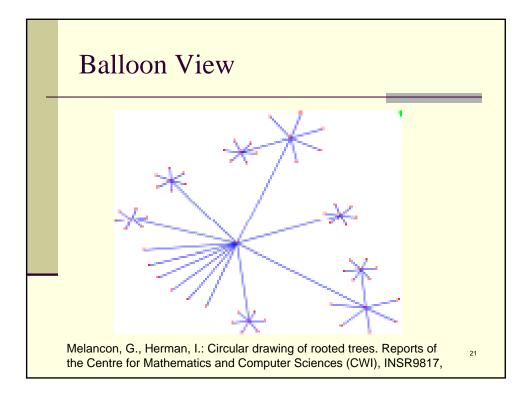


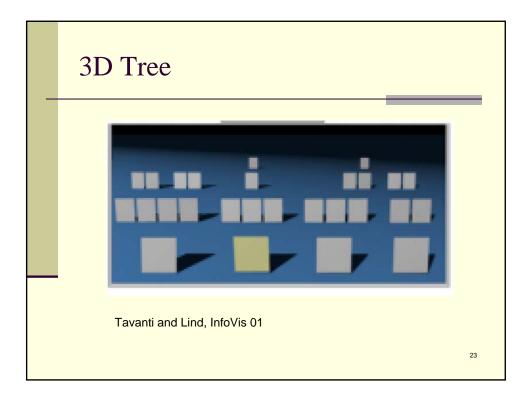
Figure 2: Positioning of children's circles along the circumference

Melancon, G., Herman, I.: Circular drawing of rooted trees. Reports of the Centre for Mathematics and Computer Sciences (CWI), INSR9817,



#### The Challenges

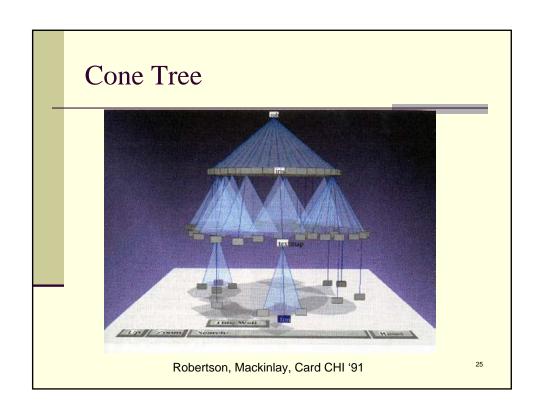
- Scalability
  - # of nodes increases exponentially
  - Available space increases polynomially (circular case)
- Showing more attributes of data cases in hierarchy or focusing on particular applications of trees
- Interactive exploration

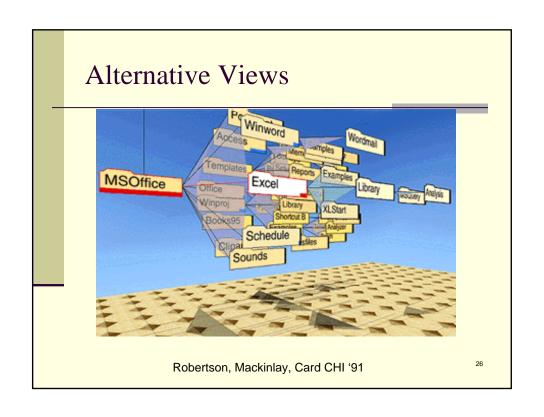


#### Cone Tree

- Key ideas:
  - Add a third dimension into which layout can go
  - Compromise of top-down and centered techniques mentioned earlier
  - Children of a node are laid out in a cylinder "below" the parent
  - Siblings live in one of the 2D planes

Robertson, Mackinlay, Card CHI '91





# Advantages vs. Limitations

- Positive
  - More effective area to lay out tree
  - Use of smooth animation to help person track updates
  - Aesthetically pleasing
- Negative
  - As in all 3D, occlusion obscures some nodes
  - Non-trivial to implement and requires some graphics horsepower

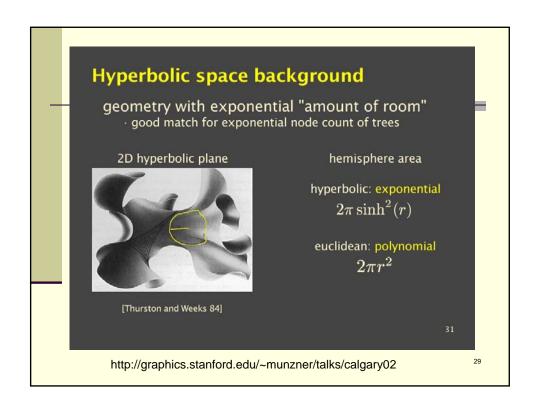
J. Stasko's InfoVis class slides

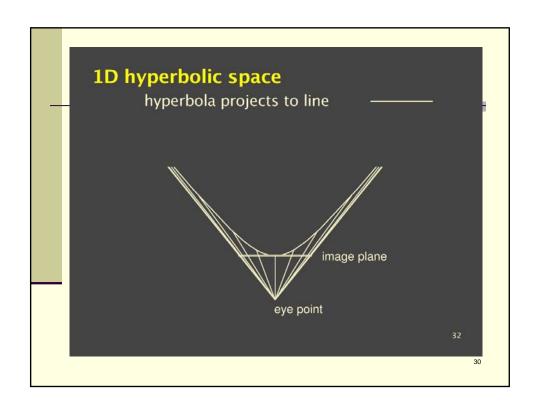
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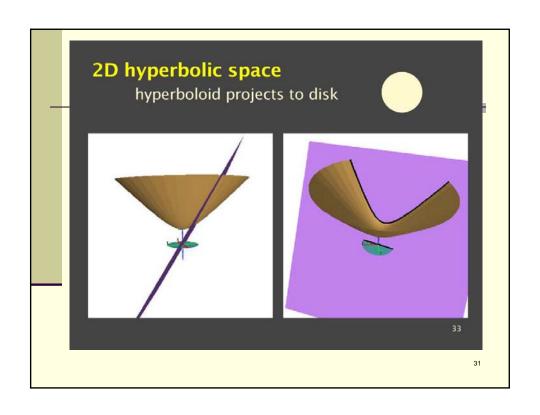
#### Hyperbolic Brower

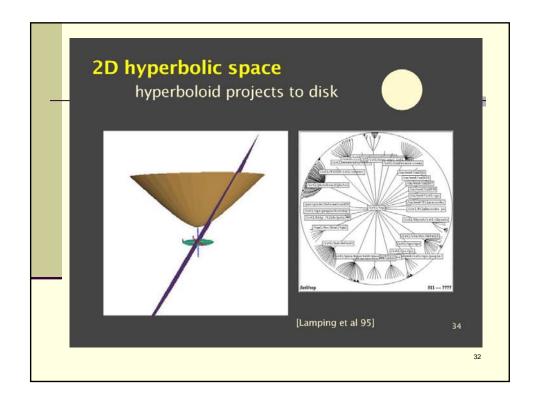
- Key idea:
  - Find a space (hyperbolic space) that increases exponentially, lay out the tree on it
  - Transform from the hyperbolic space to 2D Euclidean space

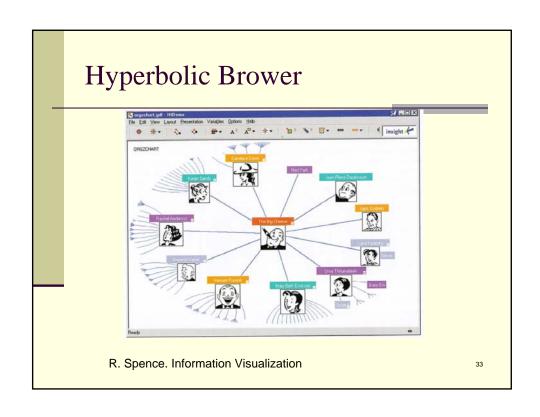
J. Lamping and R. Rao, "The Hyperbolic Browser: A Focus + Context Technique for Visualizing Large Hierarchies", *Journal of Visual Languages and Computing*, vol. 7, no. 1, 1995, pp. 33-55.

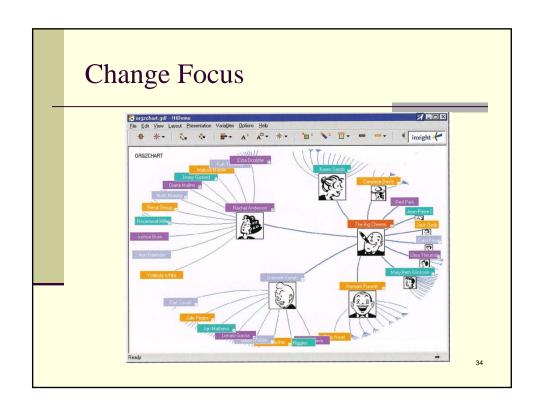








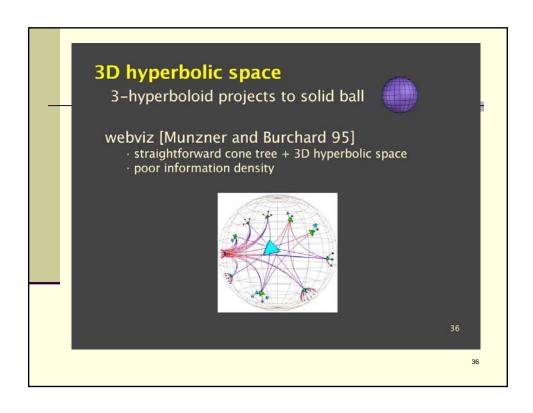


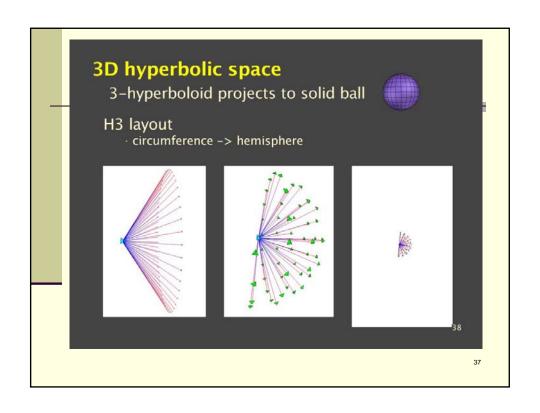


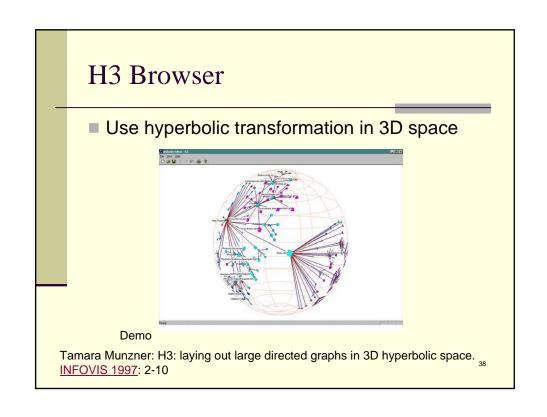
#### Key Attributes

- Natural magnification (fisheye) in center
- Layout depends only on 2-3 generations from current node
- Smooth animation for change in focus
- Don't draw objects when far enough from root (simplify rendering)

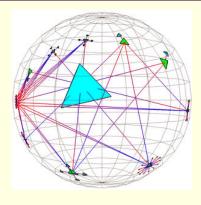
J. Stasko's InfoVis class slides

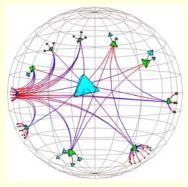












Projective model: keeps lines straight but distorts angles.

Conformal model: preserves angles but maps straight lines to circular arcs.

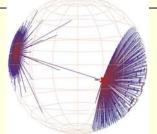
From Tamara Munzner's Ph.D. dissertation

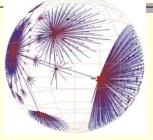
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# Projective vs. Conformal Model

- Projective model
  - Less aesthetically pleasing ⊗
  - Transformation: 4X4 matrices ©
  - Straight lines ☺
- Conformal model
  - More aesthetically pleasing ☺
  - Transformation: 2X2 complex matrices ⊗
  - Curves ⊗

# Scalability - Adaptive Drawing



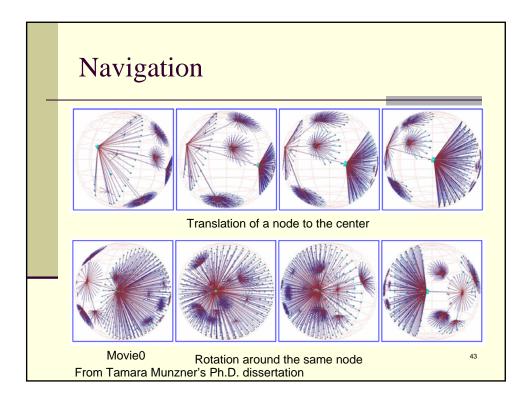


- Maintain a target frame rate
  - Draw only as much of the neighborhood around a center point as is possible in the allotted time
  - Fill in scene fringe using several bounded idle frames when the user is idle
- Question: Why use several idle frames?

Movie 3

#### Scalability - Other Tricks

- Only draw a local neighborhood of nodes
  - Nodes sufficiently far from the center will project to less than a single pixel – terminate drawing when features project to subpixel areas
- Use front buffer for highlighting



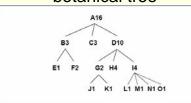
#### **Problems**

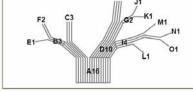
- Orientation
  - Watching the view can be disorienting
    - When a node is moved, its children don't keep their relative orientation to it as in Euclidean plane, they rotate
- Not as symmetric and regular as Euclidean techniques, two important attributes in aesthetics

J. Stasko's InfoVis class slides

# Botanical Tree [E. Kleiberg et. al. InfoVis 2001]

- Basic idea: we can easily see the branches, leaves, and their arrangement in a botanical tree
- Inspiration: Strand model of Holton
  - Strands: internal vascular structure of a botanical tree





Node and link diagram

Corresponding strand Model

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#### Botanical Tree [E. Kleiberg et. al. InfoVis 2001]

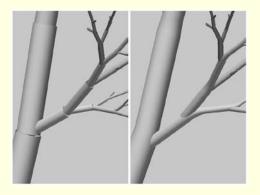
■ Use strand model to create a 3-d directory tree:



Unsatisfied features: 1. Branching points 2. long and thin branches 3. cluttered leaves

# Botanical Tree [E. Kleiberg et. al. InfoVis 2001]

■ Improve the first tree:

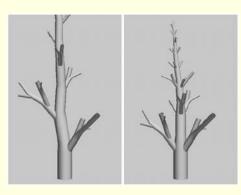


Adding smooth transition between two cylinders

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# Botanical Tree [E. Kleiberg et. al. InfoVis 2001]

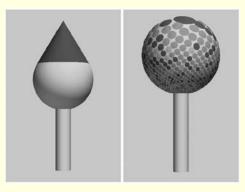
■ Improve the first tree:



Use a general tree rather than a binary tree

# Botanical Tree [E. Kleiberg et. al. InfoVis 2001]

■ Improve the first tree:

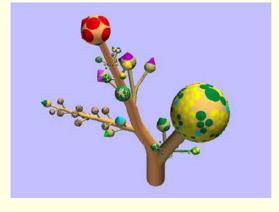


Phi-ball with one (left) and many (right) files

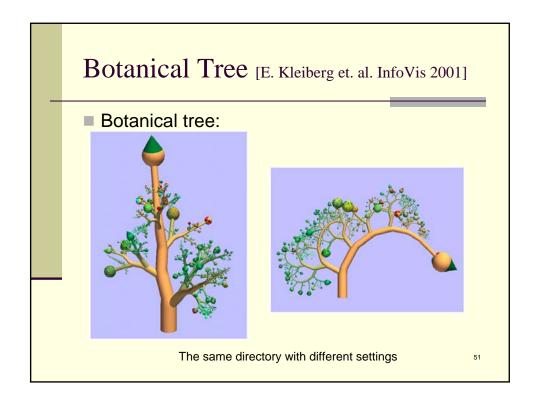
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# Botanical Tree [E. Kleiberg et. al. InfoVis 2001]

■ Botanical tree:



Final model with the improvements



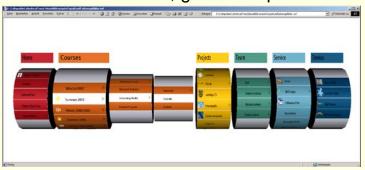
# Dynamic Visualization of Graphs with Extended Labels [wong:infovis2006]

- Labeling issue in the node-link diagram
- Video

# Collapsible Cylindrical Tree [Dachselt

& Ebert Infovis 01]

- Basic idea: use a set of nested cylinders according to the telescope metaphor
- Limitation: one path is visible in once
- Interactions: rotation, go down/up

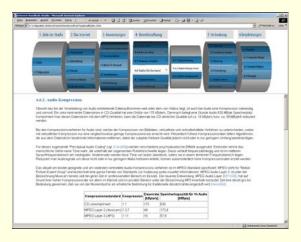


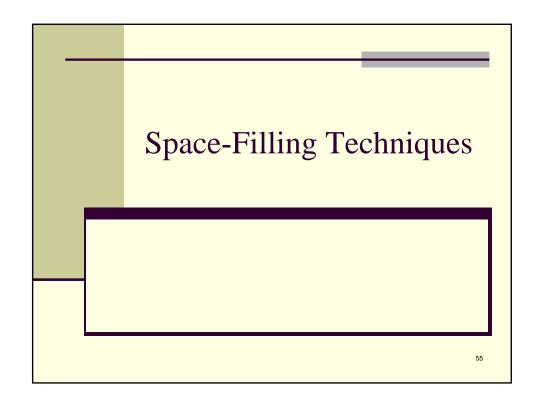
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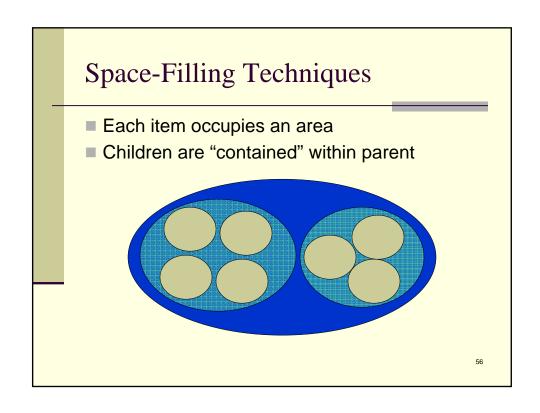
# Collapsible Cylindrical Tree [R.

Dachselt, J. Ebert Infovis 01]

Example application: web document browsing



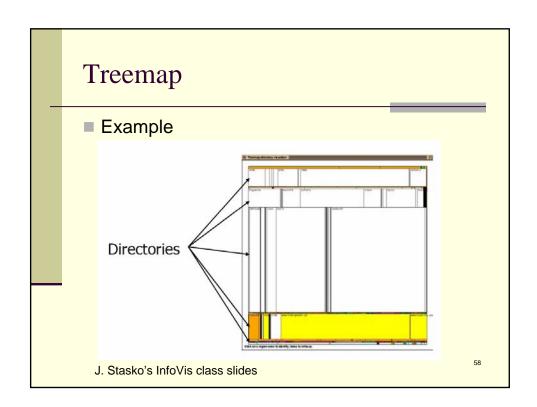


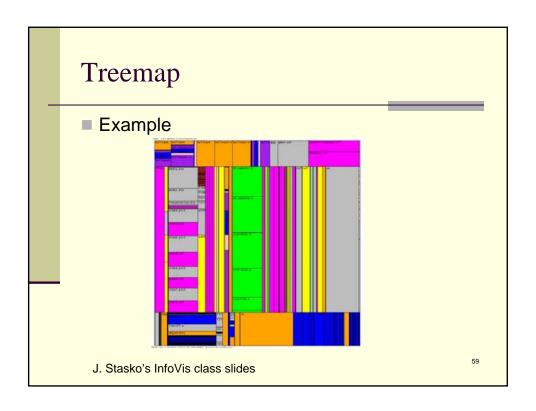


# Treemap

- Children are drawn inside their parents
- Alternative horizontal and vertical slicing at each successive level
- Use area to encode other variables of data items

<u>B. Johnson</u>, Ben Shneiderman: Tree maps: A Space-Filling Approach to the Visualization of Hierarchical Information Structures. <u>IEEE Visualization 1991</u>: 284-291



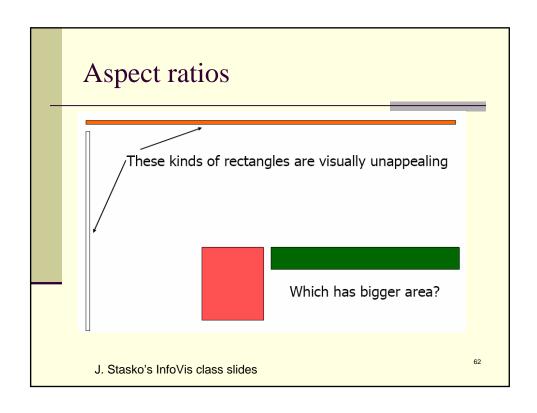


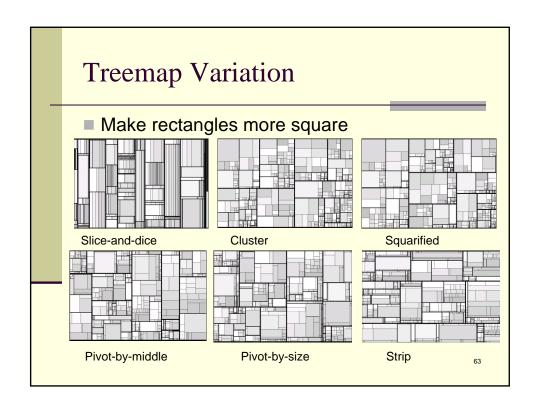
# Treemap Algorithm

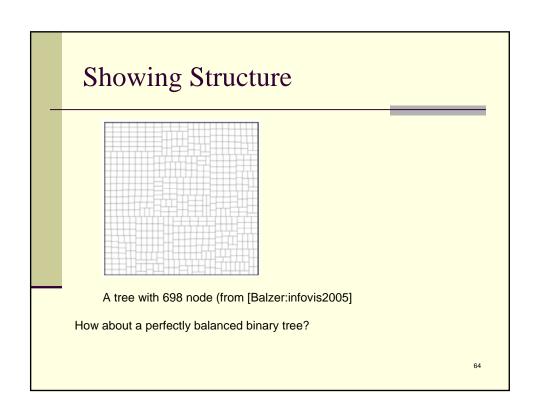
```
Draw()
   Change orientation from parent (horiz/vert)
   Read all files and directories at this level
   Make rectangle for each, scaled to size
   Draw rectangles using appropriate size and color
   For each directory
       Make recursive call using its rectangle as focus
}
J. Stasko's InfoVis class slides
```

# Treemap Affordances

- It is rectangular!
- Good representation of two attributes beyond node-link: color and area
- Not as good at representing structure
  - Can get long-thin aspect ratios
  - What happens if it's a perfectly balanced tree of items all the same size?

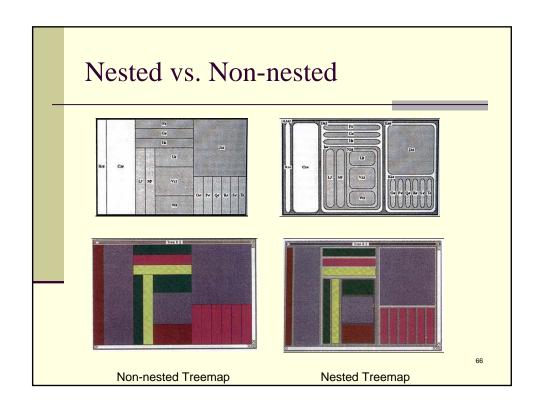


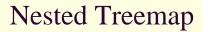




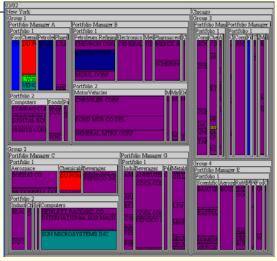
# **Showing Structure**

- Borderless treemap: hard to discern structure of hierarchy
  - What happens if it's a perfectly balanced tree of items all the same size?
- Variations:
  - Use border
  - Change rectangles to other forms





Borders help on smaller trees, but take up too much area on large, deep ones

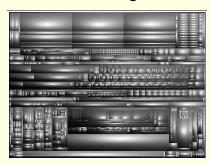


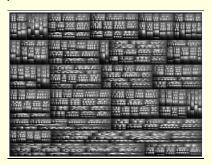
http://www.cs.umd.edu/hcil/treemap-history/treemap97.shtml

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# **Cushion Treemap**

 Add shading and texture (Van Wijk and Van de Wetering InfoVis'99)

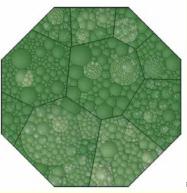




#### Voronoi Treemaps [balzer:infovis05]

- Enable subdivisions of and in polygons
- Fit into areas of arbitrary shape

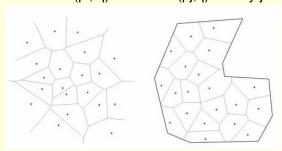




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#### Basic Voronoi Tessellations

- Enable partitioning of m-dimensional space without holes or overlappings
- Planar VT in 2D:
  - P: = {p1, ..pn} a set of n distinct points –generators
  - Divide 2D space into n Voronoi regions V(Pi):
    - Any point q lies in the region V(Pi) if and only if
    - distance(pi, q) < distance(pj,q) for any j != i</p>



#### Weighted Voronoi Tessellations

- Basic VT:  $distance_{\varepsilon}(p_i, q) := ||p_i q|| = \sqrt{(x_i x)^2 + (y_i y)^2}$
- Additively weighted Voronoi (AW VT:

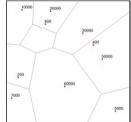
$$distance_{aw}(p_i, w_i, q) := ||p_i - q|| - w_i$$

Additively weighted power voronoi (PW VT):

$$distance_{pw}(p_i, w_i, q) := \|p_i - q\|^2 - w_i$$

Left: AW VT Right: PW VT





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#### Centroidal Voronoi Tessellations (CVT)

 Property of CVT: Each generator is itself center of mass(centroid) of corresponding voronoi region

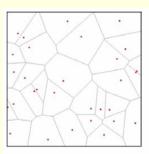




Figure 6: Voronoi tessellation of 20 random points and an associated CVT—traces illustrate the movements of the points during the computation of the CVT

#### Centroidal Voronoi Tessellations (CVT)

CVT minimize the energe function:

$$\mathcal{K}(P, \mathcal{V}(P)) = \sum_{i} \int_{V(p_i)} ||x - p_i||^2 dx$$

The energy of the CVT is equivalent to the overall aspect ratio of the subareas of the treemap layout

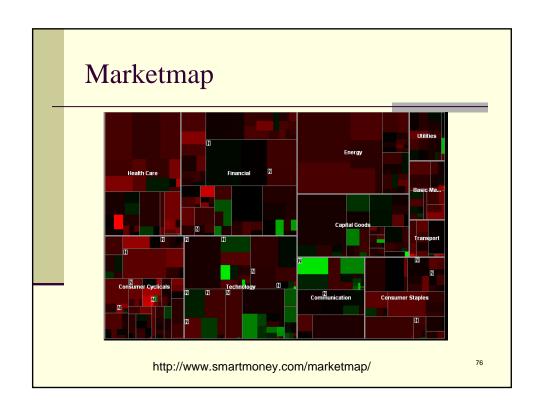
73

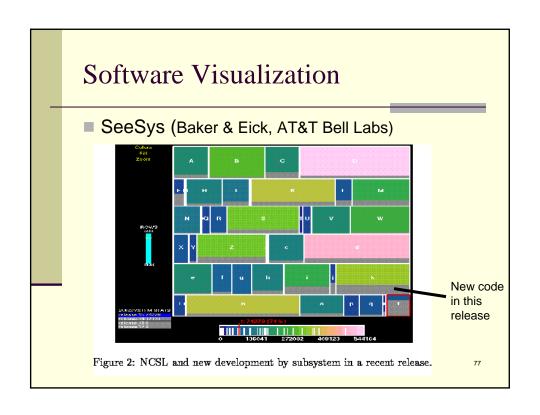
#### Voronoi Treemap Algorithm

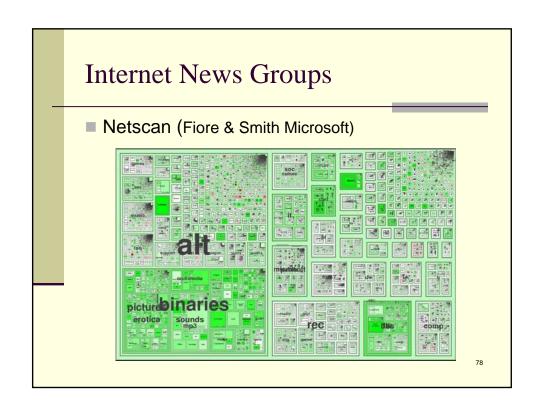
- Size of each Voronoi region should reflect size of the tree node
- Area size is not observed in CVT computation
- Extension:
  - Use iteration
  - In each iteration, adjust the area of regions by their weights
  - Weights are adjusted according to the size of the node
  - Iterate until the relative size error is under a threshold
- Video

# **Treemap Applications**

- Software visualization
- Multimedia visualization
- Tennis matches
- File/directory structures
- Basketball statistics
- Stocks and portfolios

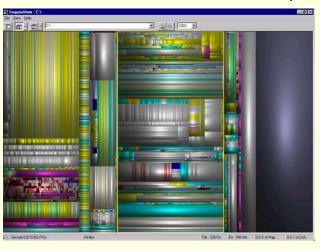






# SequoiaView

■ File visualizater www.win.tue.nl/sequoiaview/



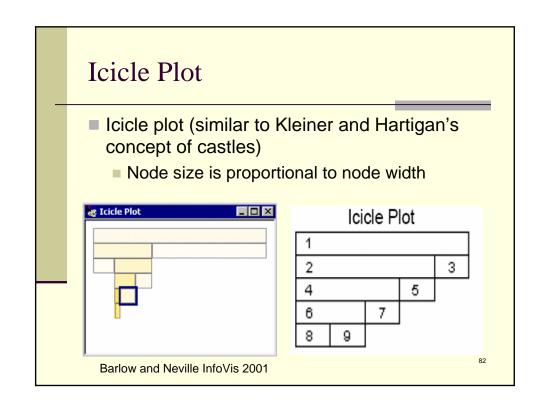
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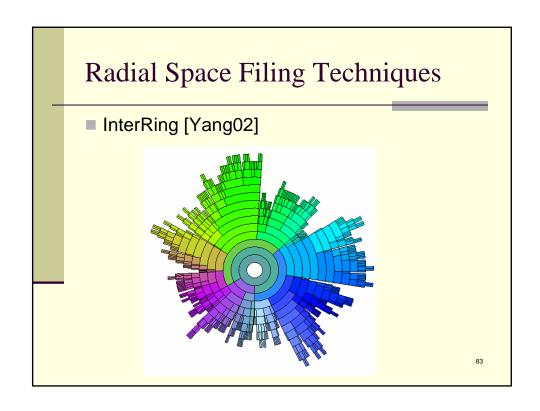
#### Photemesa

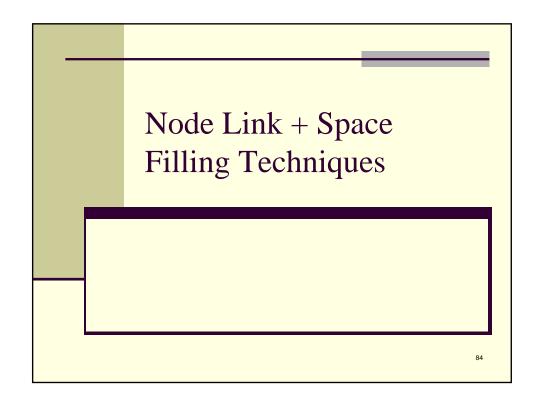
Image browser (quantum and bubble treemap) http://www.cs.umd.edu/hcil/photomesa/



# Space-Filling Techniques - Each item occupies an area - Children are "contained" within (under) parent One Example

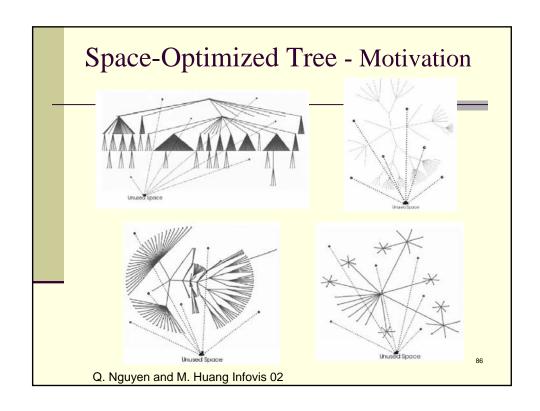






# Elastic Hierarchies: Combining Treemaps and Node-Link Diagrams [zhao:infovis 05]

- A hybrid approach
- Dynamic
- Video

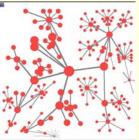


# Space-Optimized Tree [Q. Nguyen and M.

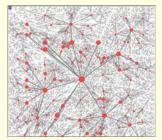
Huang Infovis 02]

#### Key idea:

- Partition display space into a collection of geometrical areas for all nodes
- Use node-link diagrams to show relational structure



Example: Tree with 150 nodes



Example: Tree with approximately 55000 nodes

# Space-Optimized Tree [Q. Nguyen and M.

Huang Infovis 02]

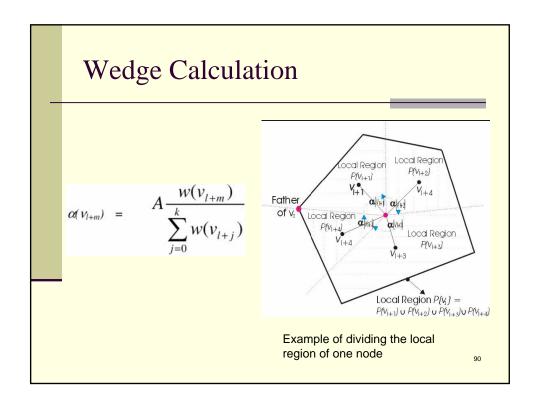
#### Algorithm for dividing a region:

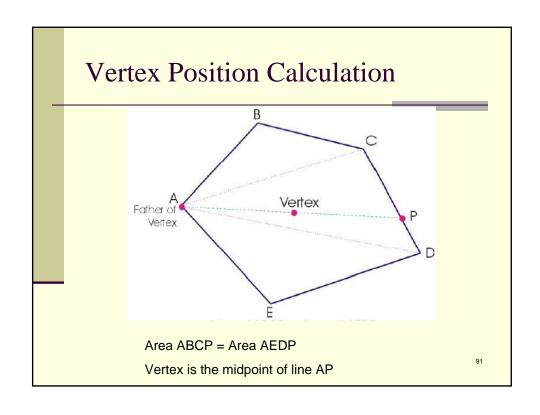
- 1. weight calculation for each direct child
- 2. wedge calculation for each direct child
- 3. vertex position calculation for each direct child

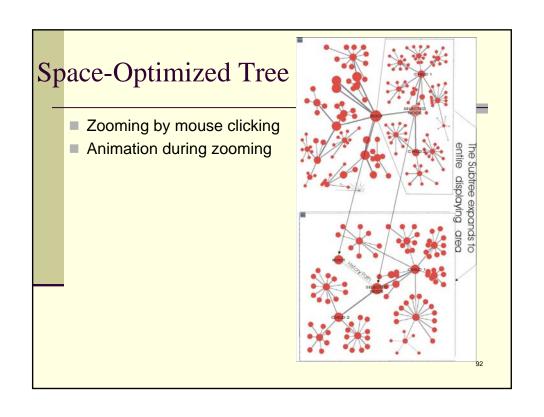
# Weight Calculation

$$w(v_i) = 1 + C \sum_{j=0}^{k-1} w(v_{l+j})$$

- V<sub>i</sub>: the direct child
- V<sub>I</sub> V<sub>I+k</sub>: Direct children of V<sub>i</sub>
- Constant C: decide difference between vertexes with more descendants and vertexes with fewer descendants.







# Reading Assignment

■ Chapter 2 of the Spence book