

”Self-Checking Test for Calculus and Linear Algebra”

Name : _____

ID : _____

Show the details of your work !!

1. (a) Let $\xi = \frac{S}{S + P_m}$, $\tau = T - t$ and $V(S, t) = (S + P_m)\bar{V}(\xi, \tau)$, where P_m is a positive constant. Show that in terms of $\xi, \bar{V}, \frac{\partial \bar{V}}{\partial \tau}, \frac{\partial \bar{V}}{\partial \xi}$, and $\frac{\partial^2 \bar{V}}{\partial \xi^2}$, for $\frac{\partial V}{\partial t}, \frac{\partial V}{\partial S}, \frac{\partial^2 V}{\partial S^2}$, there are the following expressions:

$$\begin{aligned}\frac{\partial V}{\partial t} &= -\frac{P_m}{1 - \xi} \frac{\partial \bar{V}}{\partial \tau}, \\ \frac{\partial V}{\partial S} &= \bar{V}(\xi, \tau) + (1 - \xi) \frac{\partial \bar{V}}{\partial \xi}, \\ \frac{\partial^2 V}{\partial S^2} &= \frac{(1 - \xi)^3}{P_m} \frac{\partial^2 \bar{V}}{\partial \xi^2}.\end{aligned}$$

- (b) Consider a function $V(Z_1, Z_2, Z_3)$. Let

$$\begin{cases} \xi_1 = \frac{Z_1 - Z_{1,l}}{1 - Z_{1,l}} \equiv \xi_1(Z_1), \\ \xi_2 = \frac{Z_2 - Z_{2,l}}{Z_1 - Z_{2,l}} \equiv \xi_2(Z_1, Z_2), \\ \xi_3 = \frac{Z_3 - Z_{3,l}}{Z_2 - Z_{3,l}} \equiv \xi_3(Z_2, Z_3), \end{cases}$$

where $Z_{1,l}, Z_{2,l}$, and $Z_{3,l}$ are constants. These relations also give the relations $Z_1 = Z_1(\xi_1)$, $Z_2 = Z_2(\xi_1, \xi_2)$, and $Z_3 = Z_3(\xi_1, \xi_2, \xi_3)$ implicitly. We define $\bar{V}(\xi_1, \xi_2, \xi_3) = V(Z_1(\xi_1), Z_2(\xi_1, \xi_2), Z_3(\xi_1, \xi_2, \xi_3))$ and clearly for $V(Z_1, Z_2, Z_3)$ we have the following expression:

$$V(Z_1, Z_2, Z_3) = \bar{V}(\xi_1(Z_1), \xi_2(Z_1, Z_2), \xi_3(Z_2, Z_3)).$$

Express

$$\frac{\partial V}{\partial Z_1}, \frac{\partial V}{\partial Z_2}, \frac{\partial V}{\partial Z_3}, \frac{\partial^2 V}{\partial Z_1^2}, \frac{\partial^2 V}{\partial Z_2^2}, \frac{\partial^2 V}{\partial Z_3^2}, \frac{\partial^2 V}{\partial Z_1 \partial Z_2}, \frac{\partial^2 V}{\partial Z_2 \partial Z_3}, \frac{\partial^2 V}{\partial Z_1 \partial Z_3}$$

as linear functions of

$$\frac{\partial \bar{V}}{\partial \xi_1}, \frac{\partial \bar{V}}{\partial \xi_2}, \frac{\partial \bar{V}}{\partial \xi_3}, \frac{\partial^2 \bar{V}}{\partial \xi_1^2}, \frac{\partial^2 \bar{V}}{\partial \xi_2^2}, \frac{\partial^2 \bar{V}}{\partial \xi_3^2}, \frac{\partial^2 \bar{V}}{\partial \xi_1 \partial \xi_2}, \frac{\partial^2 \bar{V}}{\partial \xi_2 \partial \xi_3}, \frac{\partial^2 \bar{V}}{\partial \xi_1 \partial \xi_3}.$$

2. $G(S)$ is defined by

$$G(S) = \frac{1}{\sqrt{2\pi}bS} e^{-[\ln(S/a)+b^2/2]^2/2b^2},$$

where a and b are positive numbers. Show that

(a) for any real number n

$$\int_0^c S^n G(S) dS = a^n e^{(n^2-n)b^2/2} N\left(\frac{\ln(c/a) + b^2/2}{b} - nb\right);$$

(b)

$$\begin{aligned} & \int_c^\infty \ln S G(S) dS \\ &= \frac{b}{\sqrt{2\pi}} e^{-[\ln(c/a)+b^2/2]^2/2b^2} + (\ln a - b^2/2) N\left(-\frac{\ln(c/a) + b^2/2}{b}\right), \end{aligned}$$

where

$$N(z) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^z e^{-\xi^2/2} d\xi.$$

(Hint: Use the substitution $\eta(S) = \frac{\ln(S/a)+b^2/2}{b}$.)

3. (a) Show that

$$\phi(\mathbf{x}_0; \mathbf{x}, \tau) = \frac{1}{(4\pi\tau)^{n/2}} e^{-\sum_{i=1}^n (x_i - x_{i0})^2/(4\tau)}$$

is a solution to

$$\frac{\partial \phi}{\partial \tau} = \sum_{i=1}^n \frac{\partial^2 \phi}{\partial x_i^2}, \quad -\infty < \mathbf{x} < \infty, \quad 0 \leq \tau,$$

where

$$\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}, \quad \mathbf{x}_0 = \begin{pmatrix} x_{10} \\ x_{20} \\ \vdots \\ x_{n0} \end{pmatrix}$$

and $-\infty < \mathbf{x} < \infty$ means

$$-\infty < x_i < \infty, \quad i = 1, 2, \dots, n.$$

(b) Show that the function $\phi(\mathbf{x}_0; \mathbf{x}, \tau)$ satisfies the conditions

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} \phi(\mathbf{x}_0; \mathbf{x}, \tau) dx_{10} dx_{20} \cdots dx_{n0} = 1$$

and

$$\lim_{\tau \rightarrow 0} \phi(\mathbf{x}_0; \mathbf{x}, \tau) = \begin{cases} \infty, & \text{at } \mathbf{x} = \mathbf{x}_0, \\ 0, & \text{otherwise,} \end{cases}$$

that is,

$$\lim_{\tau \rightarrow 0} \phi(\mathbf{x}_0; \mathbf{x}, \tau) = \delta(\mathbf{x} - \mathbf{x}_0).$$

4. Suppose that $\varphi_1(\eta)$ and $\varphi_2(\eta)$ are defined for $\eta \in [0, 1]$ and $\eta \in [1, \infty)$, respectively, and $\varphi_1(1) = \varphi_2(1)$ holds. Assume that

$$\frac{d\varphi_1(\eta)}{d\eta} = \eta^{2(r-D_0+\sigma^2/2)/\sigma^2} \frac{d\varphi_2(1/\eta)}{d\eta}$$

and

$$\varphi_2(\eta) = \max(\eta - \beta, 0), \quad 1 \leq \eta \quad \text{with} \quad \beta > 1.$$

Find the function $\varphi_1(\eta)$ for $\eta \in [0, 1]$ if $r \neq D_0$.

5. The function $G(S', T; S, t)$ is defined by

$$\begin{aligned} & G(S', T; S, t) \\ &= \frac{1}{S' \sigma \sqrt{2\pi(T-t)}} e^{-[\ln(S'/S) - (r-D_0-\sigma^2/2)(T-t)]^2 / 2\sigma^2(T-t)}, \end{aligned}$$

where r, D_0 , and σ are constants. Show

$$\frac{G(B_l^2/S', T; S, t)}{G(S', T; B_l^2/S, t)} = \frac{S'^2}{B_l^2} \left(\frac{B_l^2}{S'S} \right)^{2(r-D_0-\sigma^2/2)/\sigma^2}.$$

6. As we know, if \mathbf{P} is a symmetric matrix and all its eigenvalues are positive, then we can find a matrix \mathbf{Q} satisfying the conditions $\mathbf{Q}^T \mathbf{Q} = \mathbf{I}$ and a positive diagonal matrix $\mathbf{\Lambda}$, so that $\mathbf{P} = \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^T$.

(a) Show that we can require $\det \mathbf{Q} = \det \mathbf{Q}^T = 1$ without losing generality.

(b) Set $\mathbf{R} = \mathbf{\Lambda}^{-1/2} \mathbf{Q}^T$. Show $\det \mathbf{R} = \frac{1}{\sqrt{\det \mathbf{P}}}$.

(c) \mathbf{y} and \mathbf{y}_0 are two vectors. Set $\mathbf{x} = \mathbf{R}\mathbf{y}$, $\mathbf{x}_0 = \mathbf{R}\mathbf{y}_0$, and $\eta = \frac{\mathbf{y}_0 - \mathbf{y}}{\sqrt{2\tau}}$. Show

$$\frac{(\mathbf{x}_0 - \mathbf{x})^T (\mathbf{x}_0 - \mathbf{x})}{4\tau} = \frac{\eta^T \mathbf{P}^{-1} \eta}{2}.$$

7. (a) \mathbf{S} is a random vector and its covariance matrix is \mathbf{B} , i.e., the component on the i -th row and the j -th column of \mathbf{B} is equal to $\mathbf{E}[(S_i - \mathbf{E}[S_i])(S_j - \mathbf{E}[S_j])]$, S_i being the i -th component of \mathbf{S} . Let $\bar{\mathbf{S}} = \mathbf{A}\mathbf{S}$, \mathbf{A} being a constant matrix, and its covariance matrix be \mathbf{C} . Find the relation among \mathbf{A} , \mathbf{B} , and \mathbf{C} .

(b) How do we choose \mathbf{A} so that \mathbf{C} will be a diagonal matrix?