

M16C/62

Using the M16C/62 Analog to Digital Converter in Repeat Mode

1.0 Abstract

The following article outlines the steps necessary to set up, perform, and read multiple conversions on a single channel using the onboard analog to digital converter (ADC) of the M16C. The ADC is useful in measuring output voltages of sensors such as accelerometers or other analog instrumentation and converting them to digital values.

2.0 Introduction

The M16C line of devices features an onboard analog to digital converter (ADC). The ADC consists of one 10-bit successive approximation circuit with a capacitive coupled amplifier. There are eight analog input pins, selectable conversion clock speeds, sample and hold function, and several conversion modes. Figure 1 is an overview of the internal circuitry for the ADC block.

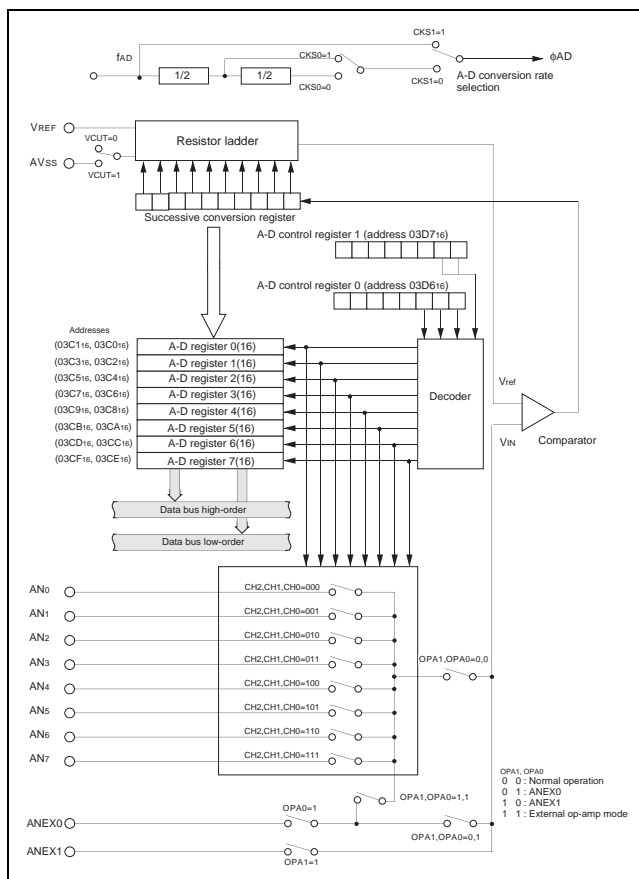


Figure 1 Internal Circuitry for ADC Block—Overview

3.0 Repeat Mode Description

In repeat mode, one pin of the ADC is selected as the input source. Once triggered, a conversion takes place on the selected pin and the result is stored in the ADC result register corresponding to the selected channel. This is repeated until the ADC conversion start flag is disabled. No interrupt is generated on the completed conversion, but rather the ADC output register can be read anytime to determine the converted value. Figure 2 and Figure 3 are overviews of the registers that will be used in this example. These registers are detailed in the included sample code. For specific details, consult the MCU specification for the device in question.

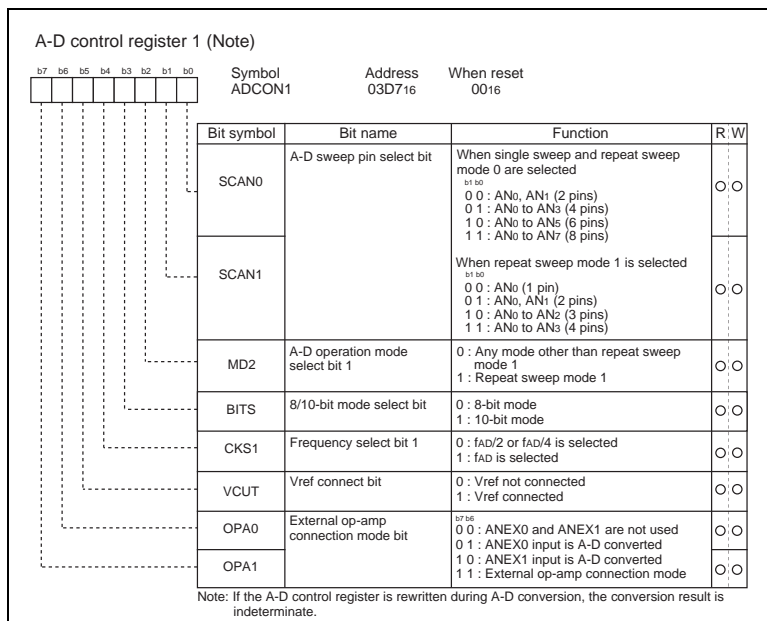
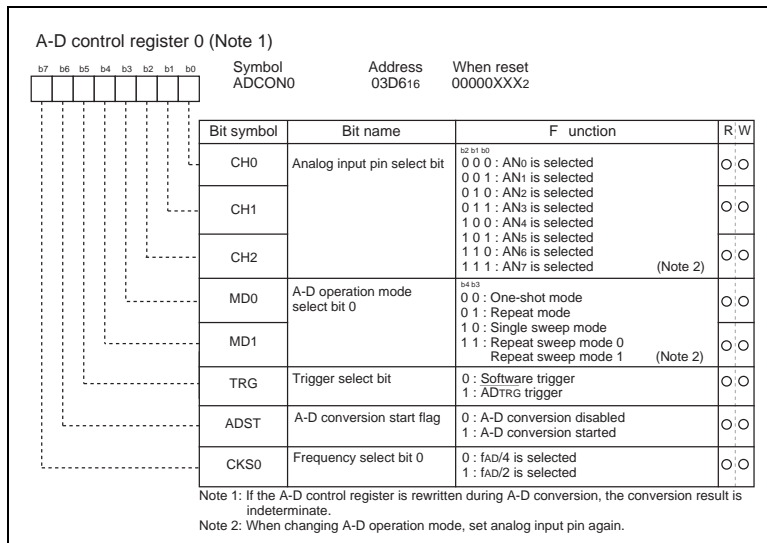


Figure 2 A-D Converter Related Registers

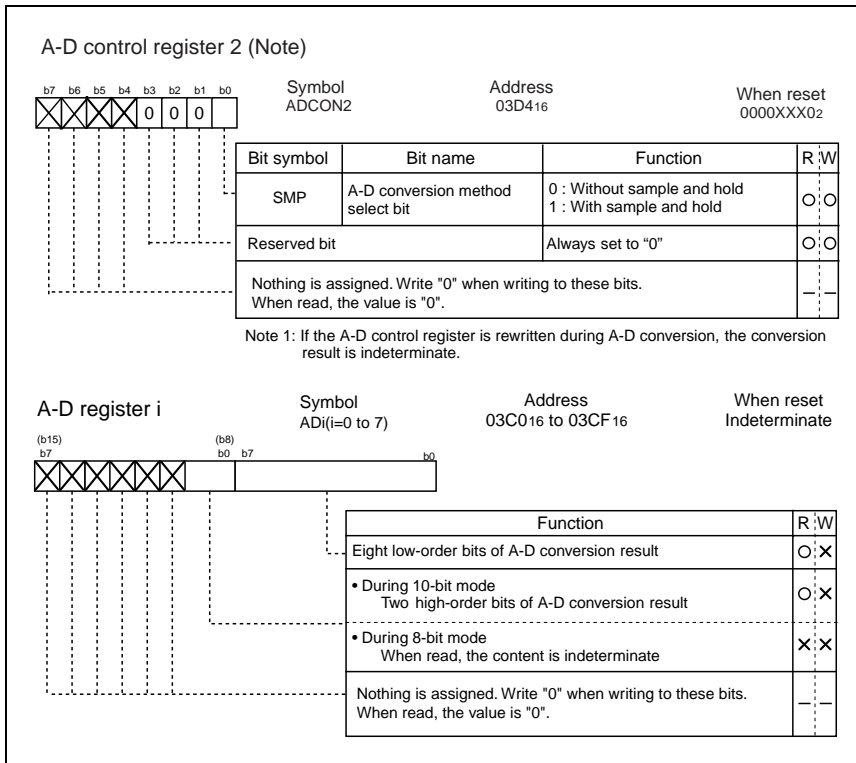


Figure 3 A-D Converter Related Register

4.0 Example Program

This example program demonstrates how to perform a conversion using the ADC in the following environment:

Environment Setup

- Repeat mode conversion
- 10-bit mode
- Analog input 0 used
- Sample and hold enabled
- Vref connected
- Conversion clock used will be $f_{AD}/2$ (if $f(Xin)$ is greater than 10 MHz, f_{AD} must be divided)
- Software conversion start

ADC Software Setup

- Set the ADCON0 register for AN0 input, $f_{AD}/2$ and repeat mode operation (0x08)
- Set the ADCON1 register for 10-bit mode, f_{AD} divided, and connect Vref (0x38)
- Set the ADCON2 register for sample and hold (0x01)
- Enable the A/D converter by setting the ADST bit to 1
- Read current A/D value in variable 'TempStore'

5.0 Reference

Renesas Technology Corporation Semiconductor Home Page

<http://www.renesas.com>

E-mail Support

support_apl@renesas.com

Data Sheets

- M16C/62 datasheets, 62aeds.pdf

User's Manual

- M16C/62 User's Manual, 62eum.pdf
- M16C/60 and M16C/20 C Language Programming Manual, 6020EC.pdf
- Application Note: Writing Interrupt Handlers in C for the M16C
- NC30 Ver. 4.0 User's Manual, NC30UE.pdf

6.0 Software Code

The sample software provided was written using the NC30 compiler. The program starts the conversion process on reset.

```
/*  
*  
*   DESCRIPTION: repeat_mode.c  
*  
*   AUTHOR: Renesas Technology Corporation (June 2003)  
*  
*  
*   PURPOSE: Outlines how to use the M16C/62 ADC in repeat  
*             mode. On reset, program repeatedly stores the result  
*             of the conversion in a variable that can be examined  
*             using KD30 and the MSV1632-62 Starter Kit or similar tool.  
*  
*  
*/  
*****/  
  
#include "sfr62.h"  
  
unsigned int TempStore = 0x0000;           // Location where ADC result is stored  
  
/*  
** main  
*  
*   PARAMETERS: None  
*  
*/
```


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