

IoTMonitor: A Hidden Markov Model-based Security System to Identify Crucial Attack Nodes in Trigger-action IoT Platforms

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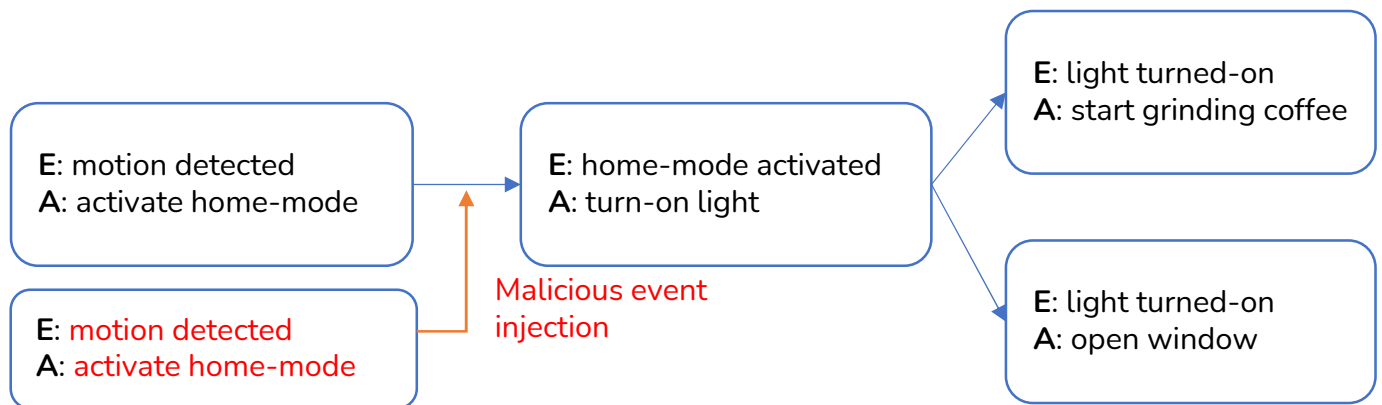


Motivation

- Trigger-action IoT platforms (e.g., IFTTT) are getting popular
- Chain of **interactions** creates security vulnerabilities
- Attackers inject malicious events remotely



Problem Statement



- How can we determine the optimal attack path an attacker may adopt to implement a trigger-action based attack?

Existing Approaches

Approach-1:

- Performing static analysis on application source code
- Instrumenting customized codes
- Generating system models at runtime
- Identifying and blocking unsafe and insecure state transitions

Example: IoTGuard [1]

[1] Z. B. Celik, G. Tan, and P. Mcdaniel, "IOTGUARD : Dynamic Enforcement of Security and Safety Policy in Commodity IoT," no. February, 2019.

Existing Approaches (Contd.)

Approach-2:

- Analyzing network traffics to extract wireless fingerprints
- Using supervised learning methods to identify malicious activities

Example: HoMonit [1]

1] W. Zhang, "HoMonit : Monitoring Smart Home Apps from Encrypted Traffic," *Comput. Commun. Secur.*, pp. 1074–1088, 2018.

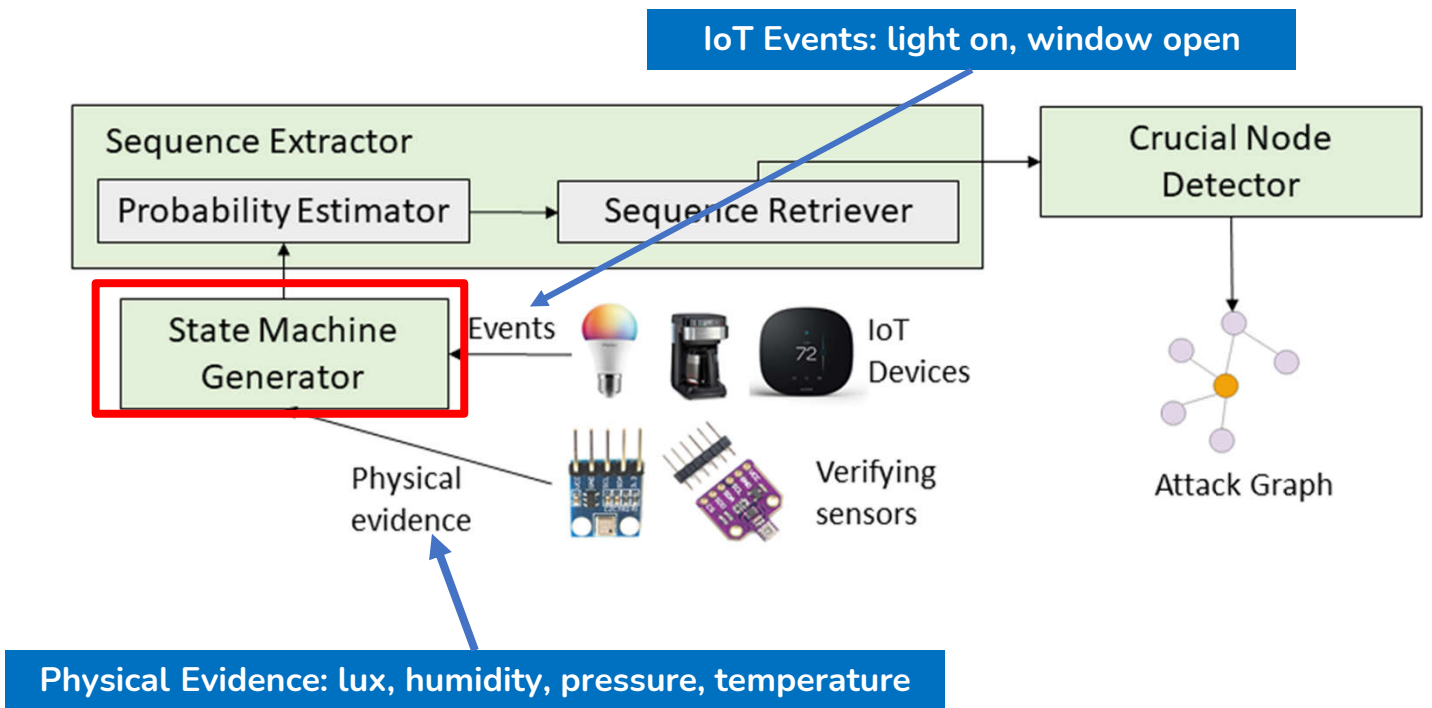
IoTMonitor at a Glance

- A **Hidden Markov Model** based security system
- Discovers probabilistic relationships between IoT event occurrences and physical evidence

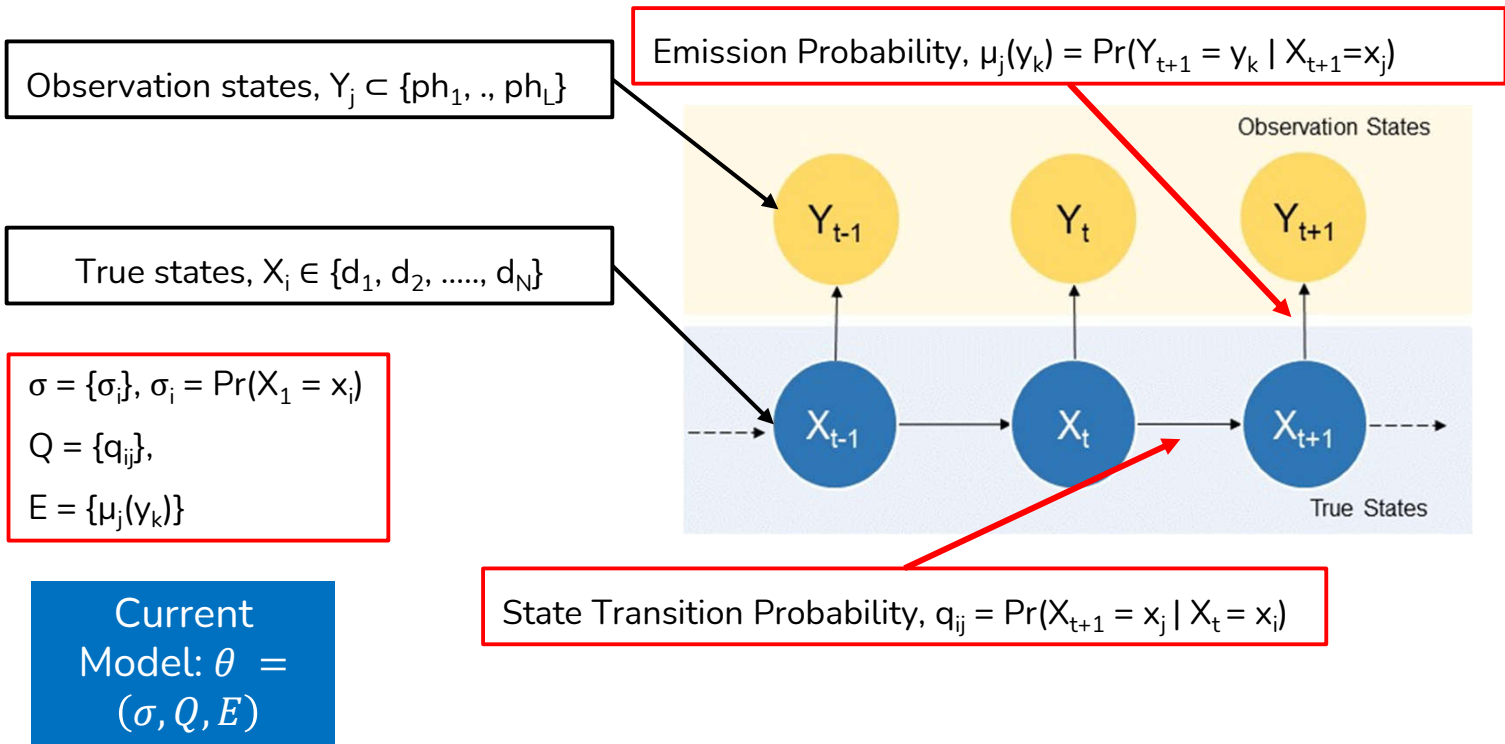
Goals:

- Determining optimal attack sequence from a set of physical evidence
- Identifying the most frequently triggered IoT events

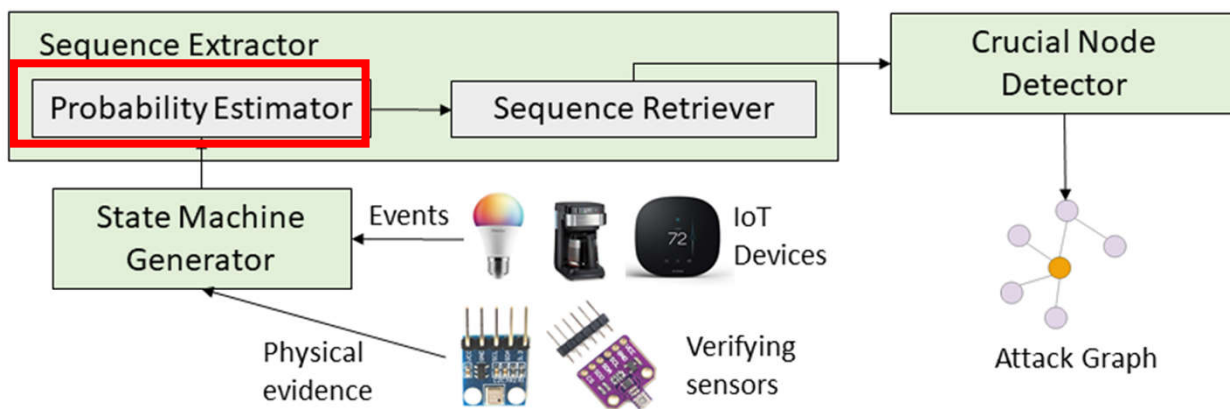
System Architecture



State Machine Generator



Probability Estimator



Goal: Given the observation sequence $Y = \{Y_1, Y_2, \dots, Y_T\}$, determine

$$\theta^* = \underset{\theta}{\operatorname{argmax}} \operatorname{Pr}(Y_1, Y_2, \dots, Y_T | \theta)$$

Probability Estimator (Contd.)

- IoTMonitor uses **forward-backward procedure** to calculate θ^* .

the probability of being in the state x_i at time t given a history of observations $\langle Y_1, Y_2, \dots, Y_t \rangle$

$$\alpha_t(i) = Pr(Y_1, Y_2, \dots, Y_t, X_t = x_i | \theta)$$

$$\beta_t(i) = Pr(Y_{t+1}, Y_{t+2}, \dots, Y_T | X_t = x_i, \theta)$$

the probability of being in the state x_i at time t given a set of observations $\langle Y_{t+1}, Y_{t+2}, \dots, Y_T \rangle$

Initialization

$$\alpha_1(i) = \sigma_i \mu_i(Y_1), \quad 1 \leq i \leq N$$

$$\beta_T(i) = 1, \quad 1 \leq i \leq N$$

Induction

$$\alpha_{t+1}(j) = \mu_j(Y_{t+1}) \sum_{i=1}^N \alpha_t(i) q_{ij}, \quad 1 \leq t \leq T-1, \quad 1 \leq j \leq N$$

$$\beta_t(i) = \sum_{j=1}^N q_{ij} \mu_j(Y_{t+1}) \beta_{t+1}(j), \quad t = T-1, \dots, 2, 1, \quad 1 \leq i \leq N$$

Probability Estimator (Contd.)

$$\begin{aligned} \delta_t(i) &= Pr(X_t = x_i | Y_1, Y_2, \dots, Y_T, \theta) \\ &= \frac{Pr(X_t = x_i, Y_1, Y_2, \dots, Y_T | \theta)}{Pr(Y_1, Y_2, \dots, Y_T | \theta)} \\ &= \frac{\alpha_t(i)\beta_t(i)}{\sum_{j=1}^N \alpha_t(j)\beta_t(j)} \end{aligned}$$

$$\begin{aligned} \xi_t(i, j) &= Pr(X_t = x_i, X_{t+1} = x_j | Y_1, Y_2, \dots, Y_T, \theta) \\ &= \frac{Pr(X_t = x_i, X_{t+1} = x_j, Y_1, Y_2, \dots, Y_T | \theta)}{Pr(Y_1, Y_2, \dots, Y_T | \theta)} \\ &= \frac{\alpha_t(i)q_{ij}\beta_{t+1}(j)\mu_j(Y_{t+1})}{\sum_{i=1}^N \sum_{j=1}^N \alpha_t(i)q_{ij}\beta_{t+1}(j)\mu_j(Y_{t+1})} \end{aligned}$$

$\delta_t(i)$ = the probability of the system being in the true state x_i at time instance t

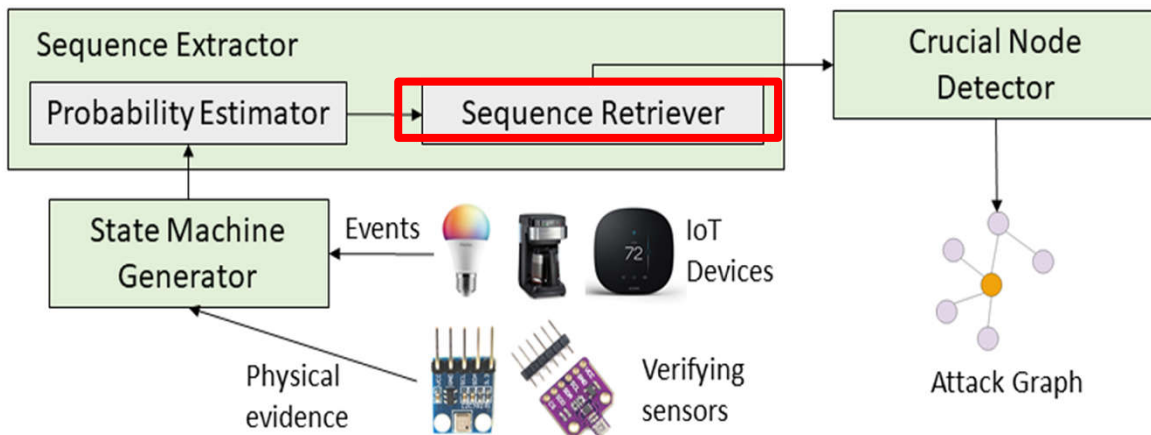
$\xi_t(i, j)$ = the probability of the system being in the true states x_i and x_j at time instances t and $t+1$

$$\bar{\sigma}_i = \delta_1(i)$$

$$\bar{q}_{ij} = \frac{\sum_{t=1}^{T-1} \xi_t(i, j)}{\sum_{t=1}^{T-1} \delta_t(i)}$$

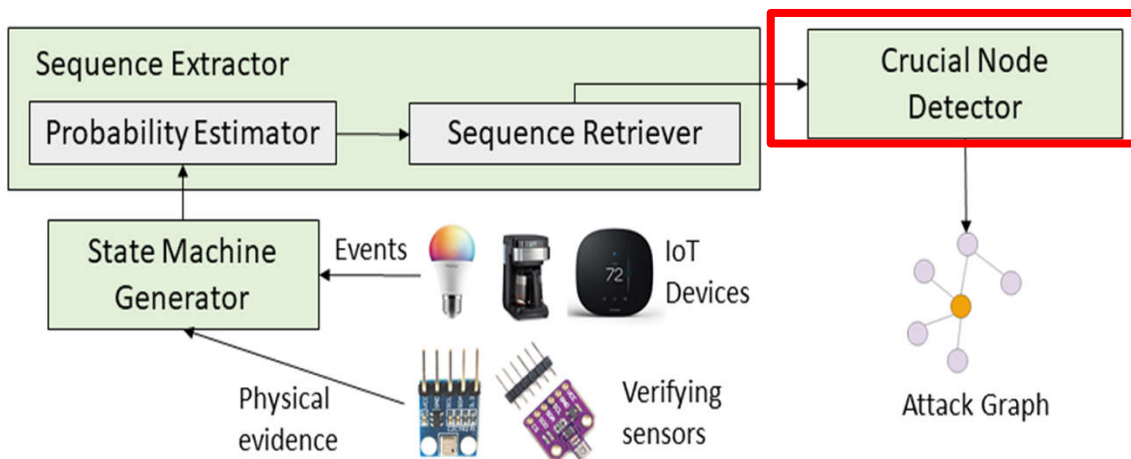
$$\bar{\mu}_j(y_k) = \frac{\sum_{t=1}^T 1_{(Y_{t+1}=y_k)} \delta_t(j)}{\sum_{t=1}^T \delta_t(j)}$$

Sequence Retriever



Goal: $\omega_t(i) = \max_{x_1, \dots, x_{i-1}} \left\{ \Pr(X_1 = x_1, \dots, X_t = x_i, Y_1, \dots, Y_t = y_k | \theta) \right\}$

Crucial Node Detector



Goal: To identify the most frequently triggered events

Crucial Node Detector (Contd.)

Algorithm 1 Crucial node detection algorithm

Input: $X, \Upsilon_1, \Upsilon_2, \dots, \Upsilon_p$

Output: Pairs of true states responding to the most frequently triggered events

```

1:  $i \leftarrow 1$ 
2: while  $i \leq p$  do
3:    $S_i \leftarrow$  Longest Common Subsequence between  $X$  and  $\Upsilon_i$ 
4:   for  $j \leftarrow 1$  to  $(|S_i| - 1)$  do
5:      $E[i, j] \leftarrow \{S_i[j], S_i[j + 1]\}$ 
6:     if  $E[i, j]$  not in  $SCORE.Keys()$  then
7:        $SCORE[E[i, j]] \leftarrow 1$ 
8:     else
9:        $SCORE[E[i, j]] \leftarrow SCORE[E[i, j]] + 1$ 
10:    end if
11:  end for
12: end while
13: return  $\underset{E[i, j]}{argmax} (SCORE[E[i, j]])$ 

```

Number of times a particular pair is present in the sequence

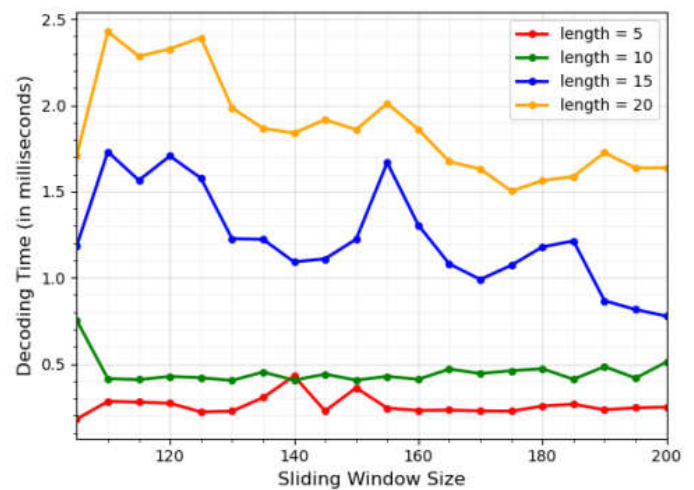
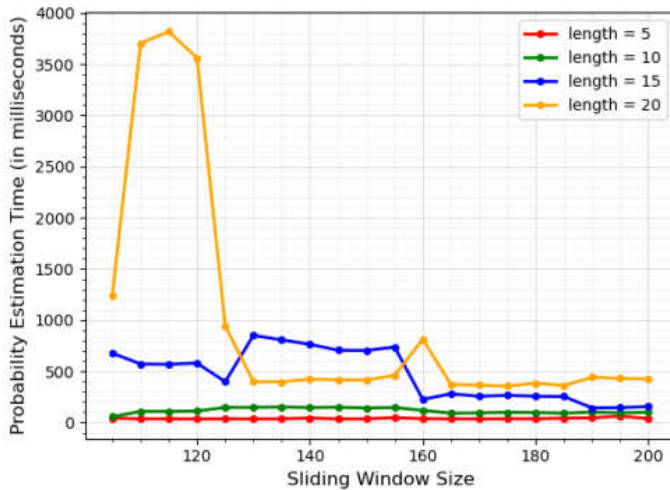
Experimental Settings

- Utilized the PEEVES [1] dataset
- Data collected from 12 distinct IoT devices and 48 sensors
- Conceptualized a sliding window w_i
- When an event is occurred at time t_i , we consider all sensor measurements collected within the time period (t_i+w_i) for the purpose of event verification

[1] S. Birnbach, S. Eberz, and I. Martinovic, "Peeves: Physical Event Verification in Smart Homes," *Proc. ACM Conf. Comput. Commun. Secur.*, pp. 1455–1467, 2019.

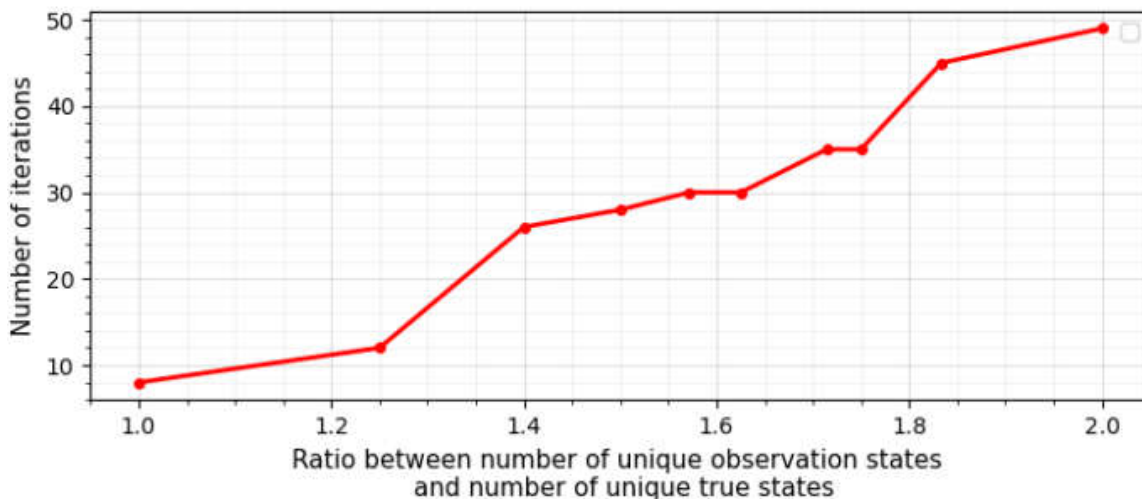
Probability Estimation Time vs Decoding Time

- **Estimation time:** the time required to estimate the converged θ^*
- **Decoding time:** the time required to extract the hidden sequence



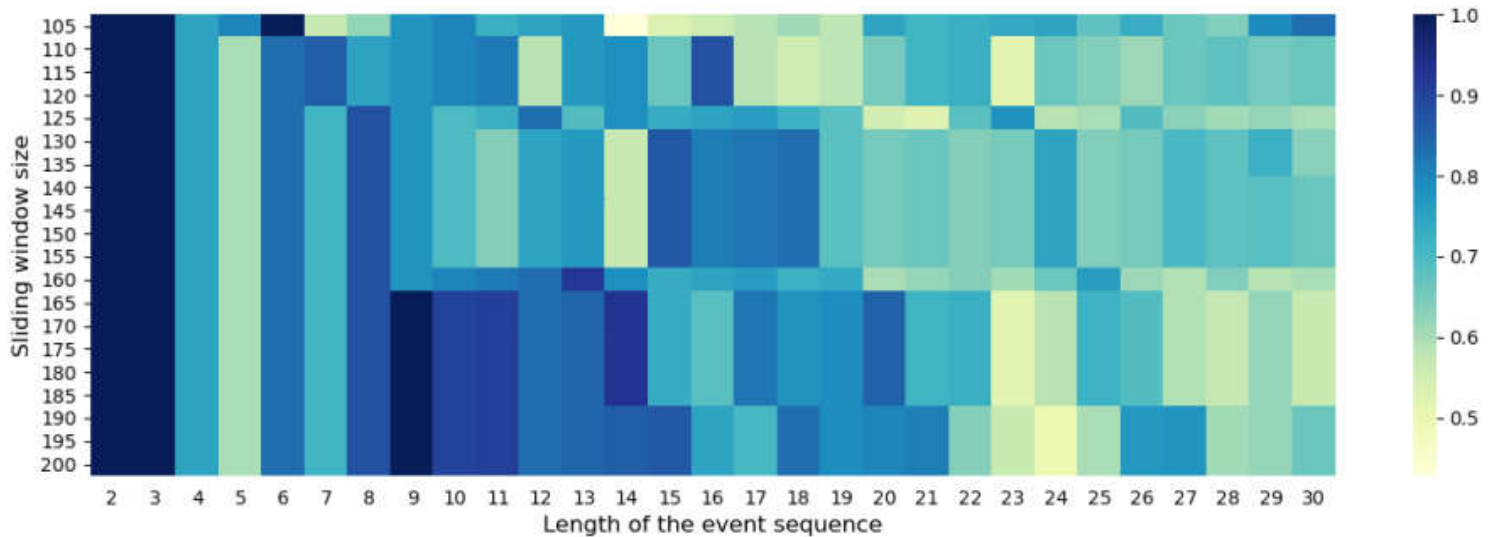
Computational Overhead

- We compute computational overhead for **forward-backward procedure** since IoTMonitor spends most of the computations for estimating probabilities



Accuracy Score

- Determines how accurately the extracted hidden sequence of events represent the actual IoT events triggered during the attack



Future Work

- Modeling the joint contribution of multiple events into leading a single trigger operation
- Investigating noisy sensor's impact on the observation space and the detection accuracy of attack path

Conclusion

- IoTMonitor uses a Hidden Markov Model based approach to determine the optimal attack sequence
- IoTMonitor leverages the probabilistic relation between physical evidence captured by sensors and actual IoT events triggered
- IoTMonitor discerns the underlying event sequence with $\geq 90\%$ accuracy mostly

Questions?