Machine Learning
ITCS 4156

Introduction

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What is (Human) Learning?

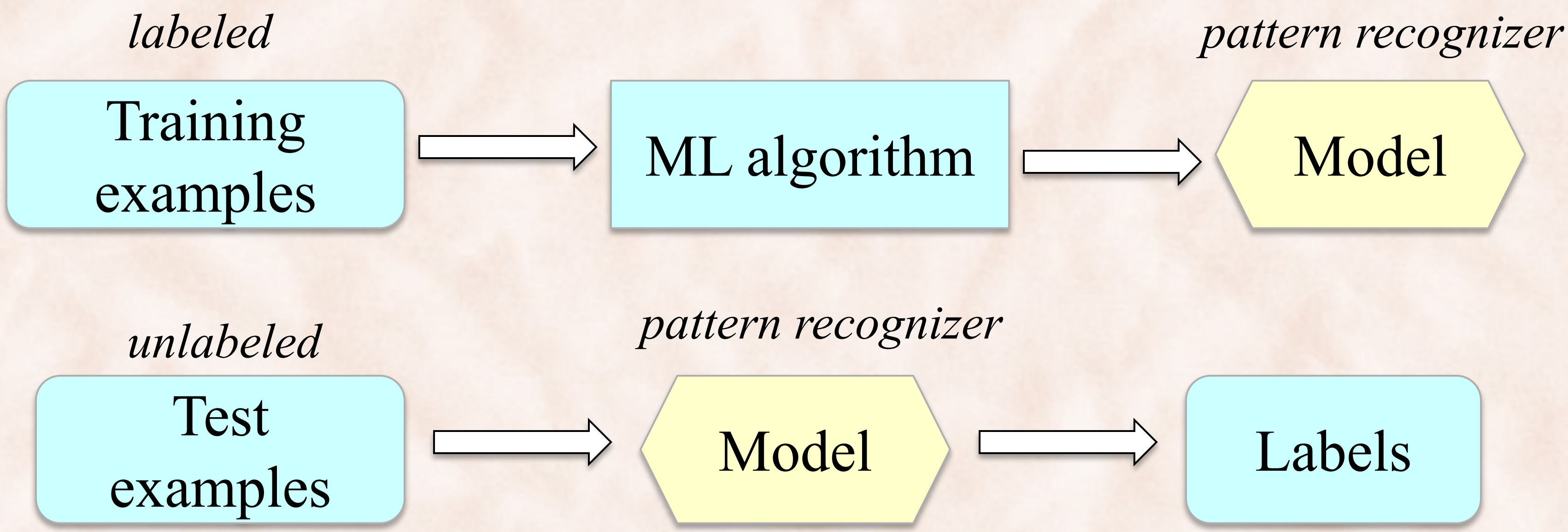
- Merriam-Webster:
  - ***learn*** = to acquire knowledge, understanding, or skill … by study, instruction, or ***experience***.

- Why do we learn?
  - to ***improve performance*** on a given ***task***.

- What (tasks) do we learn:
  1. categorize email, recognize faces, diagnose diseases, translate, …
  2. clustering (fish, insects, birds, mice, humans), summarization, sound source separation, …
  3. walk, play backgammon, ride bikes, drive cars, fly helicopters, …

What is Machine Learning?

- **Machine Learning** = constructing computer programs that *learn* from *experience* to perform well on a given task.
  - Supervised Learning i.e. discover patterns from labeled examples that enable predictions on (previously unseen) unlabeled examples.



ML is Meta-Programming

- An ML **model** (e.g. a *neural network*) is a computer **program**:
  - We do not want to explicitly program (model) the computer for each particular task.
  - Use a general ML algorithm and task-specific data to automatically create the Program, i.e. the Model, that solves the task.

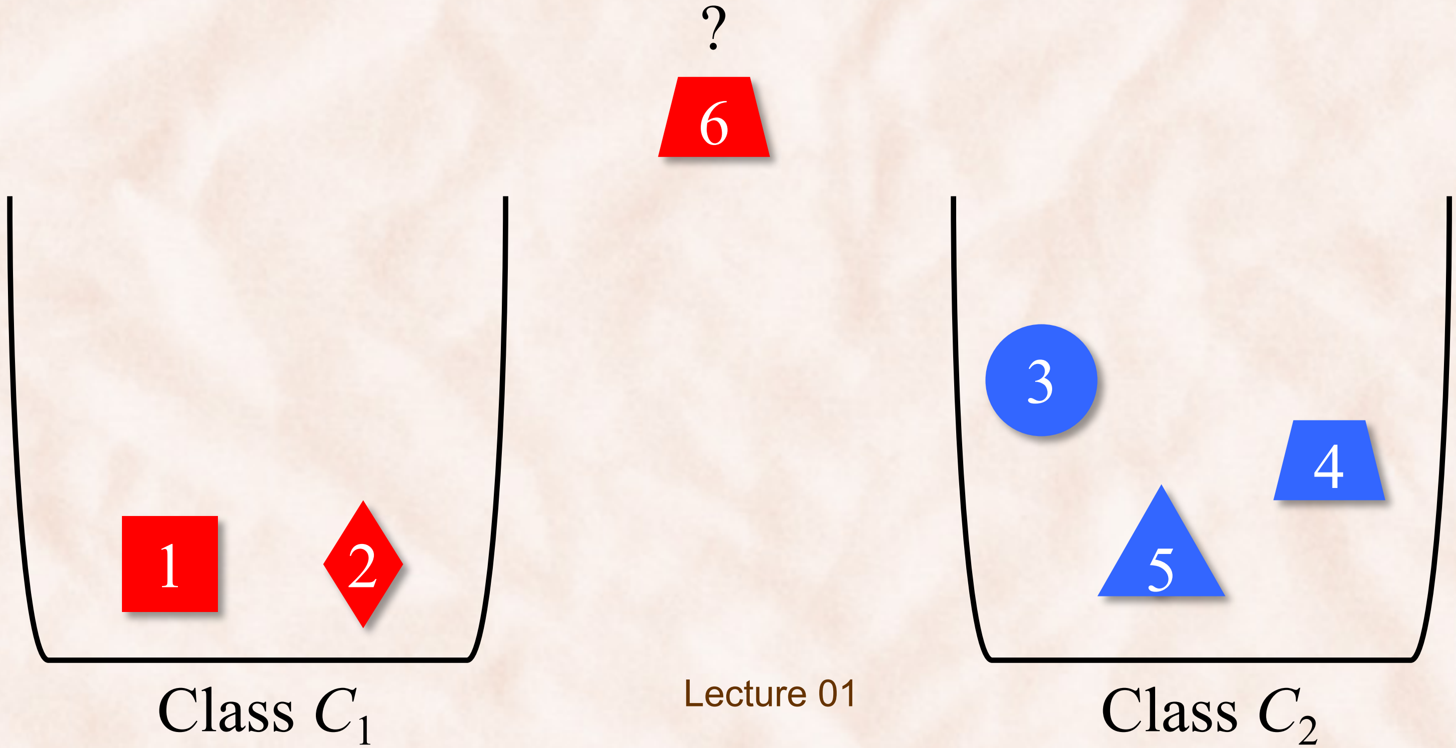
⇒ An ML algorithm (e.g. *gradient descent*) is a **meta-program**.

Example

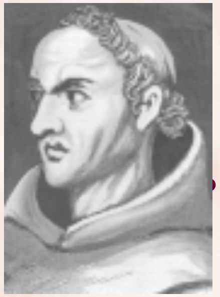
M_1: x is Red => $x \in C_1$

M_2: x is a Square or x is a Diamond => $x \in C_1$

M_3: x is Red and x is a Quadrilateral => $x \in C_1$



Occam's Razor



William of Occam (1288 – 1348)

- English Franciscan friar, theologian and philosopher.

- "*Entia non sunt multiplicanda praeter necessitatem*"
  - Entities must not be multiplied beyond necessity.

i.e. Do not make things needlessly complicated.

i.e. Prefer the simplest hypothesis that fits the data.

ML Objective

- Find a model **M**

  that is *simple* + that *fits the training data*.

$$\hat{\mathbf{M}} = \underset{\mathbf{M}}{\operatorname{argmin}} \; \mathit{Complexity}(\mathbf{M}) + \mathit{Error}(\mathbf{M}, \mathit{Data})$$

- **Inductive hypothesis**: Models that perform well on training examples are expected to do well on test (unseen) examples.

- **Occam's Razor**: Simpler models are expected to do better than complex models on test examples (assuming similar training performance).

Example

M_1: x is Red => $x \in C_1$

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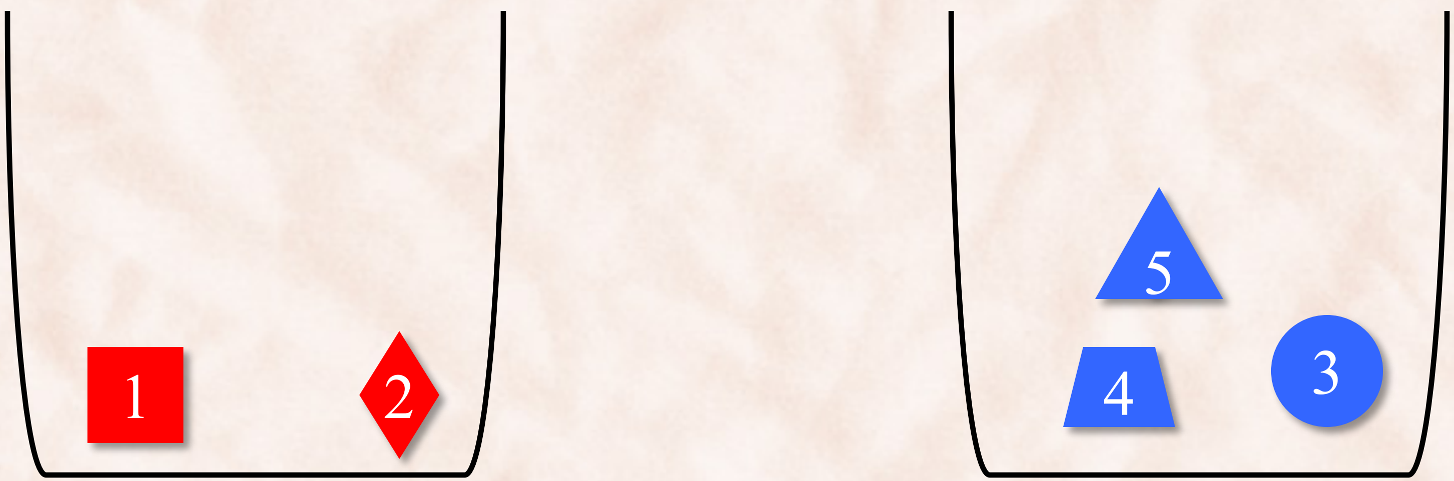
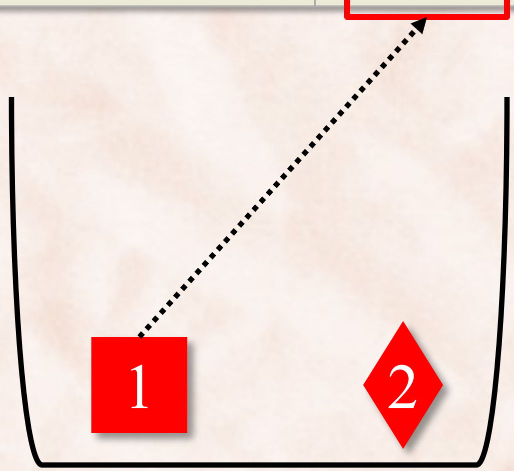


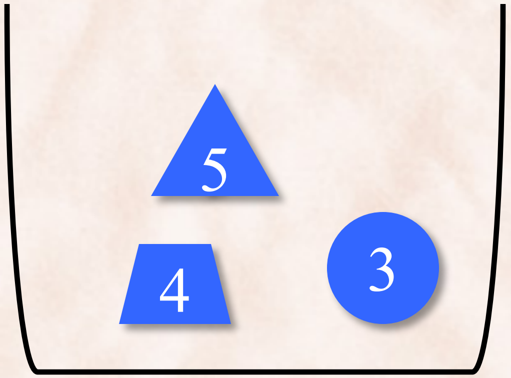
Class C_1 Class C_2

Feature Vectors

Features	$\varphi(x_1)$	$\varphi(x_2)$	$\varphi(x_3)$	$\varphi(x_4)$	$\varphi(x_5)$
(φ_1) **Red?**	1	1	0	0	0
(φ_2) **Quad?**	1	1	0	1	0
(φ_3) **Square?**	1	0	0	0	0
(φ_4) **Diamond?**	0	1	0	0	0
(y) **Label**	$y_1=+1$	$y_2=+1$	$y_3=-1$	$y_4=-1$	$y_5=-1$



Class C_1



Class C_2

Learning with Labeled Feature Vectors

Features	$\varphi(x_1)$	$\varphi(x_2)$	$\varphi(x_3)$	$\varphi(x_4)$	$\varphi(x_5)$
(φ_1) Red?	1	1	0	0	0
(φ_2) Quad?	1	1	0	1	0
(φ_3) Square?	1	0	0	0	0
(φ_4) Diamond?	0	1	0	0	0
(y) Label	y_1=+1	y_2=+1	y_3=−1	y_4=−1	y_5=−1

$\varphi(x_1) = [1, 1, 1, 0]^T$ $\varphi(x_2) = [1, 1, 0, 1]^T$ $\varphi(x_3) = [0, 0, 0, 0]^T$ ...

y_1=+1 y_2=+1 y_3=−1 ...

Learning = finding parameters $\mathbf{w} = [w_1, w_2, w_3, w_4]^T$ and τ such that:

- $\mathbf{w}^T\varphi(x_i) \geq \tau$, if $y_i = +1$
- $\mathbf{w}^T\varphi(x_i) < \tau$, if $y_i = -1$

where $\mathbf{w}^T\varphi(x) = w_1\varphi_1(x) + w_2\varphi_2(x) + w_3\varphi_3(x) + w_4\varphi_4(x)$

Model M_1: $\mathbf{x}_i$ is Red => $y_i = +1$

Red? Quad? Square? Diamond?

$\varphi(x_1) = [1, 1, 1, 0]^T$ label $y_1 = +1$ => $\mathbf{w}^T\varphi(x_1) = 1 \geq 1$
$\varphi(x_2) = [1, 1, 0, 1]^T$ label $y_2 = +1$ => $\mathbf{w}^T\varphi(x_2) = 1 \geq 1$
$\varphi(x_3) = [0, 0, 0, 0]^T$ label $y_3 = -1$ => $\mathbf{w}^T\varphi(x_3) = 0 < 1$
$\varphi(x_4) = [0, 1, 0, 0]^T$ label $y_3 = -1$ => $\mathbf{w}^T\varphi(x_4) = 0 < 1$
$\varphi(x_5) = [0, 0, 0, 0]^T$ label $y_3 = -1$ => $\mathbf{w}^T\varphi(x_5) = 0 < 1$

$\boxed{\mathbf{w} = [1, 0, 0, 0]^T}$

$\boxed{= > \mathbf{M_1} \textbf{ error is 0\%}}$

Learning = finding parameters $\mathbf{w} = [w_1, w_2, w_3, w_4]^T$ such that ($\tau = 1$):

- $\mathbf{w}^T\varphi(x_i) \geq 1$, if $y_i = +1$
- $\mathbf{w}^T\varphi(x_i) < 1$, if $y_i = -1$

where $\mathbf{w}^T\varphi(x) = w_1\varphi_1(x) + w_2\varphi_2(x) + w_3\varphi_3(x) + w_4\varphi_4(x)$

M_2: $\mathbf{x}_i$ is Square or Diamond => $y_i = +1$

Red? Quad? Square? Diamond?

$\varphi(x_1) = [1, 1, 1, 0]^T$ label $y_1 = +1$ => $\mathbf{w}^T\varphi(x_1) = 1 \geq 1$

$\varphi(x_2) = [1, 1, 0, 1]^T$ label $y_2 = +1$ => $\mathbf{w}^T\varphi(x_2) = 1 \geq 1$

$\varphi(x_3) = [0, 0, 0, 0]^T$ label $y_3 = -1$ => $\mathbf{w}^T\varphi(x_3) = 0 < 1$

$\varphi(x_4) = [0, 1, 0, 0]^T$ label $y_3 = -1$ => $\mathbf{w}^T\varphi(x_4) = 0 < 1$

$\varphi(x_5) = [0, 0, 0, 0]^T$ label $y_3 = -1$ => $\mathbf{w}^T\varphi(x_5) = 0 < 1$

$\boxed{\mathbf{w} = [0, 0, 1, 1]^T}$

$\boxed{= > \mathbf{M_2} \textbf{ error is 0\%}}$

Learning = finding parameters $\mathbf{w} = [w_1, w_2, w_3, w_4]^T$ such that ($\tau = 1$):

- $\mathbf{w}^T\varphi(x_i) \geq 1$, if $y_i = +1$
- $\mathbf{w}^T\varphi(x_i) < 1$, if $y_i = -1$

where $\mathbf{w}^T\varphi(x) = w_1\varphi_1(x) + w_2\varphi_2(x) + w_3\varphi_3(x) + w_4\varphi_4(x)$

Definition: *Bias* $w_0 = -$ *Threshold* τ

$w_1\varphi_1(x) + w_2\varphi_2(x) + w_3\varphi_3(x) + w_4\varphi_4(x) \geq \tau$

$w_1\varphi_1(x) + w_2\varphi_2(x) + w_3\varphi_3(x) + w_4\varphi_4(x) - \tau \geq 0$

Define the **bias** $w_0 = -\tau$.

$w_1\varphi_1(x) + w_2\varphi_2(x) + w_3\varphi_3(x) + w_4\varphi_4(x) + w_0 \geq 0$

$h(\mathbf{x}) = \mathbf{w}^T\varphi(\mathbf{x}) + w_0 \geq 0$

where:

$\mathbf{w} = [w_1, w_2, w_3, w_4]$

$\varphi(x) = [\varphi_1(x), \varphi_2(x), \varphi_3(x), \varphi_4(x)]$

Linear Discriminant Functions: Two classes ($K = 2$)

- Use a linear function of the input vector:

$$h(\mathbf{x}) = \mathbf{w}^T \varphi(\mathbf{x}) + w_0$$

weight vector

bias = – threshold

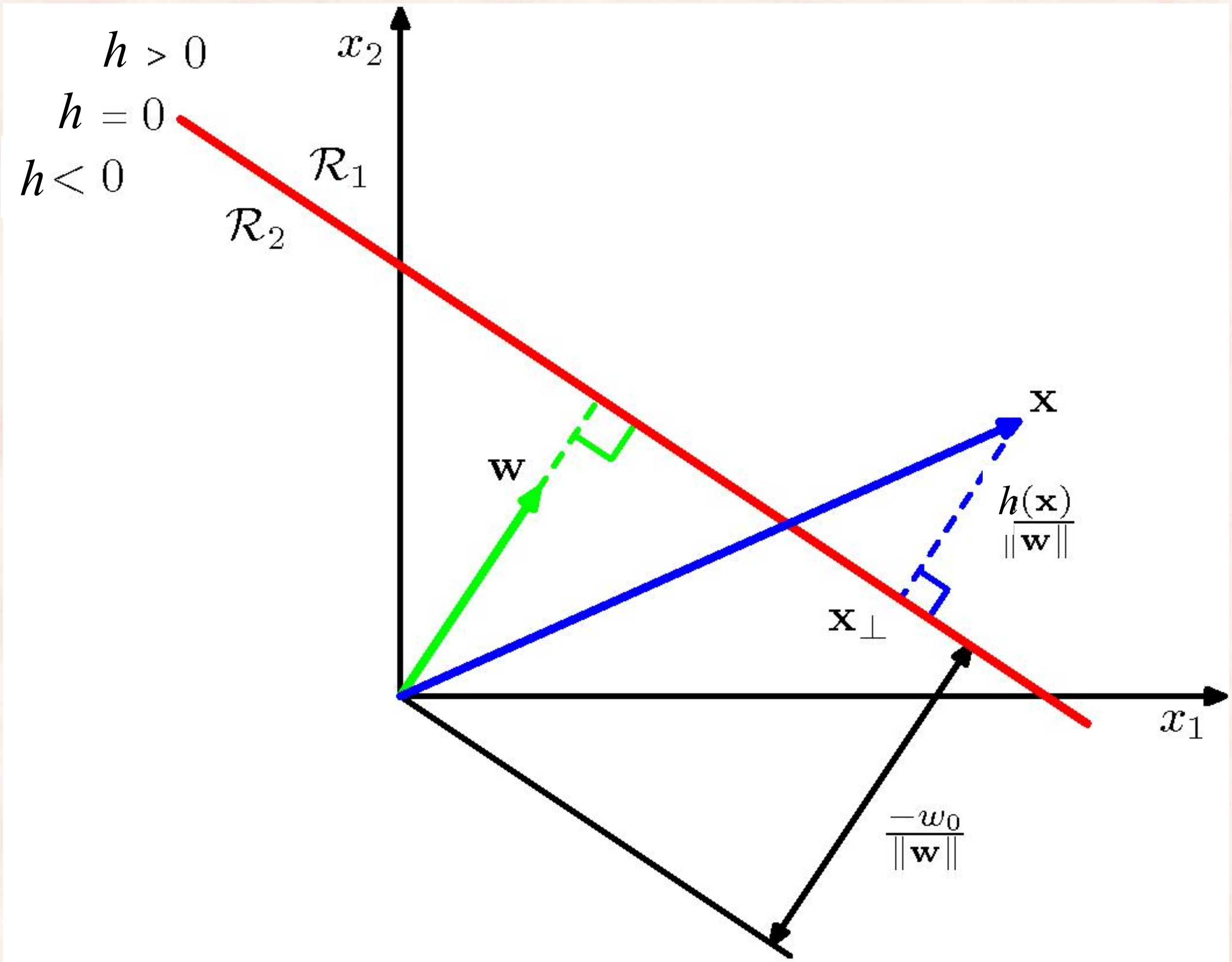
- Decision:

  $\mathbf{x} \in C_1$ if $h(\mathbf{x}) \geq 0$, otherwise $\mathbf{x} \in C_2$.

  $\Rightarrow$ **decision boundary is hyperplane $h(\mathbf{x}) = 0$.**

- Properties:
  - $\mathbf{w}$ is orthogonal to vectors lying within the decision surface.
  - w_0 controls the location of the decision hyperplane.

Geometric Interpretation



The Perceptron Algorithm: Two Classes $t_n \in \{+1, -1\}$

1. **initialize** parameters $\mathbf{w} = 0$
2. **for** $n = 1 \ldots \mathrm{N}$
3. $\quad h_n = sgn(\mathbf{w}^{\mathrm{T}}\mathbf{x}_n)$
4. $\quad$ **if** $h_{\mathrm{n}} \neq t_n$ **then**
5. $\quad\quad \mathbf{w} = \mathbf{w} + t_n\mathbf{x}_n$

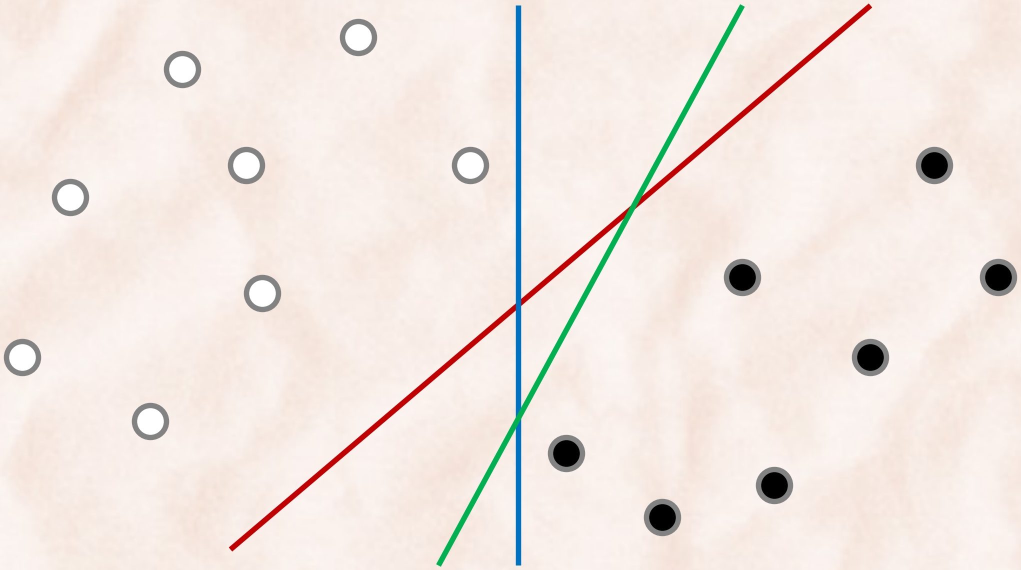
Repeat:
a) until convergence.
b) for a number of epochs E.

Theorem [Rosenblatt, 1962]:

If the training dataset is linearly separable, the perceptron learning algorithm is guaranteed to find a solution in a finite number of steps.

- see Theorem 1 (Block, Novikoff) in [Freund & Schapire, 1999].

Classifiers & Margin



The Perceptron Algorithm: Two Classes

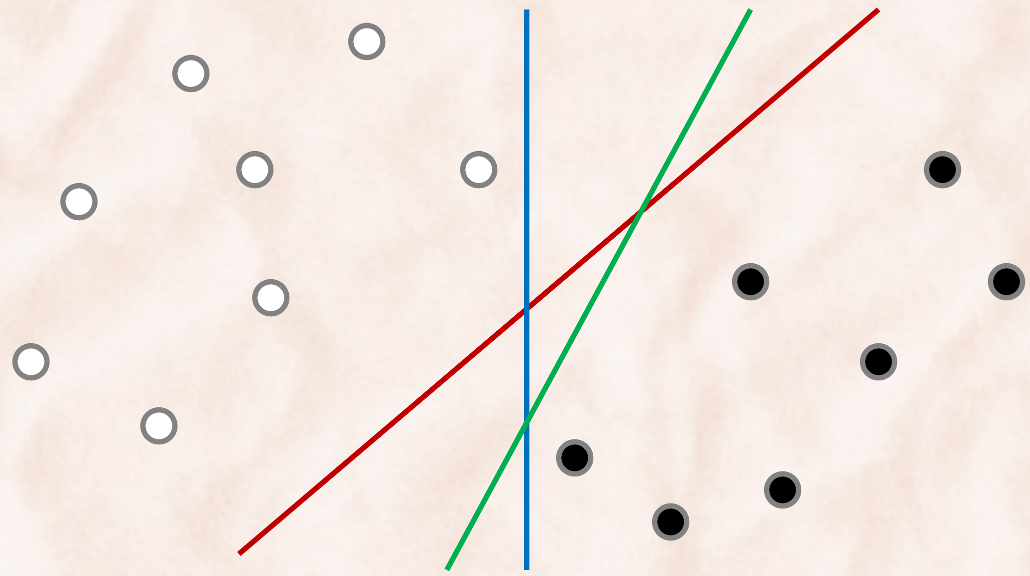
1. **initialize** parameters $\mathbf{w} = 0$
2. **for** $n = 1 \ldots \mathrm{N}$
3. $\quad h_n = sgn(\mathbf{w}^{\mathrm{T}}\mathbf{x}_n)$
4. $\quad$ **if** $h_n \neq t_n$ **then**
5. $\quad\quad \mathbf{w} = \mathbf{w} + t_n\mathbf{x}_{\mathrm{n}}$

Repeat:
a) until convergence.
b) for a number of epochs E.

Loop invariant: **w** is a weighted sum of training vectors:

$$\mathbf{w} = \sum_n \alpha_n t_n \mathbf{x}_n \quad \Rightarrow \quad \mathbf{w}^T\mathbf{x} = \sum_n \alpha_n t_n \mathbf{x}_n^T \mathbf{x}$$

Classifiers & Margin



- Which classifier has the smallest generalization error?
  - The one that maximizes the margin [Computational Learning Theory]
    - **margin** = the distance between the decision boundary and the closest sample.

M_1 or M_2?

- Model M_1: **$\mathbf{x}_i$ is Red => $y_i = +1$**
  - **$\mathbf{w}^{(1)} = [1, 0, 0, 0]^T$**
  - **Error = 0%**

- Model M_2: **$\mathbf{x}_i$ is Square or Diamond => $y_i = +1$**
  - **$\mathbf{w}^{(2)} = [0, 0, 1, 1]^T$**
  - **Error = 0%**

- Which one should we choose?
  - Which one is expected to perform better on unseen (new) examples?

ML Objective

- Find a model **w** that is *simple* and that *fits the training data*.

$$\hat{\mathbf{w}} = \arg\min_{\mathbf{w}} \ \text{Complexity}(\mathbf{w}) + \text{Error}(\mathbf{w}, \mathit{Data})$$

M_1 or M_2?

- Model M_1: **$\mathbf{x}_i$ is Red => y_i = +1**
  - $\mathbf{w}^{(1)} = [1, 0, 0, 0]^T$
  - **Error = 0%**
- Model M_2: **$\mathbf{x}_i$ is Square or Diamond => y_i = +1**
  - $\mathbf{w}^{(2)} = [0, 0, 1, 1]^T$
  - **Error = 0%**

$$\hat{\mathbf{w}} = \arg\min_{\mathbf{w}} \ \text{Complexity}(\mathbf{w}) + \text{Error}(\mathbf{w}, \mathit{Data})$$

$\boxed{\text{Complexity}(\mathbf{w}) = ?}$

$\boxed{\|\mathbf{w}\|_0 \text{ i.e. \# non-zero values}}$

$\boxed{\|\mathbf{w}\|_1 \text{ i.e. sum of absolute values}}$

$\boxed{\|\mathbf{w}\|_2 \text{ i.e sum of squared values}}$

ML Objectives

- Find a model **w** that is *simple* and that *fits the training data*.

$$\hat{\mathbf{w}} = \arg\min_{\mathbf{w}} \ \text{Complexity}(\mathbf{w}) + \text{Error}(\mathbf{w}, Data)$$

Ridge Regression:

$$\operatorname*{argmin}_{\mathbf{w}} \ \frac{\lambda}{2}\|\mathbf{w}\|^2 + \frac{1}{2}\sum_{n=1}^{N}\{y(x_n, \mathbf{w}) - t_n\}^2$$

Logistic Regression:

$$\operatorname{argmin} \frac{\alpha}{2}\|\mathbf{w}\|^2 - \sum_{n=1}^{N} \ln p(t_n | x_n)$$

ML Objectives

Support Vector Machines:

Upper bound on the number of misclassified training examples

$$\underset{\mathbf{w}}{\operatorname{argmin}} \; \frac{1}{2}\|\mathbf{w}\|^2 + C\sum_{n=1}^{N}\xi_n$$

subject to:

$$t_n(\mathbf{w}^T\varphi(\mathbf{x}_n)+b) \geq 1-\xi_n, \quad \forall n \in \{1,\ldots,N\}$$
$$\xi_n \geq 0$$

ML Concepts & Notation

- A (labeled) example ($\mathbf{x}$, t) consists of:
  - Instance / observation / raw feature vector $\mathbf{x}$.
  - Label t.

- Examples:
  1. Digit recognition:

     instance $\mathbf{x}$ = ?

     label t = ?

  2. Language modelling:
     - "machine .... is a hot topic in AI"

     gun … *learning* … *on*

     instance $\mathbf{x}$ = ?

     label t = ?

ML Concepts & Notation

- Often, a raw observation $\mathbf{x}$ is pre-processed and further transformed into a feature vector $\varphi(\mathbf{x}) = [\varphi_1(\mathbf{x}), \varphi_1(\mathbf{x}), \ldots, \varphi_K(\mathbf{x})]^T$.
  - Where do the features φ_k come from?
    - Feature engineering, e.g. in polynomial curve fitting:
      - manual, can be time consuming (e.g. SIFT).
    - Feature learning, e.g. in modern computer vision:
      - automatic, used in deep learning models.
        - » Unsupervised (e.g. auto-encoders), or
        - » Implicit (e.g. in deep CNNs).

ML Concepts & Notation

- A training dataset is a set of (training) examples $(\mathbf{x}_1,t_1)$, $(\mathbf{x}_2,t_2)$, … $(\mathbf{x}_N,t_N)$:
  - The data matrix X contains all instance vectors $\mathbf{x}_1$, $\mathbf{x}_2$, …, $\mathbf{x}_N$ row-wise.
  - The label vector $\mathbf{t} = [t_1, t_2, \ldots, t_N]^T$.

- A test dataset is a set of (test) examples $(\mathbf{x}_{N+1},t_{N+1})$, …, $(\mathbf{x}_{N+M},t_{N+M})$:
  - Must be new/**unseen**, i.e. not from the training examples!

ML Concepts & Notation

- There is a function f that maps an instance $\mathbf{x}$ to its label $t = f(\mathbf{x})$.
  - f is unknown / not given.
  - But we observe samples from f : $(\mathbf{x}_1, t_1)$, $(\mathbf{x}_2, t_2)$, … $(\mathbf{x}_N, t_N)$.

- Learning means finding a model h that maps an instance $\mathbf{x}$ to a label $h(\mathbf{x}) \approx f(\mathbf{x})$, i.e. close to the true label of $\mathbf{x}$.
  - Machine learning = finding a model h that approximates well the unknown function f.
  - Machine learning = function approximation!

ML Concepts & Notation

- Machine learning is inductive:
  - Inductive hypothesis: if a model performs well on training examples, it is expected to also perform well on unseen (test) examples.
- The model y is often specified through a set of parameters $\mathbf{w}$:
  - $\mathbf{x}$ is mapped by the model to $h(\mathbf{x}, \mathbf{w})$.
- The objective function $J(\mathbf{w})$ captures how poorly the model does on the training dataset:
  - Want to find $\hat{\mathbf{w}} = \underset{\mathbf{w}}{\operatorname{argmin}} J(\mathbf{w})$
    - Machine learning = optimization!

Fitting vs. Generalization

- Fitting performance = how well the model performs on training examples.

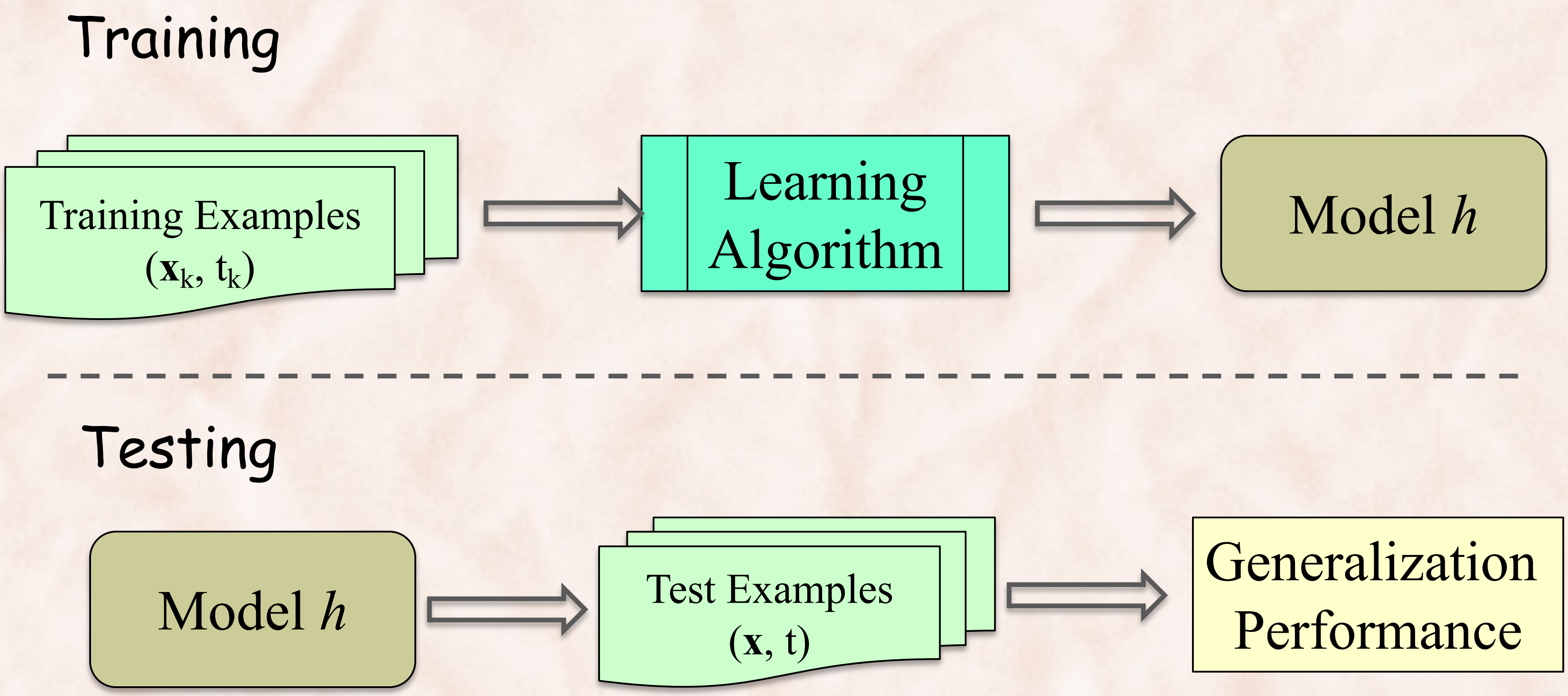
- Generalization performance = how well the model performs on unseen (test) examples.

- We are interested in **Generalization**:
  - Prefer finding patterns to memorizing examples!
    - Overfitting: Model performs much better on training than test examples.
    - Underfitting: Model is not trained enough, not achieving good performance on either training or testing.
    - Regularization:

Regularization = Any Method that Alleviates Overfitting

- **Parameter norm penalties** (term in the objective).
- Limit parameter norm (constraint).
- **Dataset augmentation**.
- **Dropout**.
- **Ensembles**.
- Semi-supervised learning.
- **Early stopping**.
- Noise robustness.
- Sparse representations.
- Adversarial training.

Supervised Learning



Features

- Learning = finding parameters $\mathbf{w} = [w_1, w_2, w_3, w_4]$ and τ such that:

$$\mathbf{w}^T\varphi(x_i) \geq \tau, \text{ if } y_i = +1$$

$$\mathbf{w}^T\varphi(x_i) < \tau, \text{ if } y_i = -1$$

where $\mathbf{w}^T\varphi(x) = w_1\times\varphi_1(x) + w_2\times\varphi_2(x) + w_3\times\varphi_3(x) + w_4\times\varphi_4(x)$

Red? Quad? Square? Diamond?

$\boxed{\text{Where do these features come from?}}$

Object Recognition: Cats





Pixels as Features?

$\varphi(x)$ = [25, 63, 125, 32, 84, 257, ..., 13,
27, 39, 8, 213, 107, 54, 73, ..., 91,
..., 9,
..., 28,
93, 44, 69, 85, 68, 54, 87, ..., 11,
117, 59, 117, 210, 177, 54, 72, ...]^T

Poor recognition accuracy!

- Learning = finding parameters $\mathbf{w} = [w_1, w_2, w_3, \ldots w_k]^T$ such that:

  $\mathbf{w}^T\varphi(x_i) \geq \tau$, if $y_i = +1$ (cat)

  $\mathbf{w}^T\varphi(x_i) < \tau$, if $y_i = -1$ (other)

  where $\mathbf{w}^T\varphi(x) = w_1\times\varphi_1(x) + w_2\times\varphi_2(x) + w_3\times\varphi_3(x) + \ldots w_k\times\varphi_k(x)$

ML Concepts & Notation

- Often, a raw observation $\mathbf{x}$ is pre-processed and further transformed into a feature vector $\varphi(\mathbf{x}) = [\varphi_1(\mathbf{x}), \varphi_1(\mathbf{x}), \ldots, \varphi_K(\mathbf{x})]^T$.
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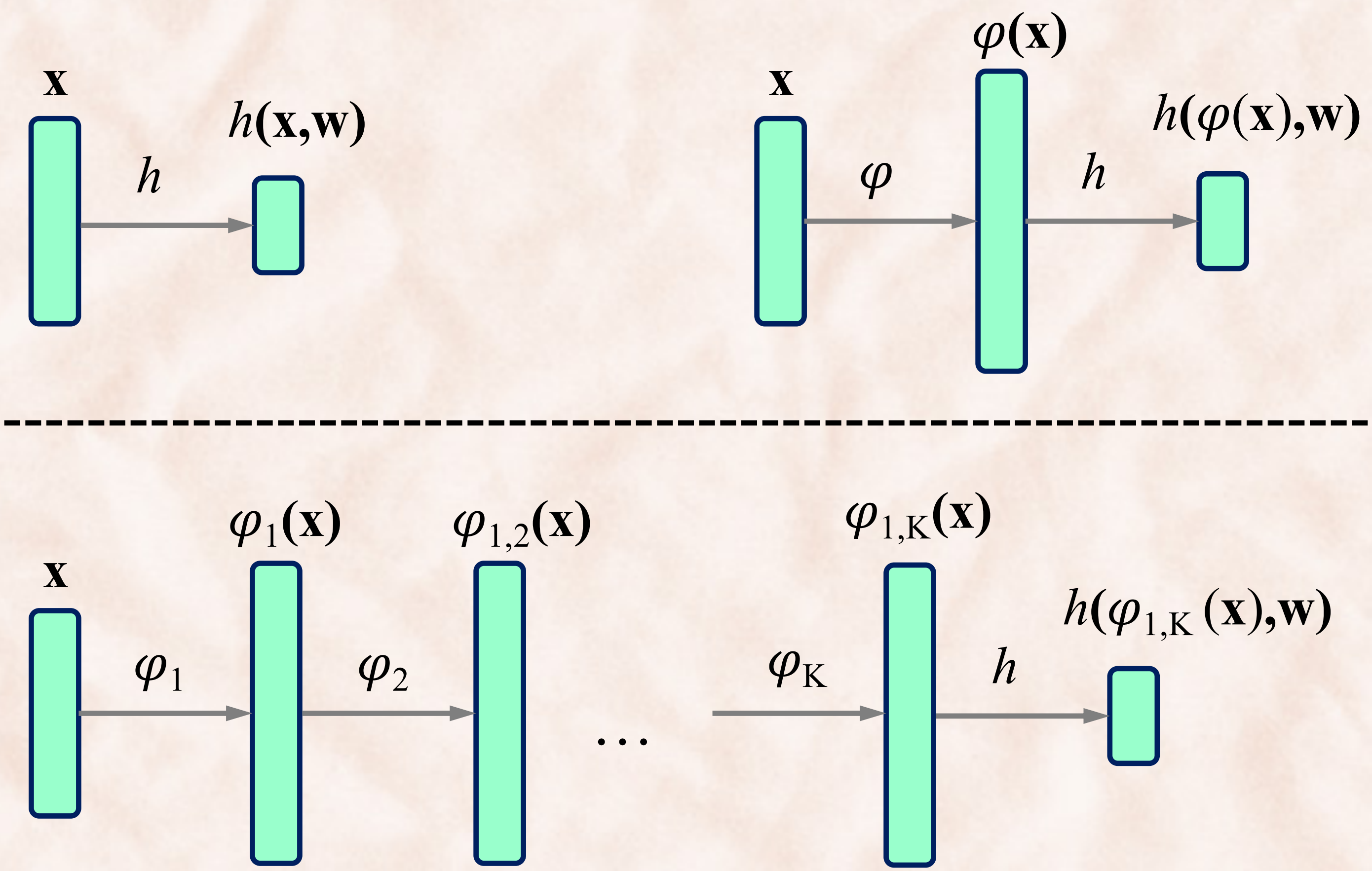
Machine Learning vs. Deep Learning



What is Machine Learning?

- **Machine Learning** = constructing computer programs that *automatically improve with experience*:
  - Supervised Learning i.e. learning from labeled examples:
    - Classification
    - Regression
  - Unsupervised Learning i.e. learning from unlabeled examples:
    - Clustering.
    - Dimensionality reduction (visualization).
    - Density estimation.
  - Reinforcement Learning i.e. learning with delayed feedback.

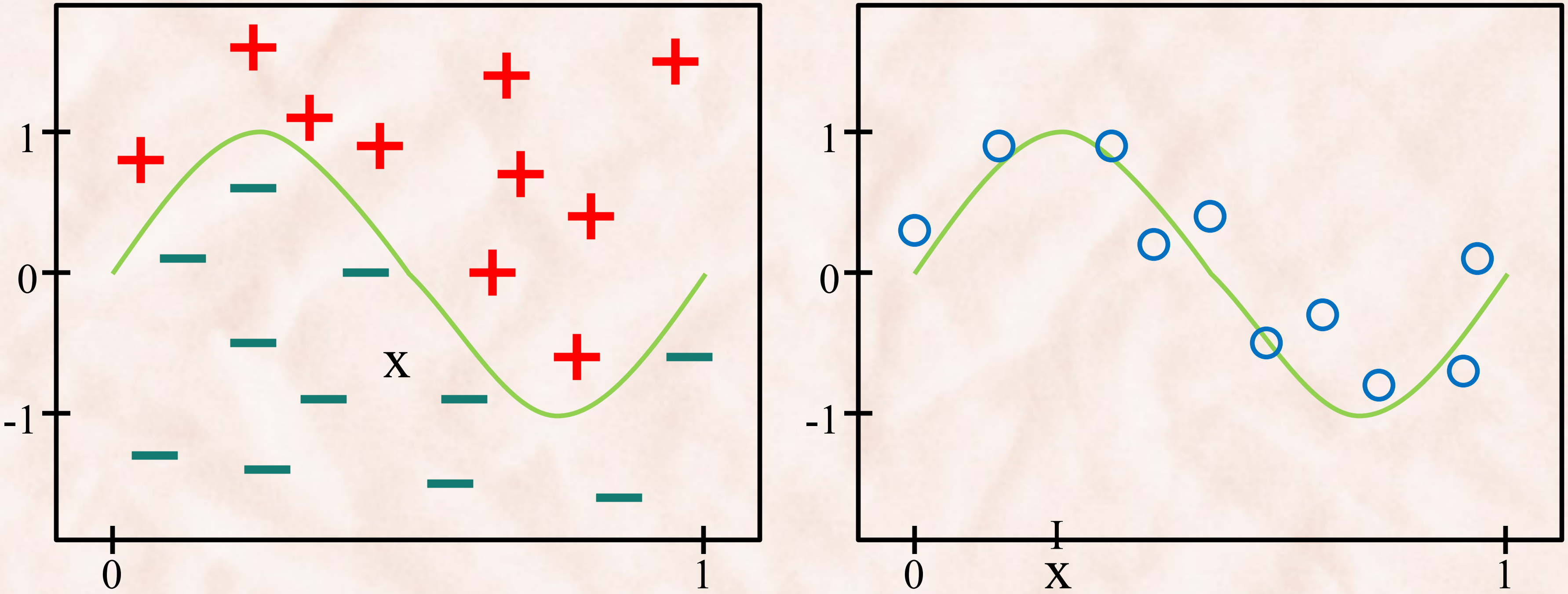
  - Association rule learning, Sequential pattern mining, …

Supervised Learning

- Task = learn a function $f : X \rightarrow T$ that maps input instances $\mathbf{x} \in X$ to output targets $t \in T$:
  - **Classification**:
    - The output $t \in T$ is one of a finite set of discrete categories.
  - **Regression**:
    - The output $t \in T$ is continuous, or has a continuous component.
- Supervision = set of training examples:

  $(\mathbf{x}_1, t_1), (\mathbf{x}_2, t_2), \ldots (\mathbf{x}_n, t_n)$

Classification vs. Regression



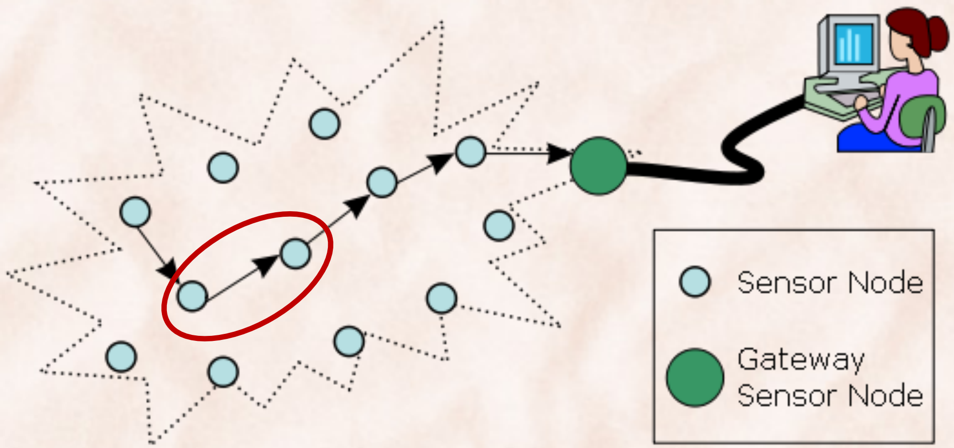
Classification: Junk Email Filtering

[Sahami, Dumais & Heckerman, AAAI'98]

From: Tammy Jordan jordant@oak.cats.ohiou.edu **Subject: Spring 2015 Course** **--** CS690: Machine Learning Instructor: Razvan Bunescu Email: bunescu@ohio.edu Time and Location: Tue, Thu 9:00 AM , ARC 101 Website: http://ace.cs.ohio.edu/~razvan/courses/ml6830 Course description: Machine Learning is concerned with the design and analysis of algorithms that enable computers to automatically find patterns in the data. This introductory course will give an overview …	**From: UK National Lottery** **edreyes@uknational.co.uk** **Subject: Award Winning Notice** **--** **UK NATIONAL LOTTERY. GOVERNMENT ACCREDITED LICENSED LOTTERY. REGISTERED UNDER THE UNITED KINGDOM DATA PROTECTION ACT;** **We happily announce to you the draws of (UK NATIONAL LOTTERY PROMOTION) International programs held in London , England Your email address attached to ticket number :3456 with serial number :7576/06 drew the lucky number 4-2-274, which subsequently won you the lottery in the first category …**

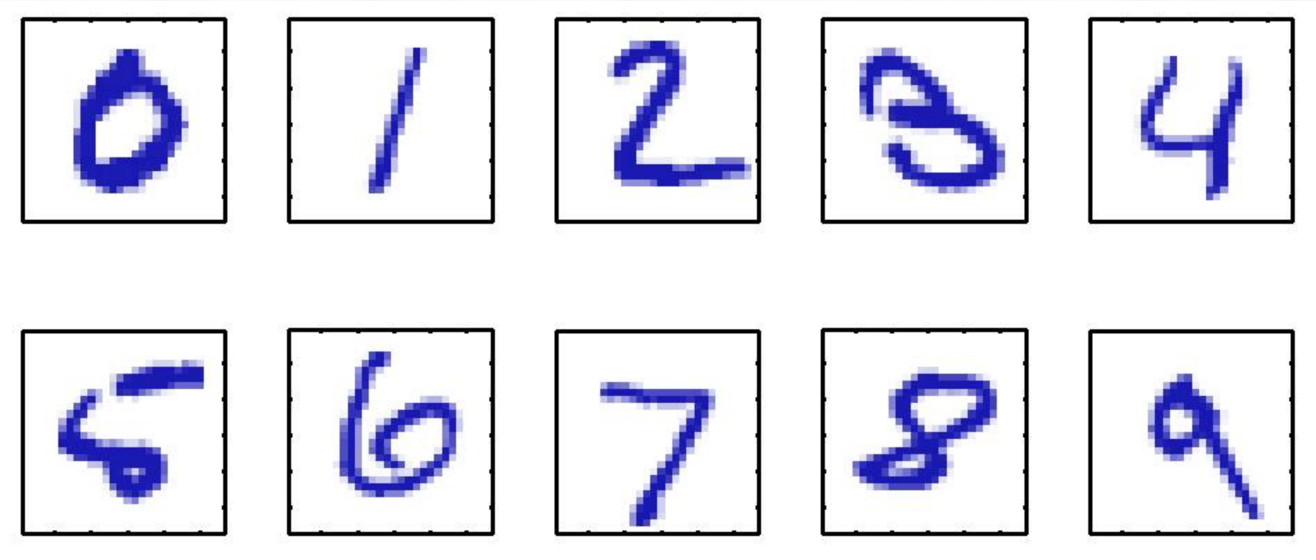
- Email filtering:
  - Provide emails labeled as *{Spam, Ham}*.
  - Train *Naïve Bayes* model to discriminate between the two.

Classification: Routing in Wireless Sensor Networks [Wang, Martonosi & Peh, SECON'06]



- Link quality prediction:
  - Provide a set of training links:
    - received signal strength, send/forward buffer sizes
    - node depth from base station, forward/backward probability
    - LQI = Link Quality Indication, binarized as {Good, Bad}
  - Train *Decision Trees* model to predict LQ using runtime features.

Classification: Handwritten Zip Code Recognition [Le Cun et al., Neural Computation ‘89]



- Handwritten digit recognition:
  – Provide images of handwritten digits, labeled as {0, 1, …, 9}.
  – Train *Neural Network* model to recognize digits from input images.

Classification: Medical Diagnosis

[Krishnapuram et al., GENSIPS'02]

- Cancer diagnosis from gene expression signatures:
  - Create database of gene expression profiles (X) from tissues of known cancer status (Y):
    - Human accute leukemia dataset:
      - http://www.broadinstitute.org/cgi-bin/cancer/datasets.cgi
    - Colon cancer microarray data:
      - http://microarray.princeton.edu/oncology
  - Train *Logistic Regression* / *SVM* / *RVM* model to classify the gene expression of a tissue of unknown cancer status.

ML for Software Verification / ATP

- Software verification requires theorem proving.
- Proving a mathematical theorem requires finding and using relevant previous theorems and definitions:
  - The space of existing theorems and definitions is huge.
  - Use machine learning to narrow the search space to relevant theorems and definitions:
    - "Premise Selection for Mathematics by Corpus Analysis and *Kernel Methods*", Alama et al., JAR 2012.
    - "DeepMath – *Deep Sequence* Models for Premise Selection", Alemi et al., NIPS 2016.
    - "Learning to Prove Theorems via Interacting with Proof Assistants", *TreeLSTM encoder-decoder*, Yang & Deng, ICML 2019.

Classification: Other Examples

- Named Entity Recognition
- Named Entity Disambiguation
- Relation Extraction
- Word Sense Disambiguation
- Coreference Resolution
- Sentiment Analysis
- Semantic Parsing
- Chord Recognition
- Voice Separation
- Tone recognition
- Hand Gesture Recognition
- Blood Glucose Level Prediction
- Galaxy Morphology Recognition
- Dysarthria Prediction
- Tone Classification in Mandarin Chinese
- Thread Migration
- Dynamic Voltage and Frequency Scaling

Regression: Examples

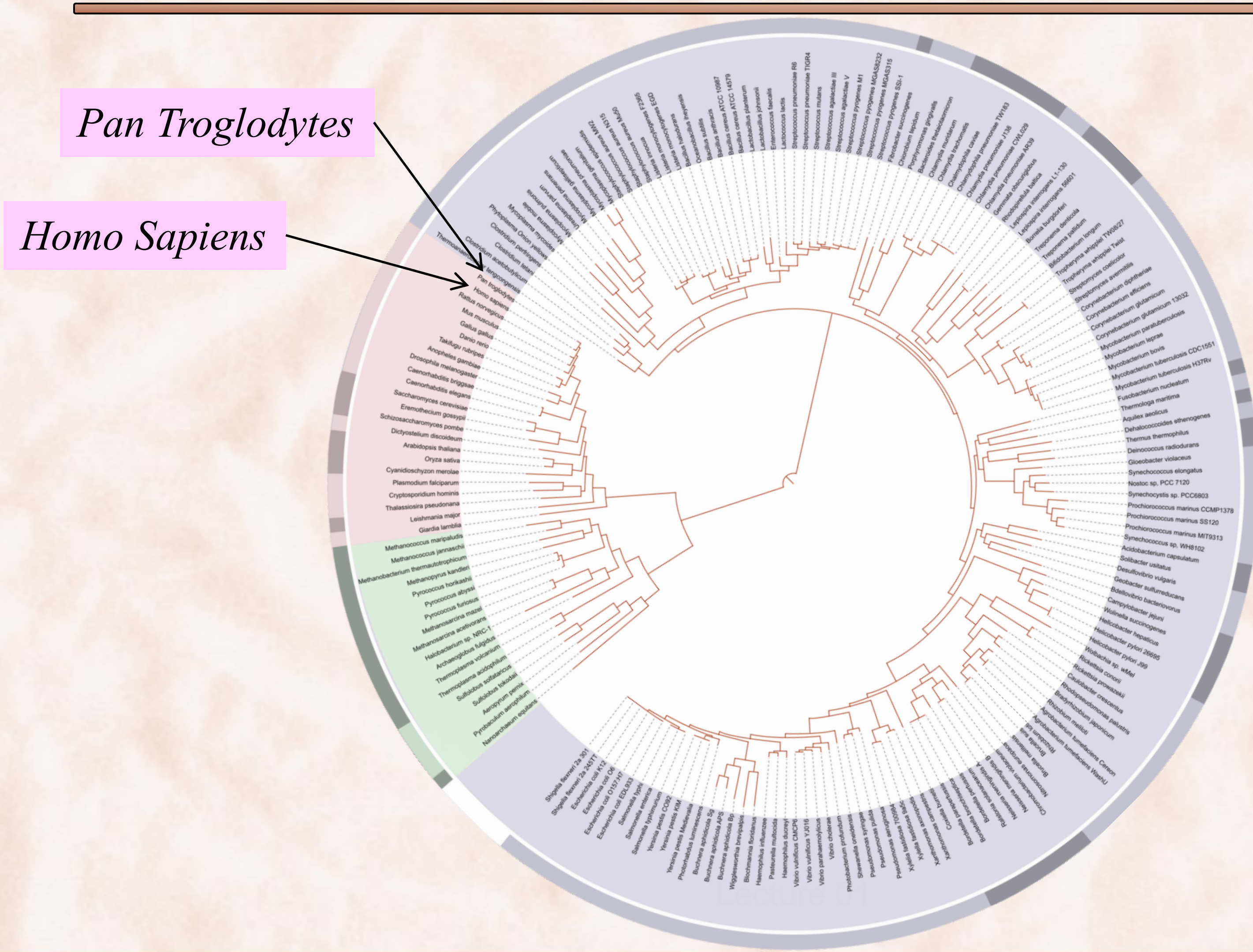
1. Stock market prediction:
   – Use the current stock market conditions ($x \in X$) to predict tomorrow's value of a particular stock ($t \in T$).

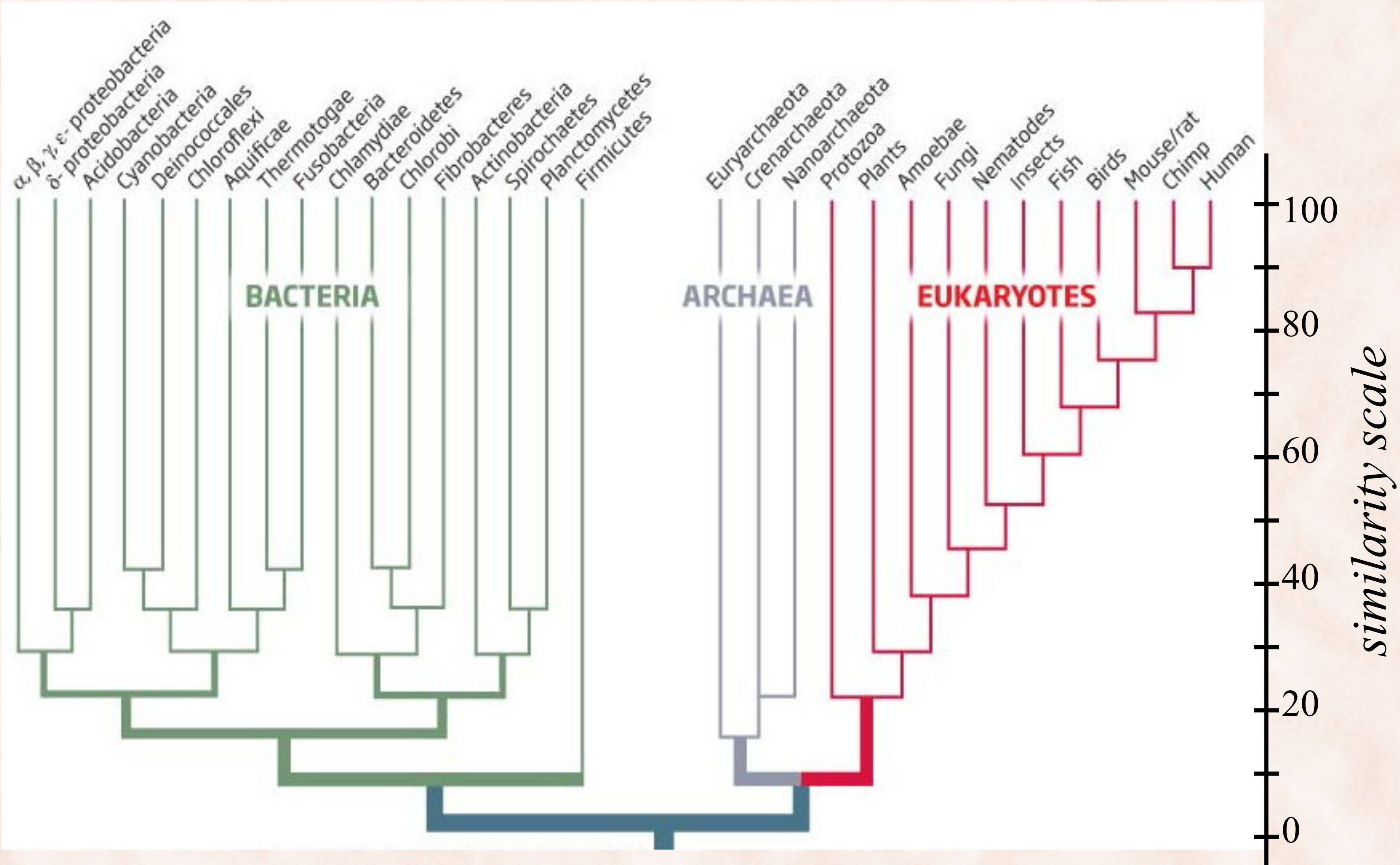
2. Oil price, GDP, income prediction.

3. Chemical processes:
   – Predict the yield in a chemical process based on the concentrations of reactants, temperature and pressure.

- Algorithms:
  – *Linear Regression*, *Neural Networks*, *Support Vector Machines*, …

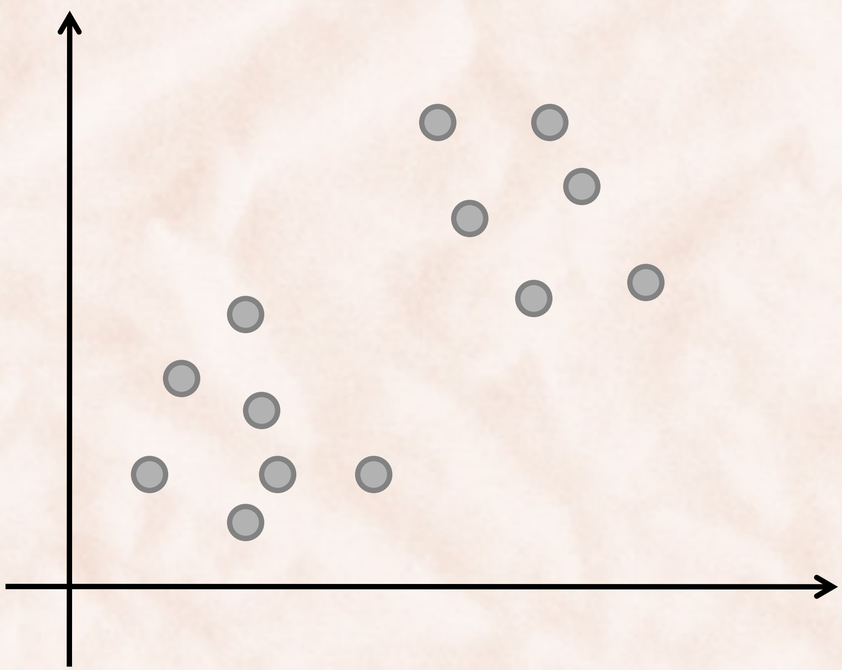
Unsupervised Learning: Hierarchical Clustering




α, β, γ, ε- proteobacteria
δ- proteobacteria
Acidobacteria
Cyanobacteria
Deinococcales
Chloroflexi
Aquificae
Thermotogae
Fusobacteria
Chlamydiae
Bacteroidetes
Chlorobi
Fibrobacteres
Actinobacteria
Spirochaetes
Planctomycetes
Firmicutes
Euryarchaeota
Crenarchaeota
Nanoarchaeota
Protozoa
Plants
Amoebae
Fungi
Nematodes
Insects
Fish
Birds
Mouse/rat
Chimp
Human
BACTERIA
ARCHAEA
EUKARYOTES
100
80
60
40
20
0
similarity scale

Unsupervised Learning: Clustering

- Partition unlabeled examples into disjoint clusters such that:
  - Examples in the same cluster are very similar.
  - Examples in different clusters are very different.



Unsupervised Learning: Clustering

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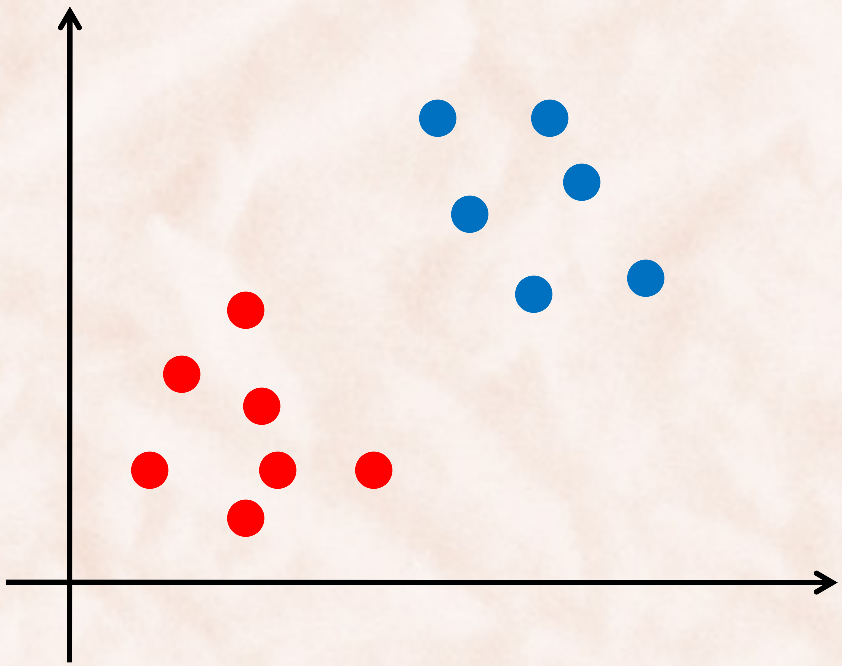
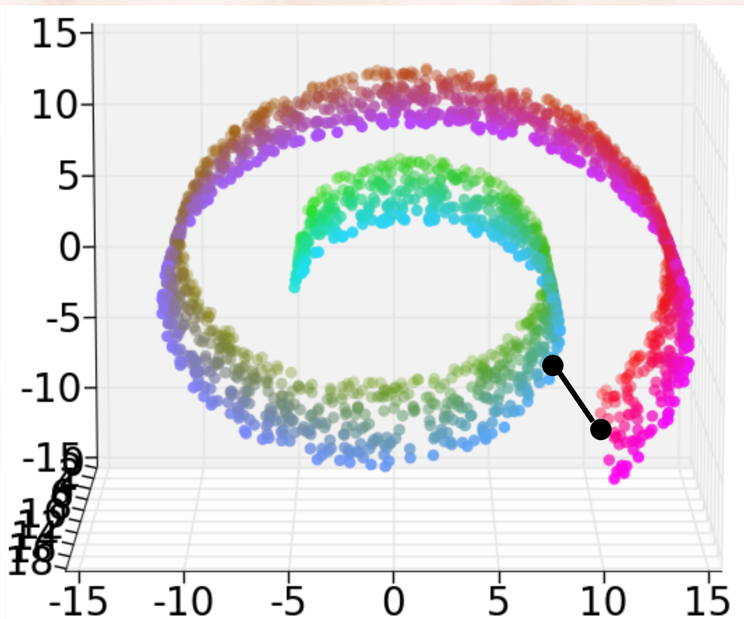
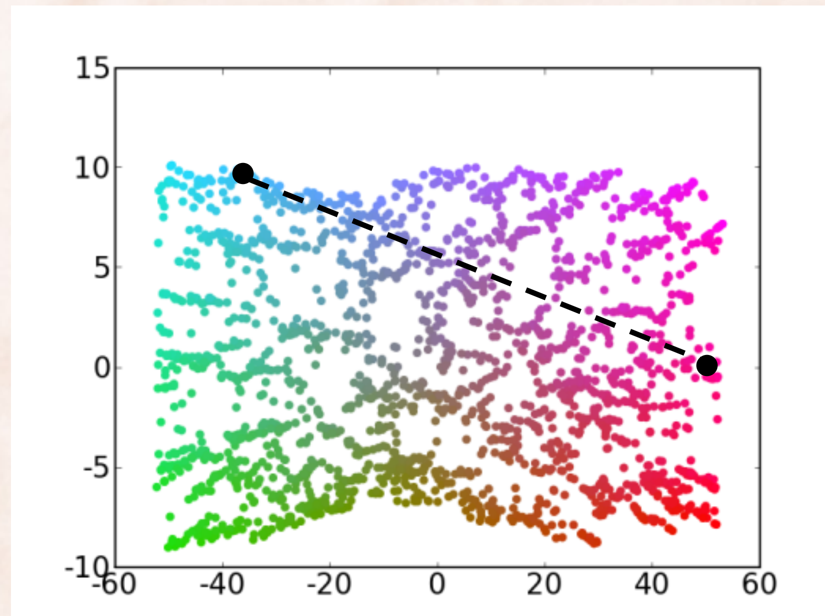


- Need to provide:
  - number of clusters ($k = 2$)
  - similarity measure (Euclidean)

Unsupervised Learning: Dimensionality Reduction

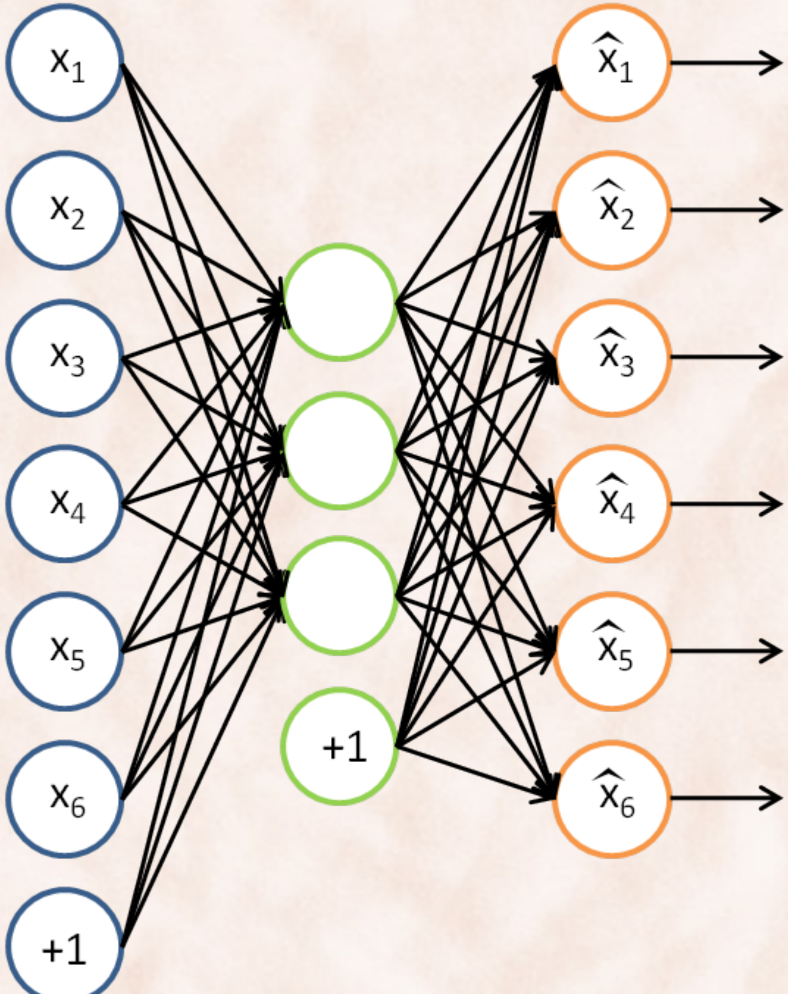
- Manifold Learning:
  - Data lies on a low-dimensional manifold embedded in a high-dimensional space.
  - Useful for *feature extraction* and *visualization*.





Unsupervised Feature Learning: Auto-encoders

[25, 63, 125, 32, 84, 257, ..., 13,
27, 39, 8, 213, 107, 54, 73, ..., 91
67, 59, 72, 33, 112, 54, 35, ..., 9
18, 37, 18, 142, 162, 54, 53, ..., 28
93, 44, 69, 85, 68, 54, 87, ..., 11,
117, 59, 117, 210, 177, 54, 72, ...]



[25, 63, 125, 32, 84, 257, ..., 13,
27, 39, 8, 213, 107, 54, 73, ..., 91
67, 59, 72, 33, 112, 54, 35, ..., 9
18, 37, 18, 142, 162, 54, 53, ..., 28
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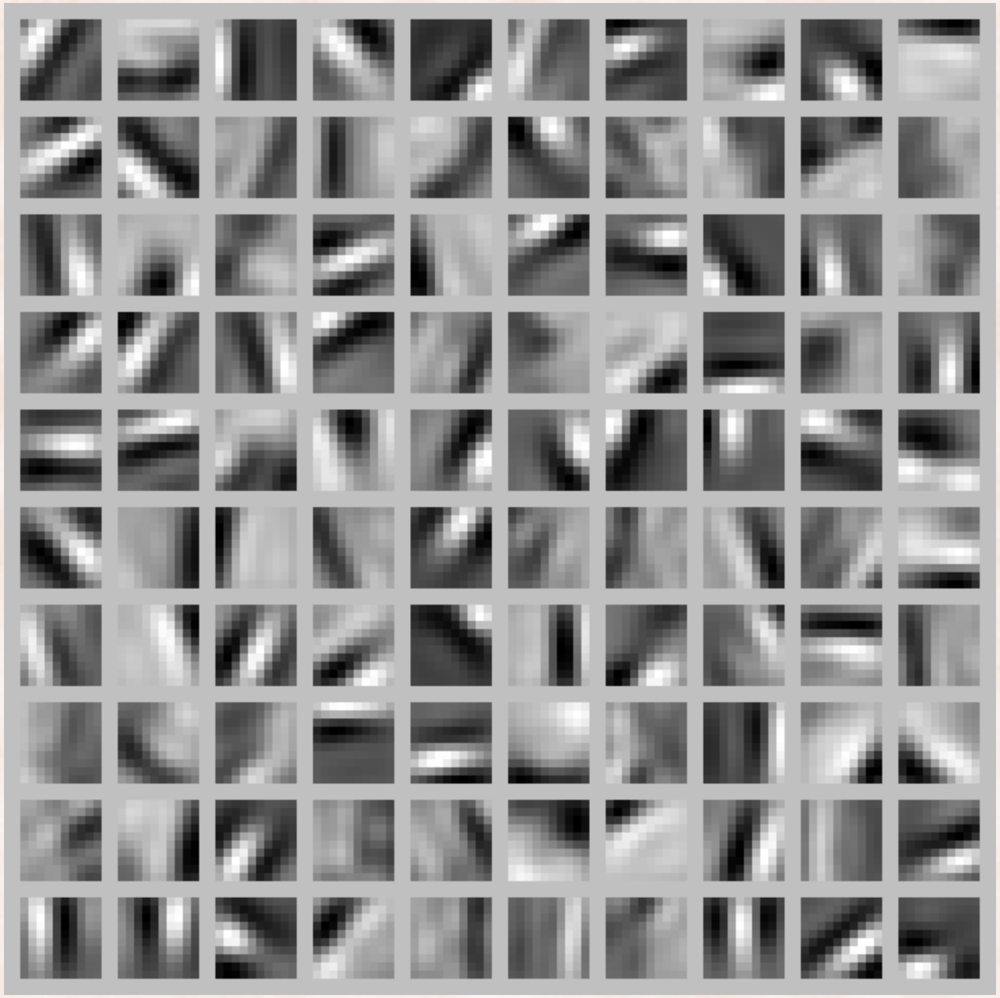
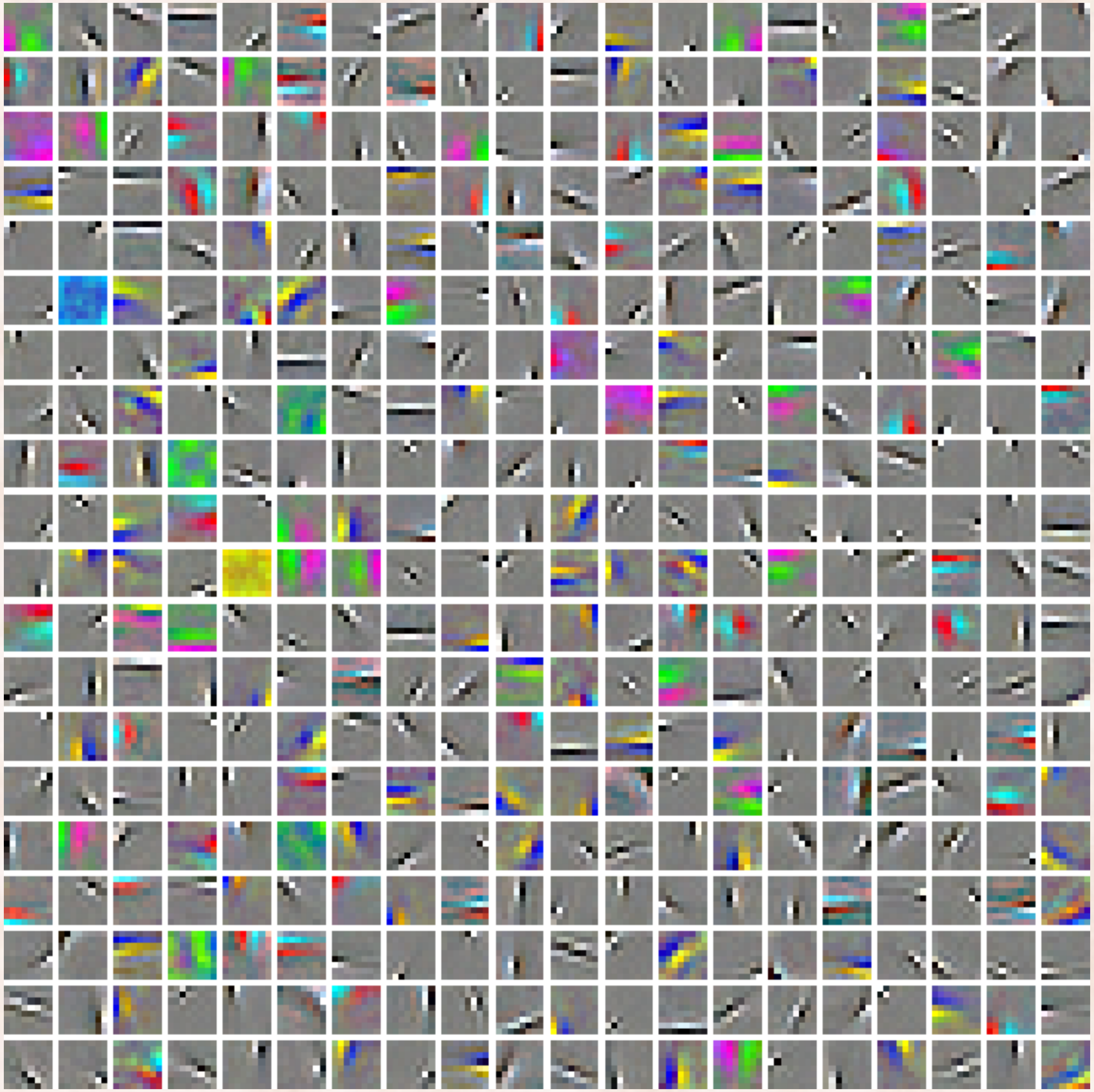
117, 59, 117, 210, 177, 54, 72, ...]

Input Features Output

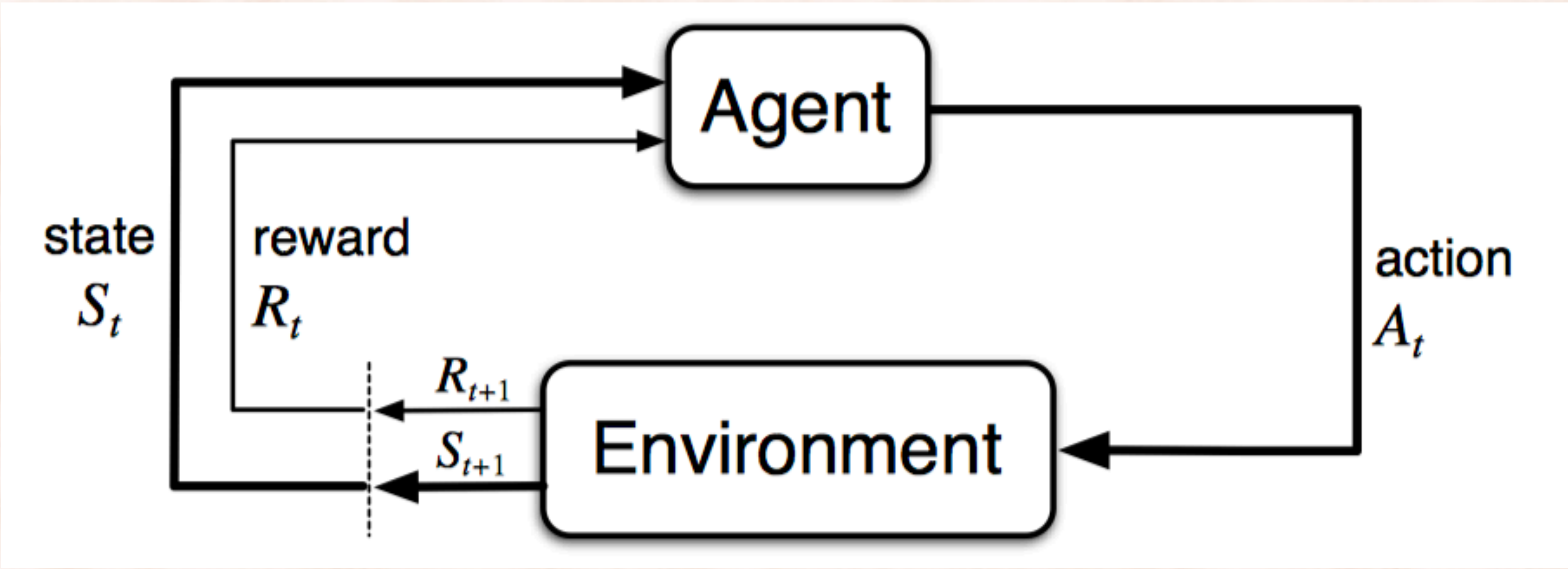
Learned Features (Representations)

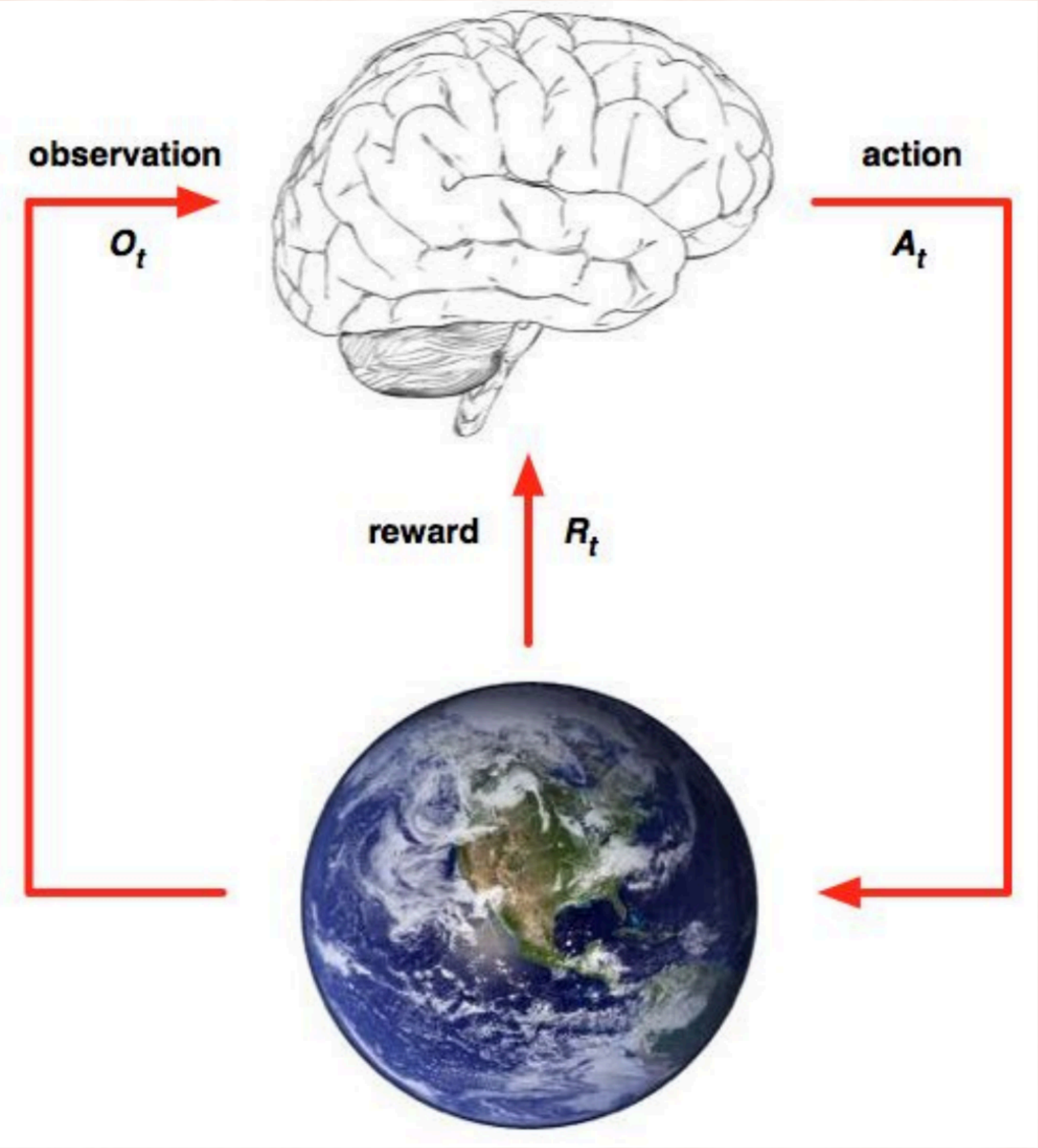


Learned Features (Representations)



Reinforcement Learning




observation
O_t
action
A_t
reward
R_t

Reinforcement Learning: TD-Gammon

[Tesauro, CACM'95]

- Learn to play Backgammon:
  - Immediate reward:
    - +100 if win
    - –100 if lose
    - 0 for all other states
  - *Temporal Difference Learning* with a *Multilayer Perceptron*.
  - Trained by playing 1.5 million games against itself.
  - Played competitively against top-ranked players in international tournaments.

Reinforcement Learning

- Interaction between agent and environment modeled as a sequence of *actions* & *states*:
  - Learn *policy* for mapping states to actions in order to maximize a *reward*.
  - Reward may be given only at the end state => *delayed reward*.
  - States may be only *partially observable*.
  - Trade-off between *exploration* and *exploitation*.
- Examples:
  - Backgammon [Tesauro, CACM'95], helicopter flight [Abbeel, NIPS'07].
  - 49 Atari games, using deep RL [Mnih et al., Nature'15].
  - AlphaGo [Silver et al., 2016], AlphaZero [Silver et al., 2017], MuZero [DeepMind, 2019]

Relevant Disciplines

- Mathematics:
  - Probability & Statistics
  - Information Theory
  - Linear Algebra
  - Optimization
- Algorithms:
  - Computational Complexity
  - Dynamic Programming
- Artificial Intelligence
  - Search
- (Computational) Neuroscience