ITCS 5356 Intro Machine Learning

<u>Python</u> Stack Linear Algebra and Optimization in <u>NumPy</u> Computation Graphs in <u>PyTorch</u>

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Python Programming Stack for Deep Learning

- <u>Python</u> = object-oriented, interpreted, scripting language.
 imperative programming, with functional programming features.
- <u>NumPy</u> = package for powerful N-dimensional arrays:
 - sophisticated (broadcasting) functions.
 - useful linear algebra, Fourier transform, and random number capabilities.
- <u>SciPy</u> = package for numerical integration and optimization.
- <u>Matplotlib</u> = comprehensive 2D and 3D plotting library.

Python Programming Stack for Deep Learning

- <u>PyTorch</u> = a wrapper of NumPy that enables the use of GPUs and automatic differentiation:
 - Tensors similar to NumPy's ndarray, but can also be used on GPU.
- <u>Jupyter Notebook</u> = a web app for creating documents that contain live code, equations, visualizations and markdown text.
- <u>Anaconda</u> = an open-source distribution of Python and Python packages:
 - Package versions are managed through Conda.
 - Install all packages above using Anaconda / Conda install.

Anaconda Install

- Anaconda: Installation instructions for various platforms can be found at: <u>https://docs.anaconda.com/anaconda/install/</u>
 - For Mac and Linux users, the system PATH must be updated after installation so that 'conda' can be used from the command line.
 - Mac OS X:
 - For bash users: export PATH=~/anaconda3/bin:\$PATH
 - For csh/tcsh users: setenv PATH ~/anaconda3/bin:\$PATH
 - For Linux:
 - For bash users: export PATH=~/anaconda3/bin:\$PATH
 - For csh/tcsh users: setenv PATH ~/anaconda3/bin:\$PATH
 - It is recommend the above statement be put in the ~/.bashrc or ~/.cshrc file, so that it is executed every time a new terminal window is open.
 - To check that conda was installed, running "conda list" in the terminal should list all packages that come with Anaconda.

Installing Packages with Conda / Anaconda

- A number of tools and libraries that we will use can be configured from Anaconda:
 - Python 3, NumPy, SciPy, Matplotlib, Jupyter Notebook, Ipython, Pandas, Scikit-learn.
 - PyTorch can be installed from Anaconda, with 'conda' from the command line:
 - The actual command line depends on the platform as follows:
 - Using the GUI on <u>pytorch.org</u>, choose the appropriate OS, conda, Python 3.6, CUDA or CPU version.

import numpy as np

- > np.array()
 - indexing, slices.
- ndarray.shape, .size, .ndim, .dtype, .T
- np.zeros(), np.ones(), np.arange(). np.eye()
 - *dtype* parameter.
 - tuple (shape) parameter.
- > np.reshape(), np.ravel()
- np.amax(), np.maximum(), np.sum(), np.mean,() np.std()
 - axis parameter, also np.ndarray
- np.stack(), np.[hv]stack(), np.column_stack(), np.split()
- np.exp(), np.log(),
- <u>https://docs.scipy.org/doc/numpy/user/quickstart.html</u>

NumPy: Broadcasting

- Broadcasting describes how numpy treats arrays with different shapes during arithmetic operations.
- The smaller array is "broadcast" across the larger array so that they have compatible shapes, subject to broadcasting rules:
 - NumPy compares their shapes element-wise.
 - It starts with the trailing dimensions, and works its way forward.
 - Two dimensions are compatible when:
 - they are equal, or one of them is 1.
- https://docs.scipy.org/doc/numpy/user/basics.broadcasting.html

Other Numpy Functions

- > np.dot(), np.vdot()
 - also np.ndarray.
- > np.outer(), np.inner()

import numpy.random as random:

• randn(), randint(), uniform()

import numpy.linalg as la:

- la.norm(), la.det(), la.matrix_rank(), np.trace()
- la.eig(), la.svd()
- la.qr(), la.cholesky()

https://docs.scipy.org/doc/numpy/reference/routines.linalg.html

Implementation: Vectorization of LR

• Version 3: Compute gradient, vectorized.

$$\nabla L(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\hat{y}_n - y_n) \mathbf{x}_n$$

grad = X.T @ sigmoid(X.dot(w) - y) / N

def sigmoid(x):
return 1 / (1 + np.exp(-x))

import scipy

- scipy.optimize:
 - scipy.optimize.fmin_l_bfgs_b()
 - theta, _, _ = fmin_l_bfgs_b(softmaxCost, theta,
 - args = (numClasses, inputSize, decay, images, labels),

maxiter = 100, disp = 1)

- scipy.optimize.fmin_cg()
- scipy.minimize

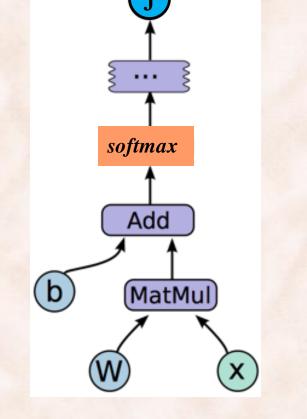
https://docs.scipy.org/doc/scipy-0.10.1/reference/tutorial/optimize.html

Towards PyTorch: Graphs of Computations

- A function *J* can be expressed by the **composition** of computational elements from a given set:
 - Mathematical operators:
 - multiplication and additions
 - Elementwise application of mathematical functions:
 - $\max(0, x), \exp(x), \dots$
- The function is defined by a graph of computations:
 - A directed acyclic graph, with one node per computational element.
 - Depth of architecture = depth of the graph = longest path from an input node to an output node.

Logistic Regression as a Computation Graph

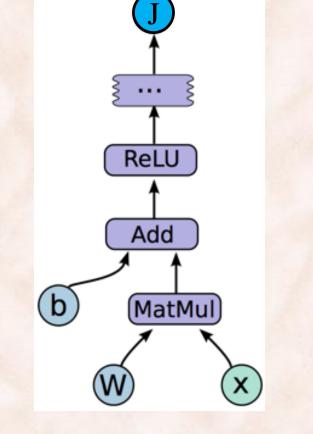
Inference = Forward Propagation



Learning = Backward Propagation

Neural Network as a Computation Graph

Inference = Forward Propagation



Learning = Backward Propagation

What is PyTorch

- A wrapper of **NumPy** that enables the use of GPUs.
 - Tensors similar to NumPy's ndarray, but can also be used on GPU.
- A flexible deep learning platform:
 - Deep Neural Networks built on a tape-based autograd system:
 - Building neural networks using and replaying a tape recorder.
 - **Reverse-mode auto-differentiation** allows changing the network at runtime:
 - The computation graph is created on the fly.
 - Backpropagation is done on the dynamically built graph.

Automatic Differentiation

https://pytorch.org/tutorials/beginner/blitz/autograd_tutorial.html

- Deep learning packages offer automatic differentiation.
- PyTorch has the *autograd* package:
 - torch. Tensor the main class; torch. Function class also important.
 - When *requires_grad* = *True*, it tracks all operations on this tensor (e.g. the parameters).
 - An acyclic graph is built **dynamically** that encodes the history of computations, i.e. compositions of functions.
 - TensorFlow compiles static computation graphs.
 - To compute the gradient, call *backward()* in a scalar valued Tensor (e.g. the *loss*).

Tensors

- PyTorch tensors support the same operations as NumPy.
 - Arithmetic.
 - Slicing and Indexing.
 - Broadcasting.
 - Reshaping.
 - Sum, Max, Argmax, ...
- PyTorch tensors can be converted to NumPy tensors.
- NumPy tensors can be converted to PyTorch tensors.

http://pytorch.org/tutorials/beginner/blitz/tensor_tutorial.html

Autograd

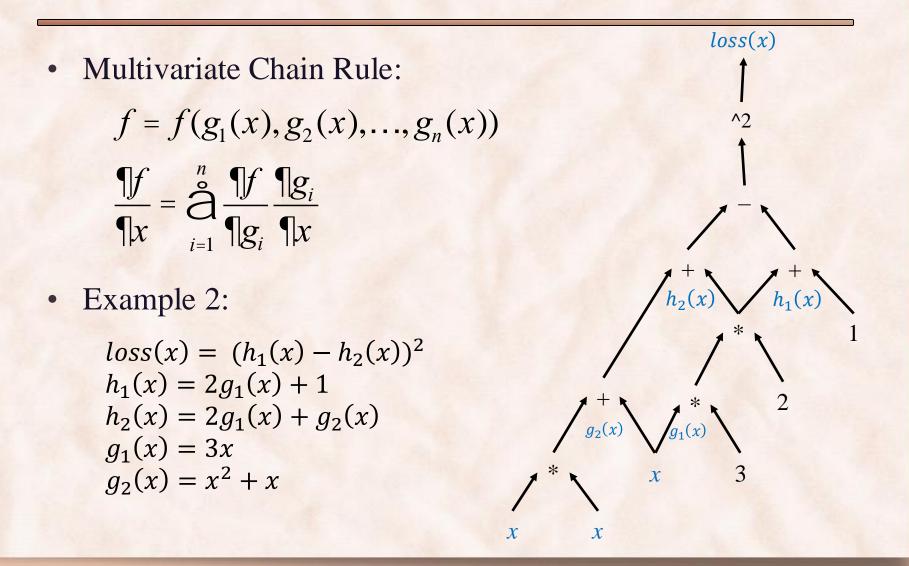
- The **autograd** package provides automatic differentiation for all operations on Tensors.
 - It is a *define-by-run* framework, which means that the gradient is defined by how your code is run:
 - Every single backprop iteration can be different.
- autograd.Tensor is the central class of the package.
 - Once you finish your computation you can call .backward() and have all the gradients computed automatically.

http://pytorch.org/tutorials/beginner/blitz/autograd_tutorial.html

Tensor and Function

- A **Tensor** v has three important attributes:
 - v.data holds the raw tensor value.
 - v.grad is another Tensor which accumulates the gradient w.r.t. v:
 - The gradient of what?
 - The gradient of any variable *u* that uses *v* on which we call u.backward().
 - <u>http://pytorch.org/docs/master/autograd.html</u>
 - v.grad_fn stores the Function that has created the Tensor *v*:
 - <u>http://pytorch.org/docs/master/autograd.html</u>

Multivariate Chain Rule for Differentiation



 $las(x) = (h_1(x) - h_2(x))^{-1}$ $\frac{\partial l}{\partial x} = \frac{\partial l}{\partial h_1} \cdot \frac{\partial h_1}{x} + \frac{\partial l}{\partial h_2} \cdot \frac{\partial h_2}{\partial x}$ $h_{1}(x) = 2g_{1}(x) + 1 \longrightarrow 7$ $h_{z}(x) = 2g_{1}(x) + g_{z}(x) - 8$ $g_{1}(x) = 3x - 3$ $= 2 \left(h_{1} - h_{2}\right) \cdot \frac{\partial h_{1}}{\partial x} + 2 \left(h_{2} - h_{1}\right) \frac{\partial h_{2}}{\partial x}$ $= 2\left(h_{1}-h_{2}\right)\left(\frac{\partial h_{1}}{\partial x}-\frac{\partial h_{2}}{\partial x}\right)$ $g_2(x) = x^2 t \overline{t} \longrightarrow 2$ $=2\left(h_{1}-h_{2}\right)\left(\begin{array}{c}\partial h_{1}\\\partial g_{1}\\\partial \end{array}\right)\left(\begin{array}{c}\partial h_{1}\\\partial g_{1}\\\partial \end{array}\right)\left(\begin{array}{c}\partial g_{1}\\\partial \end{array}\right)\left(\begin{array}{c}\partial h_{2}\\\partial g_{1}\\\partial g_{1}\\\partial g_{1}\\\partial \end{array}\right)\left(\begin{array}{c}\partial h_{2}\\\partial g_{1}\\\partial g_{1}\\\partial$ $= 2 \left(h_{1} - h_{2} \right) \left(2 \cdot 3 - 2 \cdot 3 - 1 \cdot (2\chi + 1) \right) = 2 \left(h_{1} - h_{2} \right) \left(-2\chi - 1 \right)$ $= 2 \left(h_{2} - h_{1} \right) \left(2\chi + 1 \right)$ $x = \underline{T} = -\frac{\partial \ell}{\partial x} = 2\left(8 - \overline{7}\right)\left(3\right) = 6$

 $\frac{f(x)}{\partial x} = \frac{\partial f}{\partial x} = 4x - 3$ $-f(x) = 2x^2 - 3x + 4$ F 2x2-3x+4 g E h H x-32 backward () - [(1) = 1f(1) = 3privaro X² (m) A A ferentiation chain rule of a $\partial f = d$ Dadd Oh O add (g, h) J = add 0 $1 \cdot 6 = \frac{\partial q}{\partial x} = 4x - 3$ + q = adq42-3 @ mul Omul $= 2 \cdot 2\chi + g_3 \cdot 0 = 4\chi$ Og; Oz OX

PyTorch

- Install using Anaconda:
 - conda install pytorch torchvision -c pytorch
 - <u>http://pytorch.org</u>
- Install from sources:
 - <u>https://github.com/pytorch/pytorch#from-source</u>
- Tutorials:
 - <u>http://pytorch.org/tutorials/</u>
 - <u>http://pytorch.org/tutorials/beginner/pytorch_with_examples.html</u>