Smart Cameras

as Embedded Systems

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Image Capture + Application Specific Information + Event Description + Making Decisions

Applications

- Human and Animal Detection
- Surveillance
- Motion Analysis
- Facial Identification

Advantages

- Low Power
- Low Cost

Major Focus – Real Time Analysis



Detecting Human Movement and Gestures

Detect Movement and Recognize Human Actions

 \rightarrow Walk, Stand, Wave

Processing at Two Levels

Low Level Processing \rightarrow Identify Body Parts

→ Categorize Movement

High Level Processing \rightarrow Gestures

→ Overall Activity (Based on Scenario)



Low Level Processing – Region Extraction



Input → Video (MPEG/ JPEG, Compressed / Uncompressed)

Transform Pixel to Bitmap Remove Background Detect Skin → YUV Color Model Segment Regions Combine Meaningfully



Contour Following and Ellipse Fitting



Contour Following Link Pixels into Contours Use Filter Ellipse Fitting Correct Deformation Fit Ellipses to Pixel Regions Extracted Region Modeled with Ellipses Corresponds to a Node in a

Graphical Representation of the Human Body

- Uses Bayes Classifier to Compute Feature Vectors
- Matches Meaningfully to Body Parts
- Begins Matching With Face to Increase Speed

Low Level Processing is Common to all Systems

High Level Processing needs to be Adapted



Use Hidden Markov Models

- → System is a Markov Process (Unobserved States)
- Compare Motion Pattern of Body Part in Sequence of Feature Vectors in Space and Time
- → Evaluate Overall Activity Using Known Gesture



Discrete HMMs to Generate 8 Directional Code Words

→Check the Up, Down, Left, Right, and Circular Movement of Each Body Part

- Current Motion Pattern Combined With Old Pattern
- New Pattern Probability Calculated
- Old & New Probabilities Compared to Identify Actions
- Gaps Indicate End of Action
- **Reference Models Generated**

Used MATLAB To Run Algorithms

→ Much Slower Than Embedded Implementation No Real-Time Video Processing Possible

Solution: Ported MATLAB to C Code → Runs on VLIW Video processor

Achieved Real-Time Operation?

- Frame Rate
- Latency

Memory Requirement?



Processor: 100-MHz PhilipsTriMedia TM-1300 Video Processor **Features:**

32-bit fixed- and floating-point VLIW processor

Dedicated Image Coprocessor Variable Length Decoder

Optimizing C/C++ Compiler MPEG, motion JPEG, 2D text and graphics



Experiments and Optimizations



Measured the CPU Times of Low Level Processing Step

Optimized Implementation by Substituting New Algorithms Suited to Real-Time

Used TriMedia Library Routines→ Replaced C-level Code

Levenberg-Marquardt Fitting Rrocedure – Low Execution

Time

Contour Following Performed in Parallel



Modifications, Results and Development

Optimization Benefits:

- Improved CPU Performance
- Frame Rate Increased From 5-31 Frames / Second
- Latency Decreased from 340 to 40-60 Milliseconds per Frame

Currently Useful for Some Applications

VLSI System will Enable High Volume Embedded Computing Products

Most Efficient Network Type for Multi-Camera Implementation Not Determined





