Machine Learning ITCS 4156

## **Support Vector Machines**

Razvan C. Bunescu

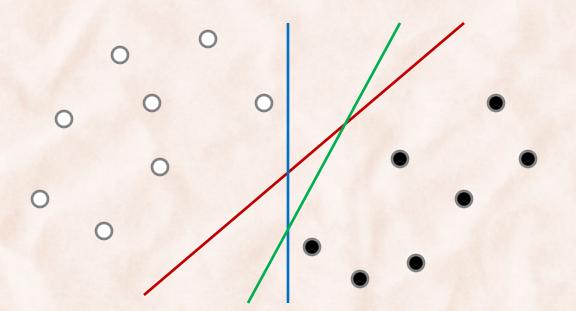
Department of Computer Science @ CCI

rbunescu@uncc.edu

### Max-Margin Classifiers: Separable Case

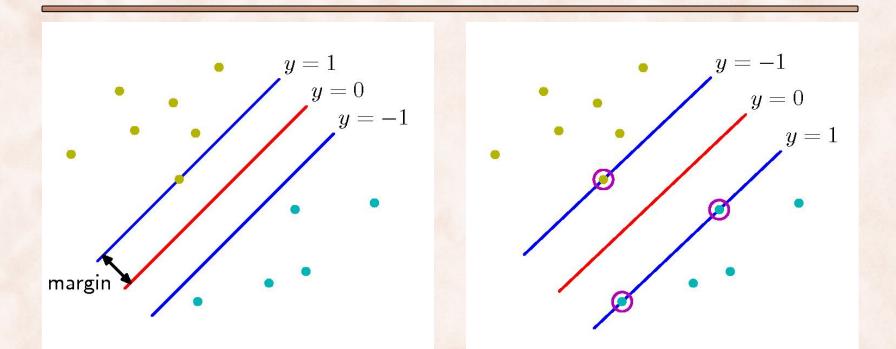
- Linear model for binary classification:  $y(\mathbf{x}) = \mathbf{w}^T \varphi(\mathbf{x}) + b$
- Training examples:  $(\mathbf{x}_{1}, t_{1}), (\mathbf{x}_{2}, t_{2}), ... (\mathbf{x}_{N}, t_{N}), \text{ where } t_{n} \in \{+1, -1\}$
- Assume training data is linearly separable:  $t_n y(x_n) > 0$ , for all  $1 \le n \le N$
- $\Rightarrow$  perceptron solution depends on:
  - initial values of w and b.
  - order of processing of data points.

## Maximum Margin Classifiers



- Which hyperplane has the smallest generalization error?
  - The one that maximizes the margin [Computational Learning Theory]
    - margin = the distance between the decision boundary and the closest sample.

## Maximum Margin Classifiers



• The distance between a point  $\mathbf{x}_n$  and a hyperplane  $y(\mathbf{x})=0$  is:

$$\frac{|y(\mathbf{x}_n)|}{\|\mathbf{w}\|} = \frac{t_n y(\mathbf{x}_n)}{\|\mathbf{w}\|} = \frac{t_n (\mathbf{w}^T \varphi(\mathbf{x}_n) + b)}{\|\mathbf{w}\|}$$

#### Maximum Margin Classifiers

• Margin = the distance between hyperplane  $y(\mathbf{x})=0$  and closest sample:

$$\min_{n} \left[ \frac{t_n(\mathbf{w}^T \varphi(\mathbf{x}_n) + b)}{\|\mathbf{w}\|} \right]$$

• Find parameters w and b that maximize the margin:

$$\arg\max_{\mathbf{w},b} \left\{ \frac{1}{\|\mathbf{w}\|} \min_{n} \left[ t_n(\mathbf{w}^T \varphi(\mathbf{x}_n) + b) \right] \right\}$$

- Rescaling w and b does not change distances to the hyperplane:
  - $\Rightarrow$  for the closest point(s), set  $t_n(\mathbf{w}^T \varphi(\mathbf{x}_n) + b) = 1$
  - $\Rightarrow t_n(\mathbf{w}^T \varphi(\mathbf{x}_n) + b) \ge 1, \quad \forall n \in \{1, \dots, N\}$

• Constrained optimization problem:

minimize:  $J(\mathbf{w}, b) = \frac{1}{2} \|\mathbf{w}\|^2$ subject to:  $t_n(\mathbf{w}^T \varphi(\mathbf{x}_n) + b) \ge 1, \quad \forall n \in \{1, \dots, N\}$ 

- Solved using the technique of Lagrange Multipliers.
  - [derivation not shown in this class, but see end of slides if interested].

• Equivalent dual representation:

maximize:  

$$L_{D}(\boldsymbol{\alpha}) = \sum_{n=1}^{N} \alpha_{n} - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} \alpha_{n} \alpha_{m} t_{n} t_{m} k(\mathbf{x}_{n}, \mathbf{x}_{m})$$
subject to:  

$$\alpha_{n} \ge 0, \quad n = 1, \dots, N$$

$$\sum_{n=1}^{N} \alpha_{n} t_{n} = 0$$

-  $k(\mathbf{x}_n, \mathbf{x}_m) = \varphi(\mathbf{x}_n)^T \varphi(\mathbf{x}_n)$  is the *kernel* function. - where  $\mathbf{w} = \sum_{n=1}^N \alpha_n t_n \varphi(x_n)$  and  $\sum_{n=1}^N \alpha_n t_n = 0$ 

Exactly like in the Kernel Perceptron!

## **KKT** conditions

- 1. primal constraints:  $t_n y(x_n) 1 \ge 0$
- 1. dual constraints:  $\alpha_n \ge 0$
- 2. complementary slackness:  $\alpha_n \{ t_n y(x_n) 1 \} = 0$
- $\Rightarrow \text{ for any data point, either } \alpha_n = 0 \text{ or } t_n y(x_n) = 1$  $S = \{n \mid t_n y(x_n) = 1\} \text{ is the set of support vectors}$

#### Max-Margin Solution

• After solving the dual problem  $\Rightarrow$  know  $\alpha_n$ , for n = 1...N

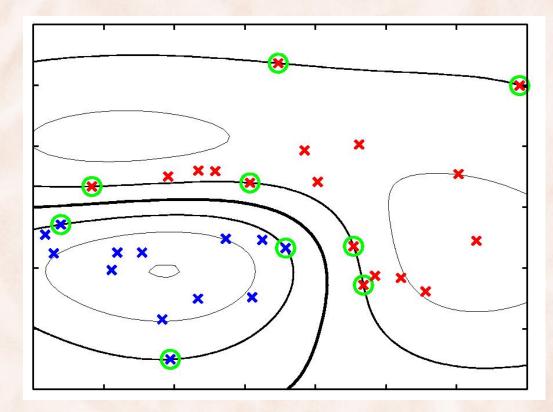
$$\mathbf{w} = \sum_{n=1}^{N} \alpha_n t_n \varphi(x_n) = \sum_{m \in S} \alpha_m t_m \varphi(x_m)$$
$$b = \frac{1}{|S|} \sum_{n \in S} \left( t_n - \sum_{m \in S} \alpha_m t_m k(\mathbf{x}_n, \mathbf{x}_m) \right)$$

• Linear discriminant function becomes:

$$y(x) = \sum_{m \in S} \alpha_m t_m k(x, x_m) + b$$

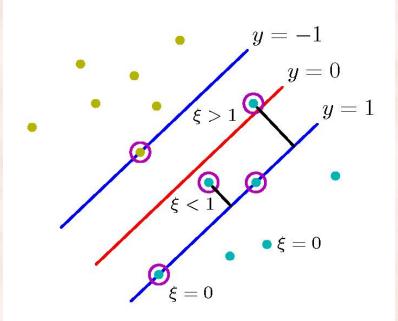
⇒ In both training and testing, examples are used only through the *kernel function*!

## An SVM with Gaussian kernel



# Max-Margin Classifiers: Non-Separable Case

- Allow data points to be on the wrong side of the margin boundary.
  - Penalty that increases with the distance from the boundary.



• Optimization problem:

minimize:  

$$J(\mathbf{w}, b) = \frac{1}{2} \|\mathbf{w}\|^{2} + C \sum_{n=1}^{N} \xi_{n}$$
subject to:  

$$t_{n}(\mathbf{w}^{T} \varphi(\mathbf{x}_{n}) + b) \ge 1 - \xi_{n}, \quad \forall n \in \{1, \dots, N\}$$

$$\xi_{n} \ge 0$$

• Solve it using the technique of Lagrange Multipliers.

• Dual representation:

maximize:  

$$L_{D}(\boldsymbol{\alpha}) = \sum_{n=1}^{N} \alpha_{n} - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} \alpha_{n} \alpha_{m} t_{n} t_{m} k(\mathbf{x}_{n}, \mathbf{x}_{m})$$
subject to:  

$$0 \le \alpha_{n} \le C, \quad n = 1, \dots, N$$

$$\sum_{n=1}^{N} \alpha_{n} t_{n} = 0$$

•  $\mathbf{k}(\mathbf{x}_n, \mathbf{x}_m) = \varphi(\mathbf{x}_n)^T \varphi(\mathbf{x}_n)$  is the *kernel* function.

## (Some of the) KKT conditions

- 1. primal constraints:  $t_n y(x_n) 1 + \xi_n \ge 0$
- 1. dual constraints:  $0 \le \alpha_n \le C$
- 2. complementary slackness:  $\alpha_n \{ t_n y(x_n) 1 + \xi_n \} = 0$
- $\Rightarrow$  for any data point, either  $\alpha_n = 0$  or  $t_n y(x_n) = 1 \xi_n$

 $S = \{n \mid t_n y(x_n) = 1 - \xi_n\}$  is the set of support vectors

 $M = \{n \mid 0 < \alpha_n < C\}$  is the set of SVs that lie on the margin.

#### Max-Margin Solution

• After solving the dual problem  $\Rightarrow$  know  $\alpha_n$ , for n = 1...N

$$\mathbf{w} = \sum_{n=1}^{N} \alpha_n t_n \varphi(\mathbf{x}_n) = \sum_{m \in S} \alpha_m t_m \varphi(\mathbf{x}_m)$$
$$b = \frac{1}{|M|} \sum_{n \in M} \left( t_n - \sum_{m \in S} \alpha_m t_m k(\mathbf{x}_n, \mathbf{x}_m) \right)$$

• Linear discriminant function becomes:

$$y(x) = \sum_{m \in S} \alpha_m t_m k(x, x_m) + b$$

⇒ In both training and testing, examples are used only through the *kernel function*!

## Support Vector Machines

• Optimization problem:

upper bound on the **misclassification** error on the training data.

minimize:  

$$J(\mathbf{w}, b) = \frac{1}{2} \|\mathbf{w}\|^{2} + C \sum_{n=1}^{N} \xi_{n}$$
subject to:  

$$t_{n}(\mathbf{w}^{T} \varphi(\mathbf{x}_{n}) + b) \ge 1 - \xi_{n}, \quad \forall n \in \{1, \dots, N\}$$

$$\xi_{n} \ge 0$$

#### - Implemented in *sklearn*:

- <u>https://scikit-learn.org/stable/modules/svm.html</u>
- https://scikit-learn.org/stable/modules/generated/sklearn.svm.SVC.html