

Quiz 5

Key

1. (3 points) Find the image of $(3, -5, 1)$ under the transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ where T is defined by $T(x_1, x_2, x_3) = (4x_1 - 7x_2, x_3 - 3)$

way 1:

$$\begin{aligned} T(3, -5, 1) &= (4 \cdot 3 - 7 \cdot -5, 1 - 3) \\ &= (12 + 35, -2) \\ &= (47, -2) \end{aligned}$$

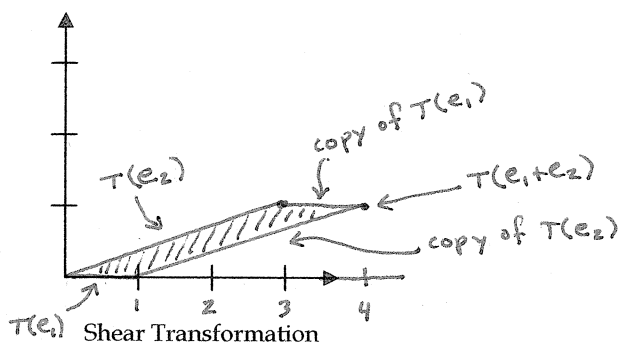
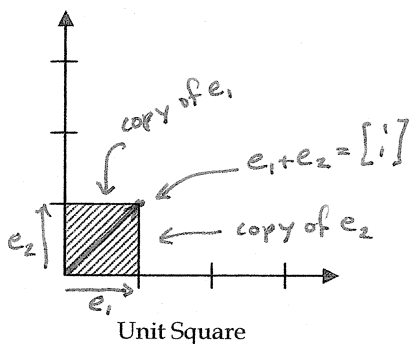
way 2:

$$\begin{aligned} T\left(\begin{bmatrix} 3 \\ -5 \\ 1 \end{bmatrix}\right) &= \begin{bmatrix} 4 \cdot 3 - 7 \cdot -5 \\ 1 - 3 \end{bmatrix} \\ &= \begin{bmatrix} 47 \\ -2 \end{bmatrix} \end{aligned}$$

2. (4 points) Find the standard matrix of the linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given that $T(e_1) = (-1, 4, -7)$, $T(e_2) = (0, 0, 3)$, and $T(e_3) = (5, 2, 3)$. Be careful of rows/columns.

$$\begin{aligned} A &= [T(e_1) \ T(e_2) \ T(e_3)] \\ &= \begin{bmatrix} -1 & 0 & 5 \\ 4 & 0 & 2 \\ -7 & 3 & 3 \end{bmatrix} \end{aligned}$$

3. (3 points) Find the image of the unit square after the following horizontal shear transformation has been applied to it: $Tx = Ax$, where $A = \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix}$ and $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$. Hint: the unit square is formed by using the standard vectors $e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$.



way 1:

transform the sides of the unit square:

$$T(e_1) = \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$T(e_2) = \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

way 2:

find where the "points" of the square will end up
i.e.: $(0,0)$, $(1,0)$, $(0,1)$, & $(1,1)$

$$T\left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \end{bmatrix} \leftarrow T(e_1 + e_2)$$

$$T(e_1) = e_1$$

$$T(e_2) = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$