Machine Learning ITCS 6156/8156

Principal Component Analysis

Whitening

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Principal Component Analysis (PCA)

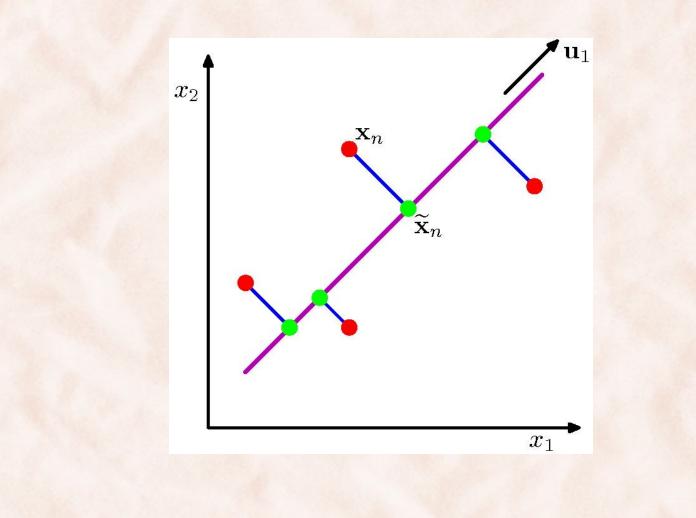
• A technique widely used for:

- dimensionality reduction.
- data compression.
- feature extraction.
- data visualization.

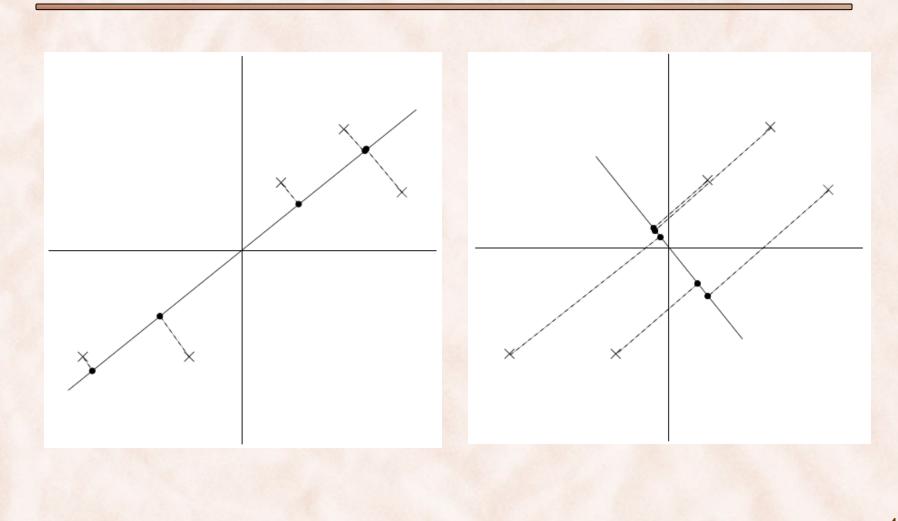
maximum variance

- Two equivalent definitions of PCA:
 - 1) Project the data onto a lower dimensional space such that the variance of the projected data is *maximized*.
 - Project the data onto a lower dimensional space such that the mean squared distance between data points and their projections (average projection cost) is *minimized*.

Principal Component Analysis (PCA)



Principal Component Analysis (PCA)



PCA (Maximum Variance)

- Let $X = {\mathbf{x}_n}_{1 \le n \le N}$ be a set of observations:
 - Each $\mathbf{x}_n \in \mathbf{R}^D$ (*D* is the dimensionality of \mathbf{x}_n).
- Project X onto an *M* dimensional space (*M* < *D*) such that the *variance* of the projected X is *maximized*.
 - Minimum error formulation leads to the same solution [PRML 12.1.2].
 - shows how PCA can be used for compression.
- Work out solution for M = 1, then generalize to any M < D.

• The lower dimensional space is defined by a vector $\mathbf{u}_1 \in \mathbb{R}^D$.

- Only direction is important \Rightarrow choose $||\mathbf{u}_1||=1$.

- Each \mathbf{x}_n is projected onto a scalar $\mathbf{u}_1^T \mathbf{x}_n$
- The (sample) mean of the data is:

$$\overline{\mathbf{x}} = \frac{1}{N} \sum_{n=1}^{N} \mathbf{x}_n$$

• The (sample) mean of the projected data is $\mathbf{u}_1^T \overline{\mathbf{x}}$

• The (sample) variance of the projected data:

$$\frac{1}{N}\sum_{n=1}^{N} \left(\mathbf{u}_{1}^{T}\mathbf{x}_{n}-\mathbf{u}_{1}^{T}\overline{\mathbf{x}}\right)^{2} = \mathbf{u}_{1}^{T}\boldsymbol{\Sigma}\mathbf{u}_{1}$$

where Σ is the data covariance matrix:

$$\boldsymbol{\Sigma} = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{x}_n - \overline{\mathbf{x}}) (\mathbf{x}_n - \overline{\mathbf{x}})^T$$

• Optimization problem is:

minimize:

$$-\mathbf{u}_{1}^{T} \boldsymbol{\Sigma} \mathbf{u}_{1}$$

subject to:
 $\mathbf{u}_{1}^{T} \mathbf{u}_{1} = 1$

• Lagrangian function:

 $L_P(\mathbf{u}_1, \lambda_1) = -\mathbf{u}_1^T \Sigma \mathbf{u}_1 + \lambda_1(\mathbf{u}_1^T \mathbf{u}_1 - 1)$

where λ_1 is the Lagrangian multiplier for constraint $\mathbf{u}_1^T \mathbf{u}_1 = 1$

• Solve:

 $\frac{\partial L_p}{\partial \mathbf{u}_1} = 0 \Rightarrow \mathbf{\Sigma} \mathbf{u}_1 = \lambda_1 \mathbf{u}_1 \Rightarrow \begin{cases} \mathbf{u}_1 \text{ is an eigenvector of } \mathbf{\Sigma} \\ \lambda_1 \text{ is an eigenvalue of } \mathbf{\Sigma} \end{cases}$ $\Rightarrow -\mathbf{u}_1^T \mathbf{\Sigma} \mathbf{u}_1 = -\lambda_1 \mathbf{u}_1^T \mathbf{u}_1 = -\lambda_1$ $\Rightarrow \lambda_1 \text{ is the largest eigenvalue of } \mathbf{\Sigma}.$

- λ_1 is the largest eigenvalue of Σ .
- \mathbf{u}_1 is the eigenvector corresponding to λ_1 :
 - also called the *first principal component*.
- For M < D dimensions:
 - $\mathbf{u}_1 \, \mathbf{u}_2 \, \dots \, \mathbf{u}_M$ are the eigenvectors corresponding to the largest eigenvalues $\lambda_1 \, \lambda_2 \, \dots \, \lambda_M$ of $\boldsymbol{\Sigma}$.
 - proof by induction.

PCA on Normalized Data

- Preprocess data $X = \{\mathbf{x}^{(i)}\}_{1 \le i \le m}$ such that:
 - features have the same mean(0).
 - features have the same *variance* (1).

1. Let
$$\mu = \frac{1}{m} \sum_{i=1}^{m} x^{(i)}$$
.

- 2. Replace each $x^{(i)}$ with $x^{(i)} \mu$.
- 3. Let $\sigma_j^2 = \frac{1}{m} \sum_i (x_j^{(i)})^2$
- 4. Replace each $x_j^{(i)}$ with $x_j^{(i)}/\sigma_j$.

PCA on Natural Images

- **Stationarity**: the statistics in one part of the image should be the same as any other.
 - \Rightarrow no need for variance normalization.
 - ⇒ do mean normalization by subtracting from each image its mean intensity.

$$\mu^{(i)} := \frac{1}{n} \sum_{j=1}^{n} x_j^{(i)}$$
$$x_j^{(i)} := x_j^{(i)} - \mu^{(i)}$$

PCA on Normalized Data

• The covariance matrix is:

$$\boldsymbol{\Sigma} = \frac{1}{m} \boldsymbol{X} \boldsymbol{X}^{T} = \frac{1}{m} \sum_{i=1}^{m} \mathbf{x}^{(i)} \left(\mathbf{x}^{(i)} \right)^{T}$$

• The eigenvectors are:

 $\Sigma \mathbf{u}_j = \lambda_j \mathbf{u}_j$ where $\lambda_1 \ge \lambda_2 \ge ... \ge \lambda_D$ and $u_j^T u_j = 1$ • Equivalent with:

 $\Sigma U = U\Lambda$ $U = [u_1, u_2, \dots, u_D] \quad \lambda_1 \ge \lambda_2 \ge \dots \ge \lambda_D \text{ and } U^T U = I$ $\Lambda = diag(\lambda_1, \lambda_2, \dots, \lambda_D)$

PCA on Normalized Data

- U is an orthogonal (rotation) matrix, i.e. $U^T U = I$.
- The full transformation (rotation) of $x^{(i)}$ through PCA is:

$$y^{(i)} = U^T x^{(i)}$$
$$\Rightarrow x^{(i)} = U y^{(i)}$$

• The *k*-dimensional projection of $x^{(i)}$ through PCA is:

$$\hat{y}^{(i)} = U_{1,k}^T x^{(i)} = [u_1, \dots, u_k]^T x^{(i)}$$
$$\implies \hat{x}^{(i)} = U_{1,k} \hat{y}^{(i)}$$

• How many components k should be used?

How many components k should be used?

Compute *percentage of variance retained* by $Y = \{y^{(i)}\}$, for • each value of k:

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$$\hat{y}^{(i)} = [u_1, \dots, u_k]^T x^{(i)}$$

$$Var(k) = \sum_{j=1}^k Var[\hat{y}_j] = \sum_{j=1}^k Var[u_j^T x]$$

$$= \sum_{j=1}^k \frac{1}{m} \sum_{i=1}^m (u_j^T x^{(i)} - u_j^T \overline{x})^2 = \sum_{j=1}^k \frac{1}{m} \sum_{i=1}^m (u_j^T x^{(i)})^2 = \sum_{j=1}^k \lambda_j$$

$$HW: Prove it is \lambda_j$$

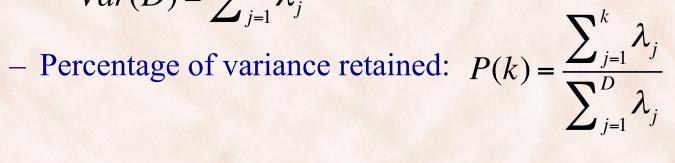
How many components k should be used?

- Compute *percentage of variance retained* by $Y = \{y^{(i)}\}$, for each value of k:
 - Variance retained:

$$Var(k) = \sum_{j=1}^{k} \lambda_j$$

- Total variance:

 $Var(D) = \sum_{j=1}^{D} \lambda_j$



How many components k should be used?

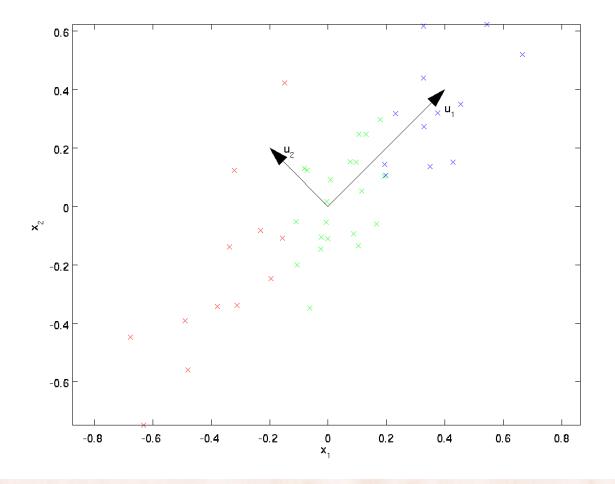
• Compute *percentage of variance retained* by Y = {y⁽ⁱ⁾}, for each value of *k*:

$$P(k) = \frac{\sum_{j=1}^{k} \lambda_j}{\sum_{j=1}^{D} \lambda_j}$$

• Choose smallest k as to retain 99% of variance:

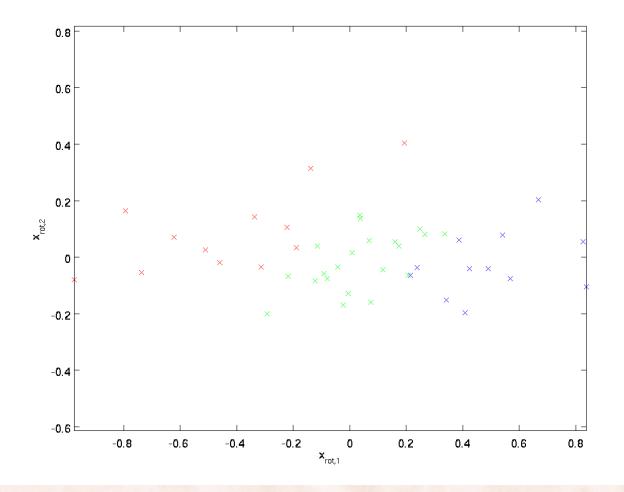
 $\hat{k} = \underset{1 \le k \le D}{\operatorname{argmin}} \left[P(k) \ge 0.99 \right]$

PCA on Normalized Data: $[x_1^{(i)}, x_2^{(i)}]^T$

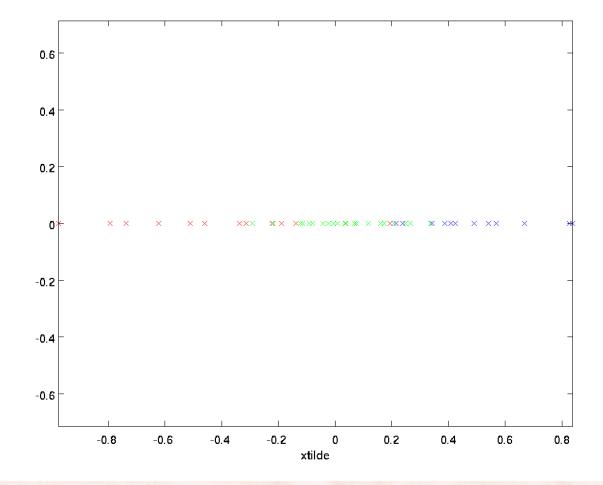


17

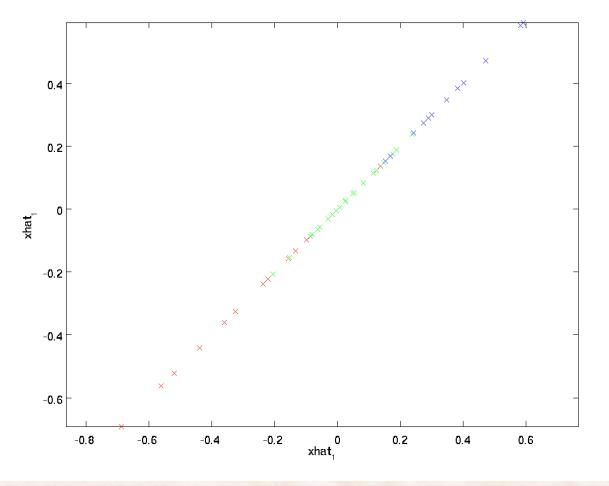
Rotation through PCA: $[u_1^T x^{(i)}, u_2^T x^{(i)}]^T$



1-Dimensional PCA Projection: $[u_1^T x^{(i)}, 0]^T$



1-Dimensional PCA Approximation: $u_1u_1^T x^{(i)}$



PCA as a Linear Auto-Encoder

- The full transformation (rotation) of $x^{(i)}$ through PCA is: $y = U^T x \Rightarrow x = Uy$
- The *k*-dimensional projection of $x^{(i)}$ through PCA is:

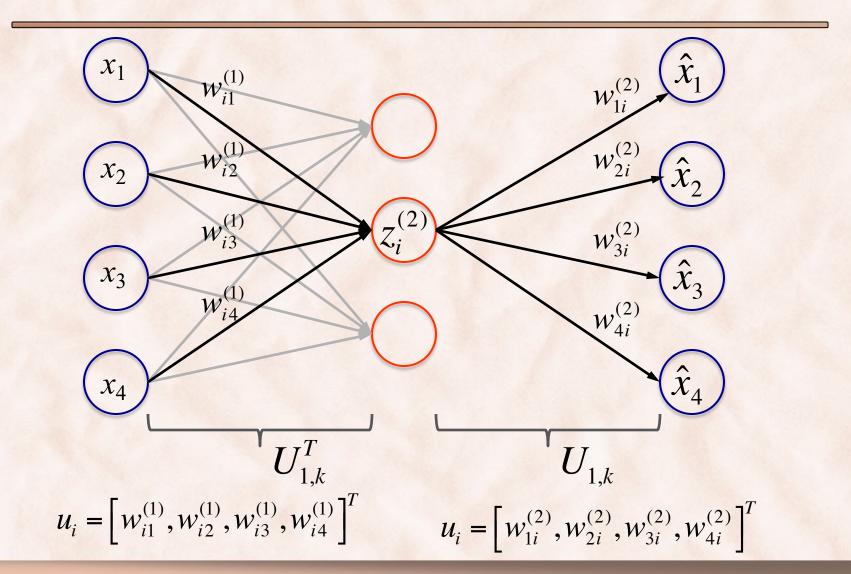
$$\hat{y} = U_{1,k}^T x = [u_1, \dots, u_k]^T x \Longrightarrow \hat{x} = U_{1,k} \hat{y} = U_{1,k} U_{1,k}^T x$$

• The minimum error formulation of PCA:

$$U_{1,k}^* = \arg\min_{U_{1,k}} \sum_{i=1}^m \left\| U_{1,k} U_{1,k}^T x^{(i)} - x^{(i)} \right\|^2$$

a linear auto-encoder with tied weights!

PCA as a Linear Auto-Encoder



22

PCA and Decorrelation

- The full transformation (rotation) of $x^{(i)}$ through PCA is: $y^{(i)} = U^T x^{(i)} \Rightarrow Y = U^T X$
- What is the covariance matrix of the rotated data Y?

$$\frac{1}{m}YY^{T} = \frac{1}{m}(U^{T}X)(U^{T}X)^{T} = \frac{1}{m}U^{T}XX^{T}U$$
$$= U^{T}\left(\frac{1}{m}XX^{T}\right)U = U^{T}\Sigma U = \Lambda$$
$$= diag(\lambda_{1}, \lambda_{2}, \dots, \lambda_{D}) \qquad => \text{ the features in } y$$
are decorrelated!

PCA Whitening (Sphering)

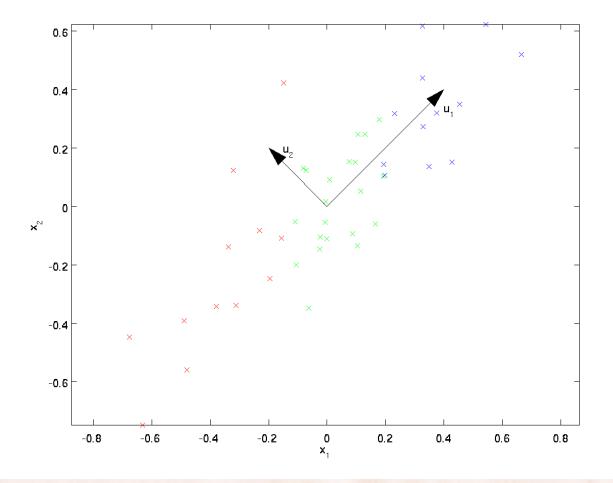
- The goal of **whitening** is to make the input *less redundant*, i.e. the learning algorithm sees a training input where:
 - 1. The features are not correlated with each other.
 - 2. The features all have the same variance.
- 1. PCA already results in uncorrelated features:

$$y^{(i)} = U^T x^{(i)} \Leftrightarrow Y = U^T X$$
 $\frac{1}{m} Y Y^T = diag(\lambda_1, \lambda_2, \dots, \lambda_D)$

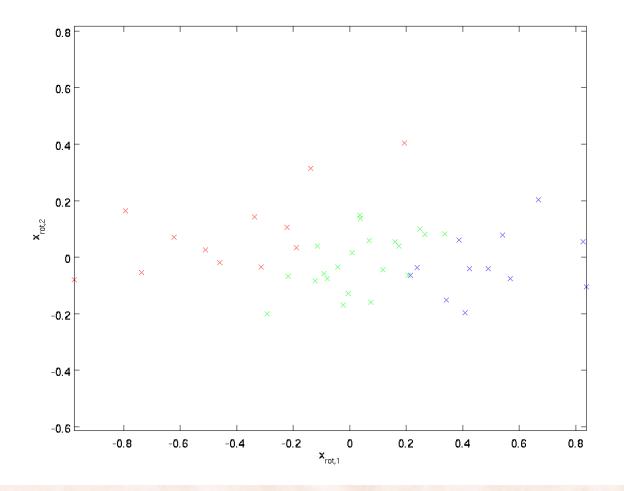
2. Transform to identity covariance (PCA Whitening) :

$$y_j^{(i)} = \frac{u_j^T x^{(i)}}{\sqrt{\lambda_j}} \Leftrightarrow y^{(i)} = \Lambda^{-\frac{1}{2}} U^T x^{(i)} \Leftrightarrow Y = \Lambda^{-\frac{1}{2}} U^T X$$

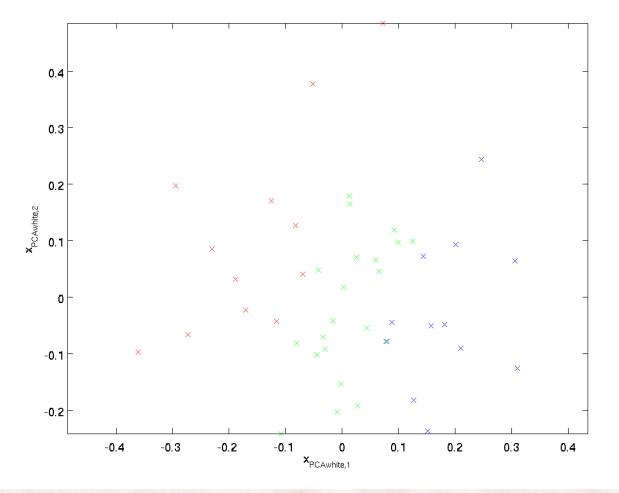
PCA on Normalized Data: $[x_1^{(i)}, x_2^{(i)}]^T$



Rotation through PCA: $[u_1^T x^{(i)}, u_2^T x^{(i)}]^T$







ZCA Whitening (Sphering)

- Observation: If Y has identity covariance and R is an orthogonal matrix, then RY has identity covariance.
 - 1. PCA Whitening:

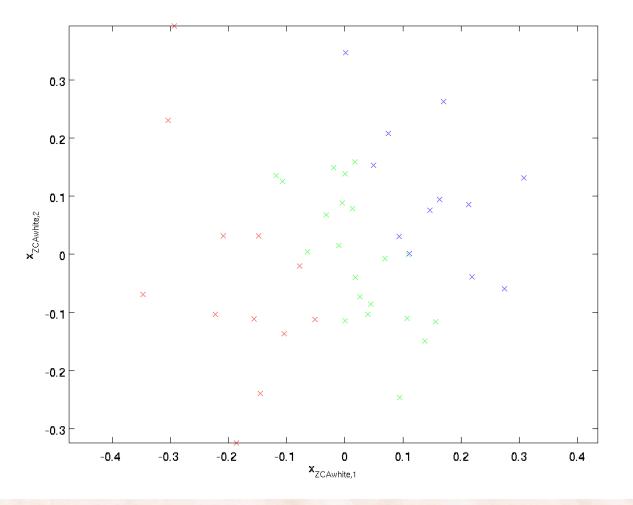
$$Y_{PCA} = \Lambda^{-1/2} U^T X$$

2. ZCA Whitening:

$$Y_{ZCA} = UY_{PCA} = U\Lambda^{-1/2}U^T X$$

Out of all rotations, U makes Y_{ZCA} closest to original X.

ZCA Whitening: $Y_{ZCA} = U\Lambda^{-1/2}U^T X$



Smoothing

- When eigenvalues λ_j are very close to 0, dividing by $\lambda_j^{-1/2}$ is numerically unstable.
- Smoothing: add a small ε to eigenvalues before scaling for PCA/ZCA whitening:

$$y_j^{(i)} = \frac{u_j^T x^{(i)}}{\sqrt{\lambda_j + \varepsilon}} \qquad \varepsilon \approx 10^{-5}$$

• ZCA whitening is a rough model of how the biological eye (the retina) processes images (through retinal neurons).